

# Machine learning based on physical dynamics

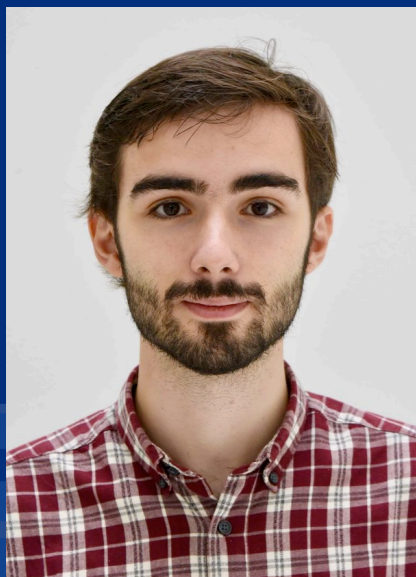
Florian Marquardt

Max Planck Institute for the Science of Light and  
Friedrich-Alexander Universität Erlangen-Nürnberg

works with:

Victor Lopez-Pastor (Phys. Rev. X 2023)

Clara Wanjura (arXiv 2023)



# DEEP LEARNING REVOLUTION

2012

IMAGENET

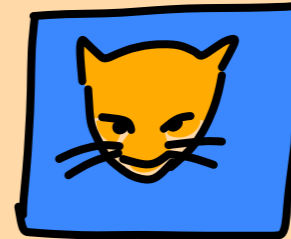
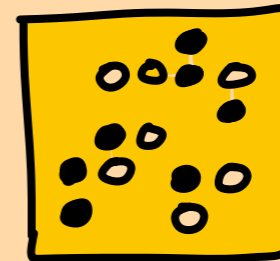


IMAGE RECOGNITION

2017

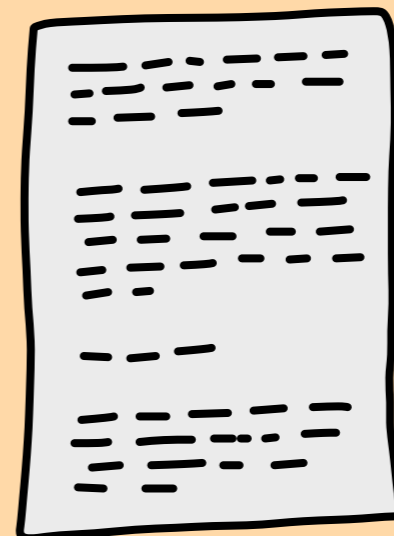
ALPHA ZERO



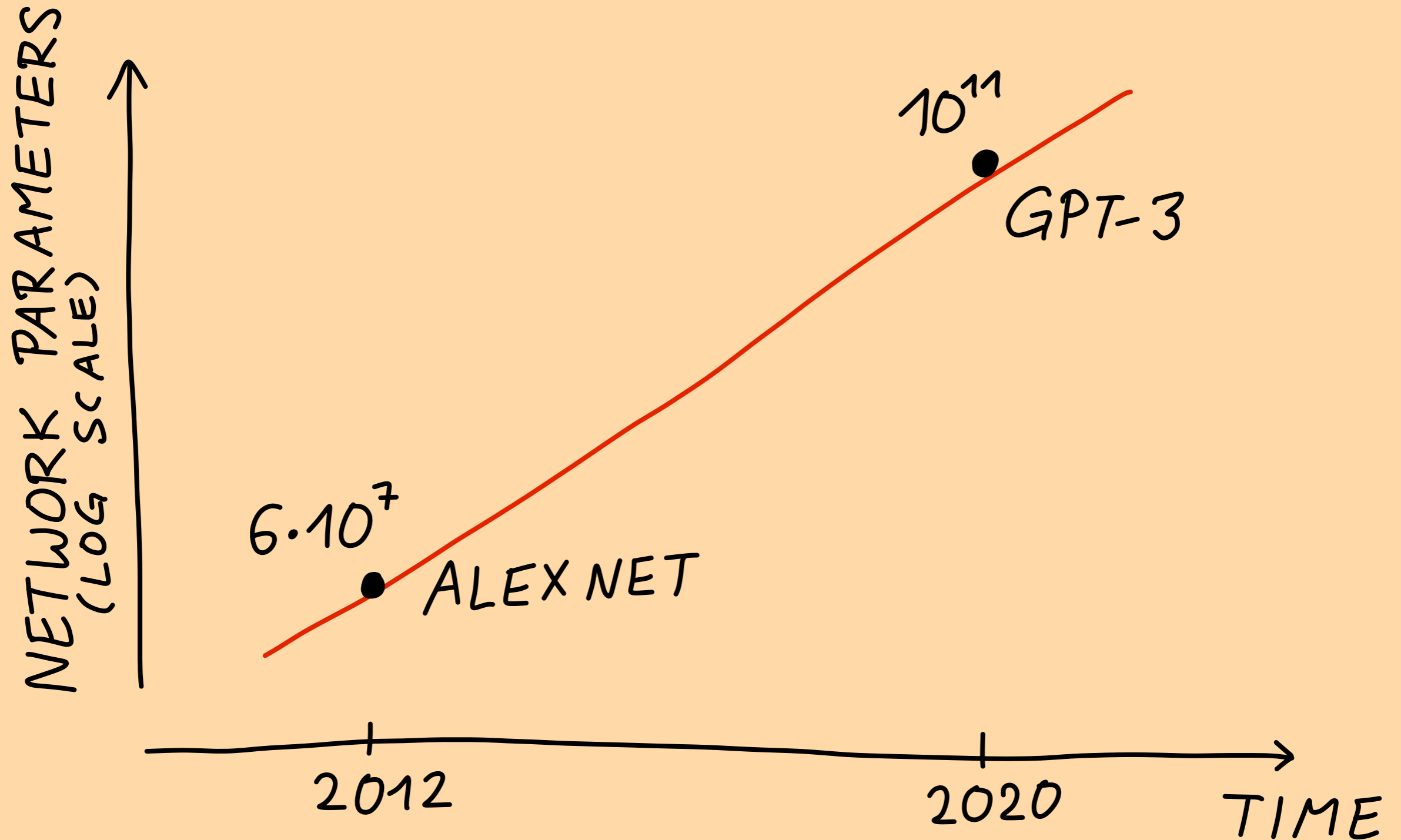
PLAYING GAMES

2020

GPT-3



WRITING TEXT

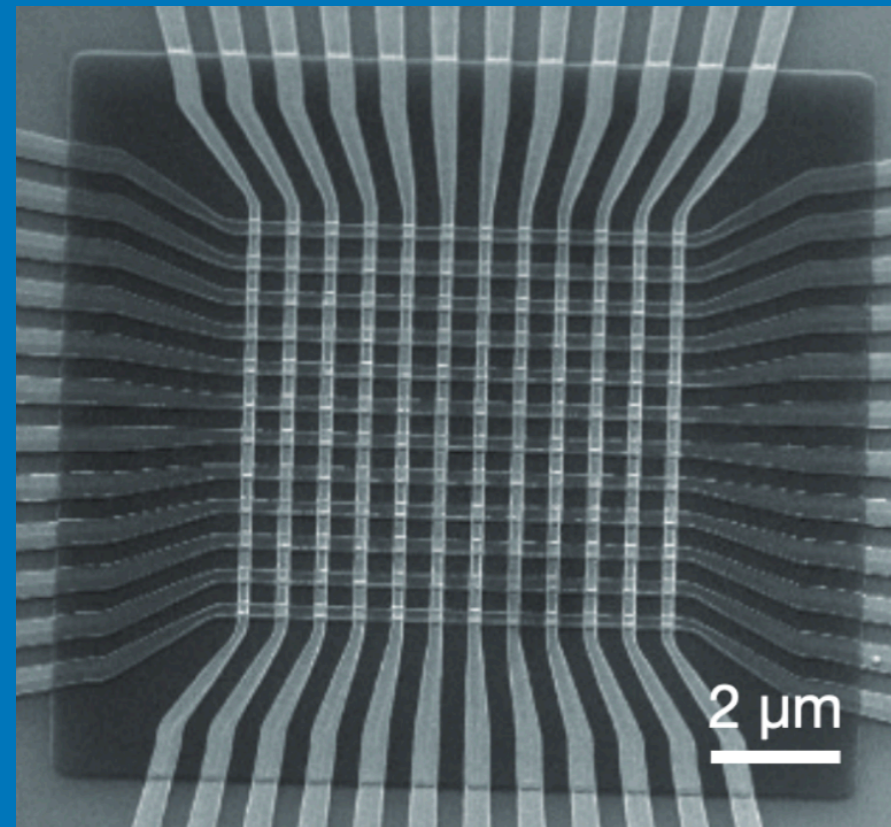


→ CAN WE BUILD BETTER HARDWARE?  
FAST, HIGHLY PARALLEL, ENERGY-EFFICIENT

→ NEUROMORPHIC COMPUTING

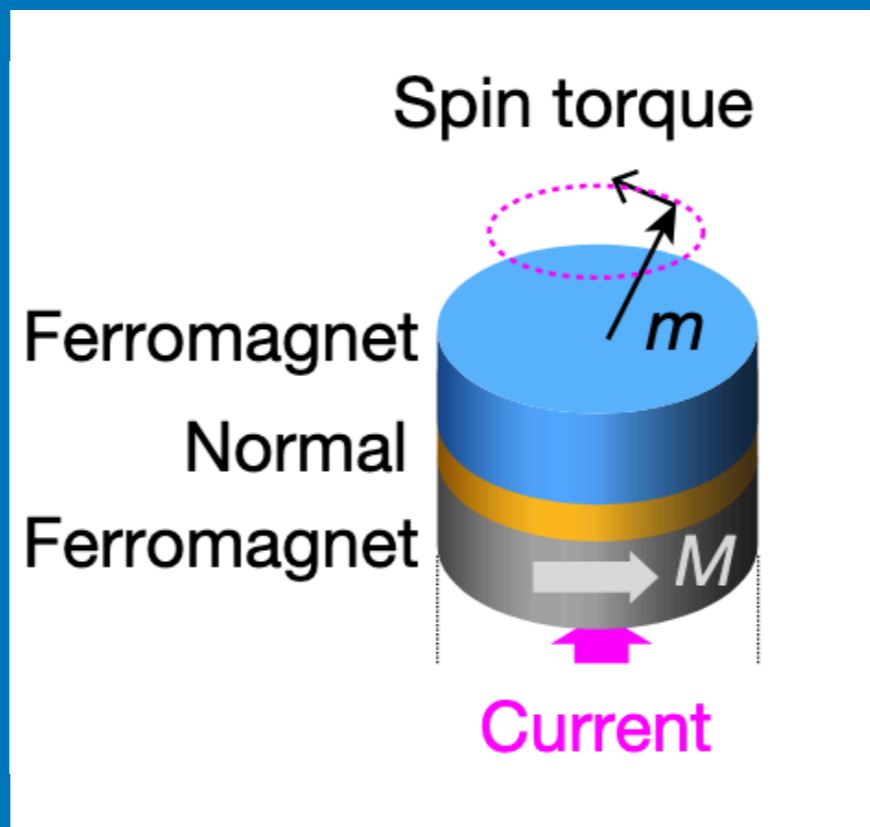


# NEUROMORPHIC COMPUTING



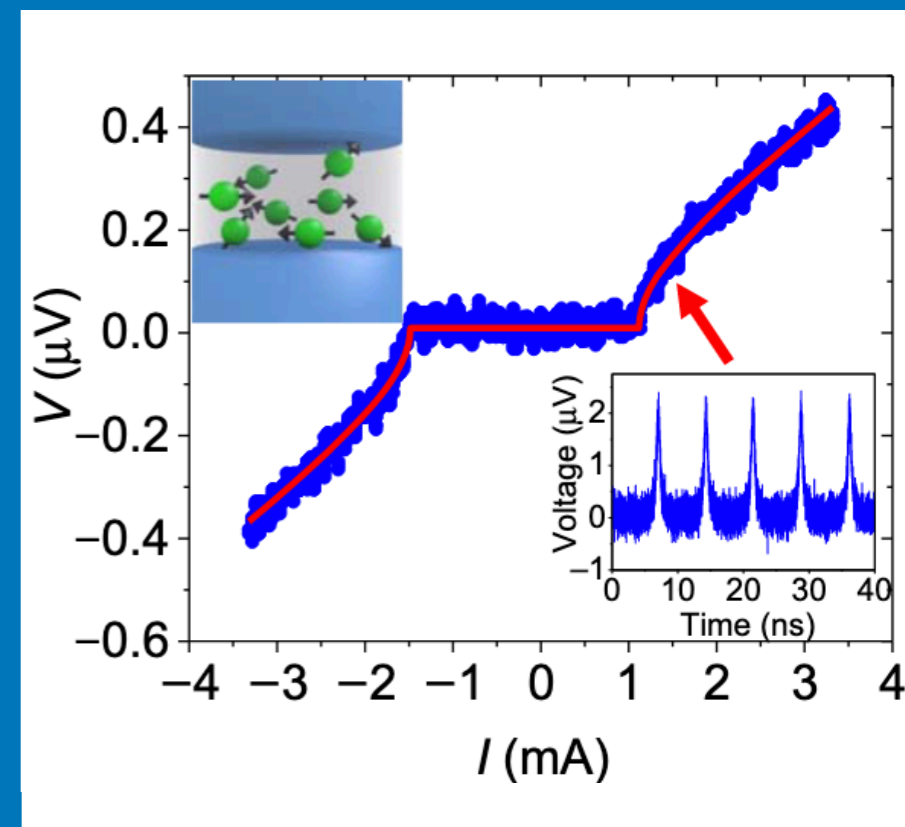
(Prezioso et al 2015)

## MEMRISTORS



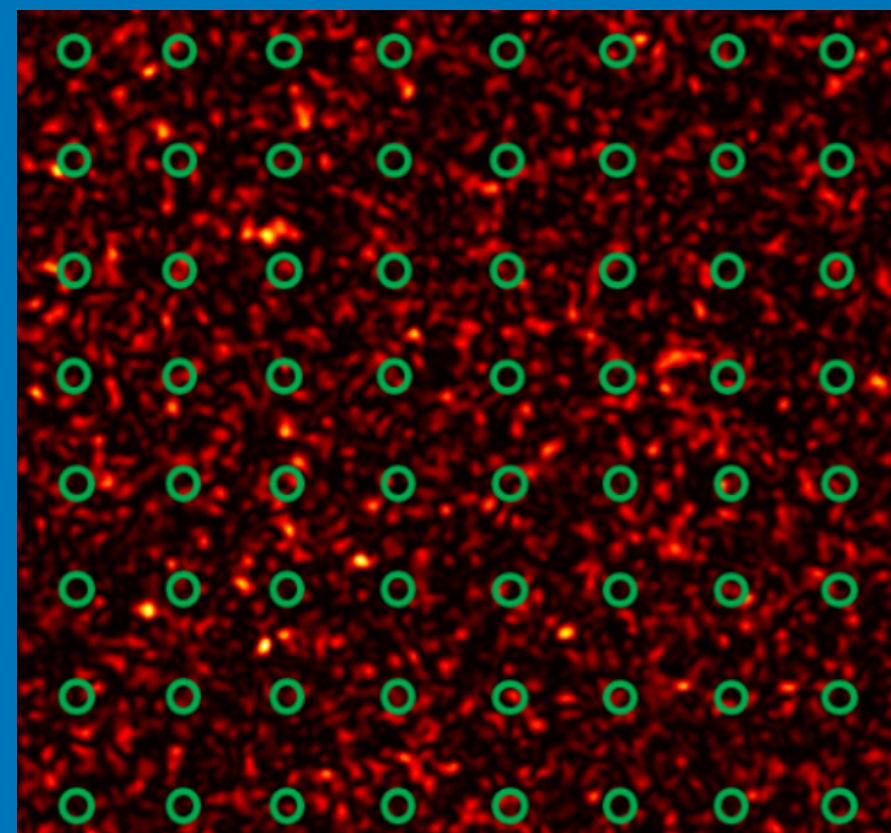
(Torrejon et al 2017)

## SPINTRONIC OSCILLATORS



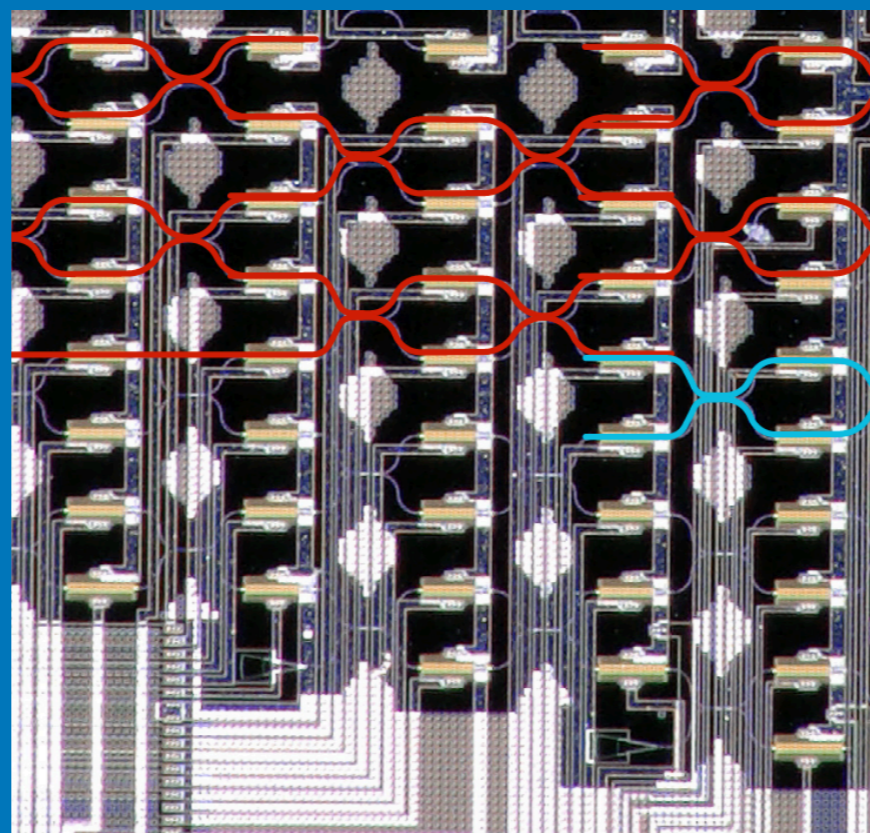
(Schneider et al 2018)

## MAGN. JOSEPHSON JUNCTIONS



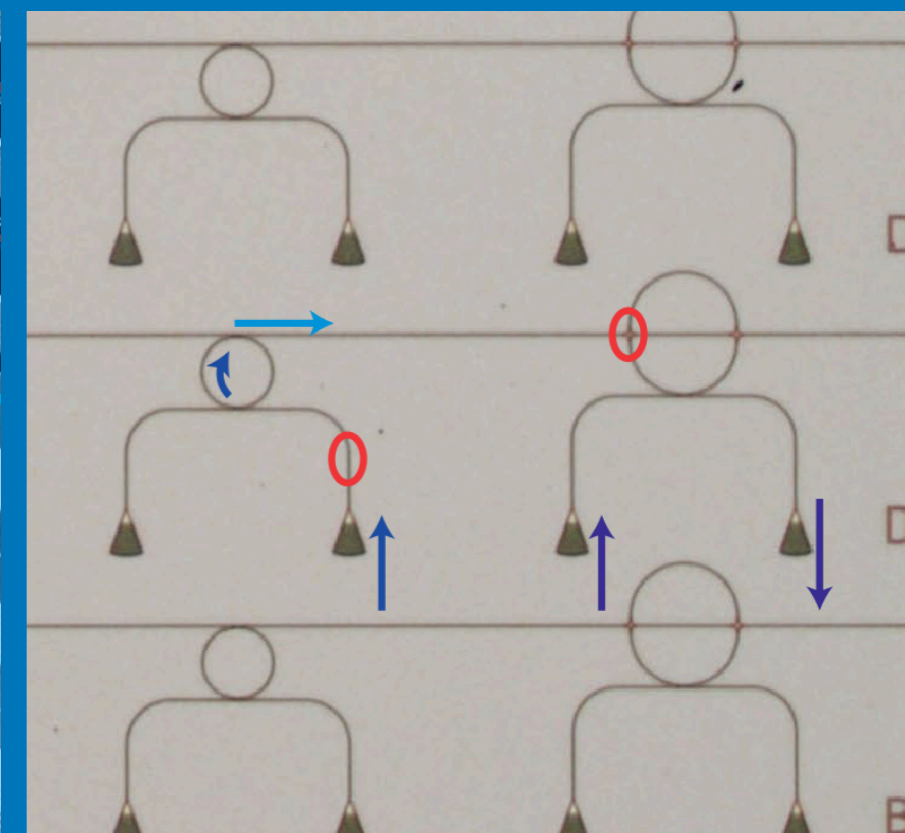
(Dong et al 2019)

## OPTICS IN COMPLEX MEDIA



(Shen et al 2017)

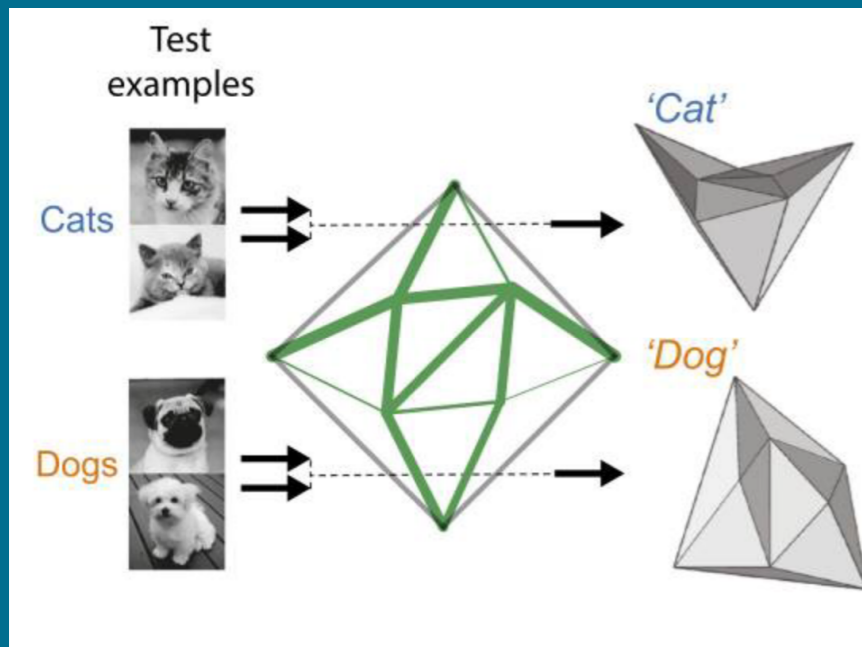
## TUNEABLE INTERFEROMETER



(Feldmann et al 2019)

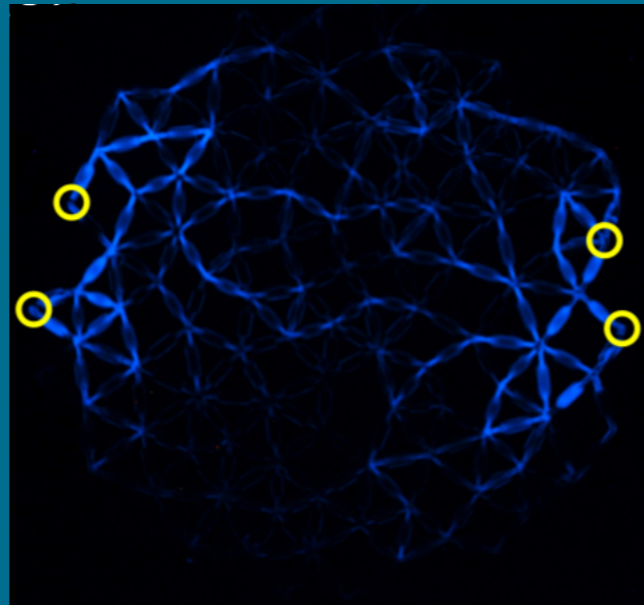
## PHASE-CHANGE MATERIALS





(Stern et al 2020)

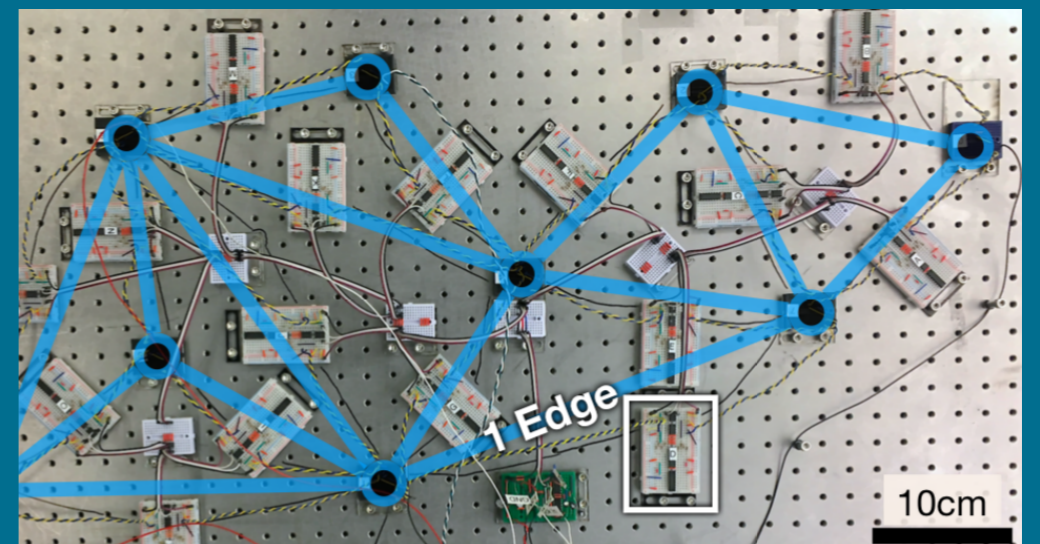
# LEARNING TO FOLD



(Pashine 2021)

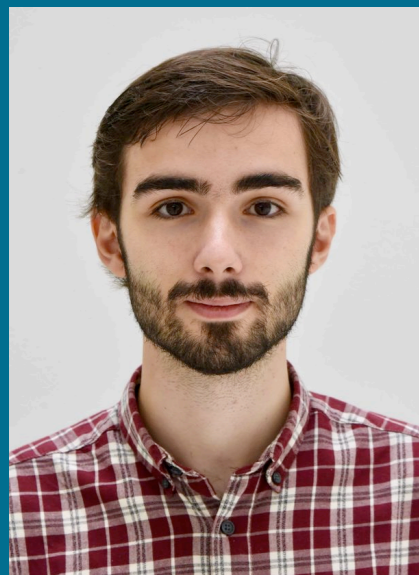
# MECHANICAL NETWORKS

# RESISTOR NETWORKS



(Dillavou et al 2022)

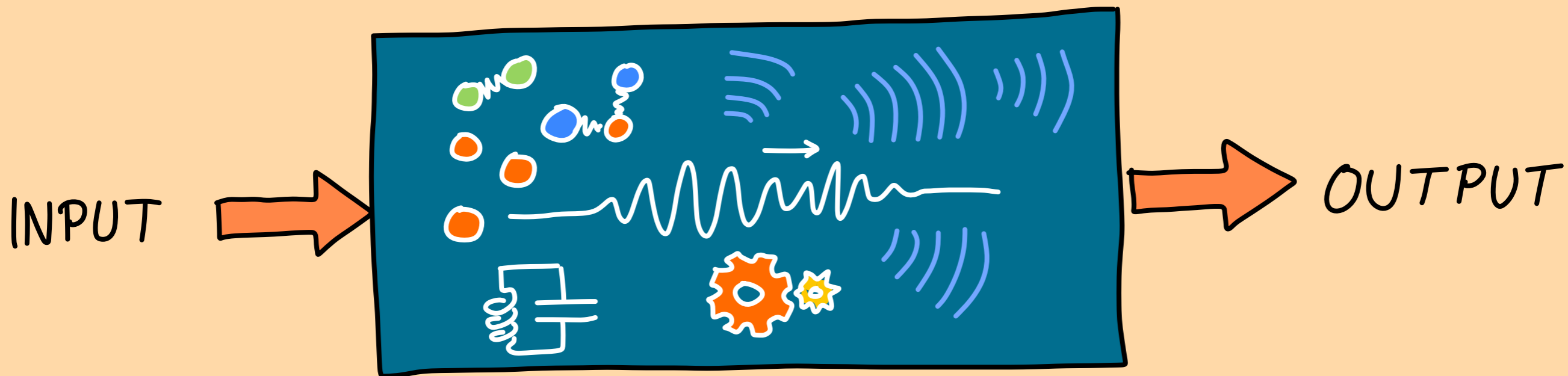
# A new way to learn: Hamiltonian Echo Backpropagation



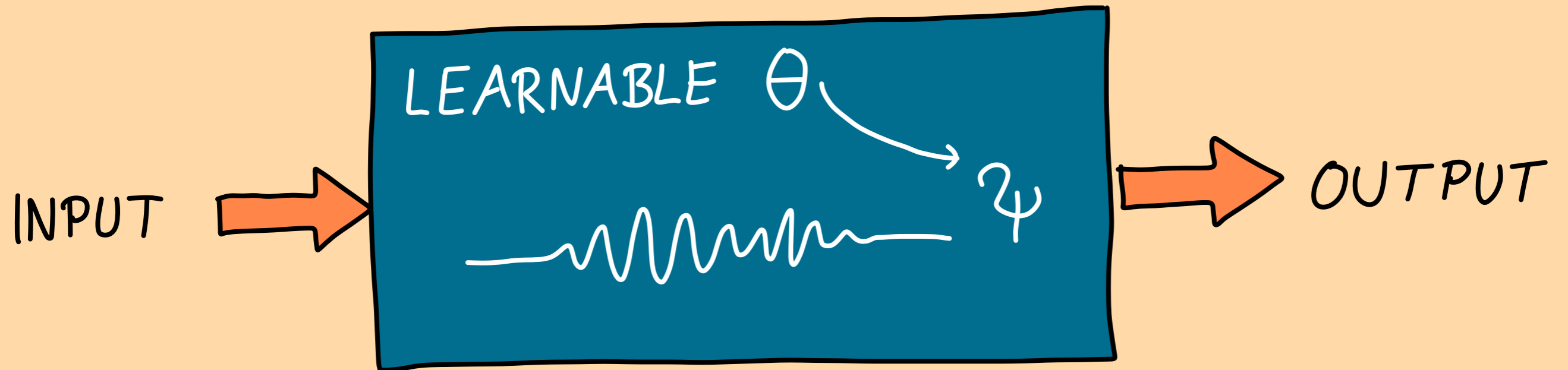
Victor Lopez-Pastor & F.M.  
Phys. Rev. X 13, 031020 (2023)



# PHYSICAL LEARNING MACHINE

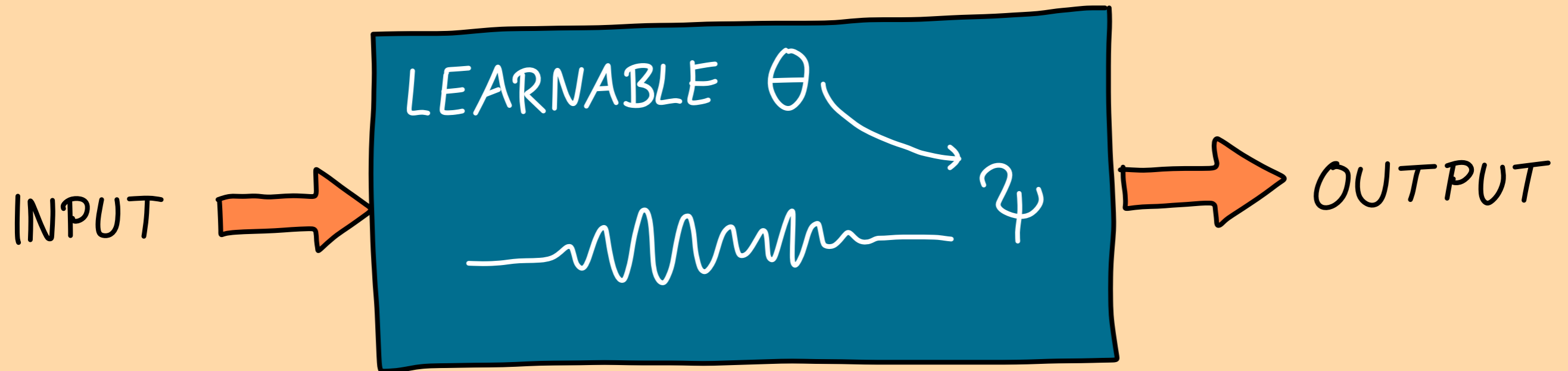


# PHYSICAL LEARNING MACHINE





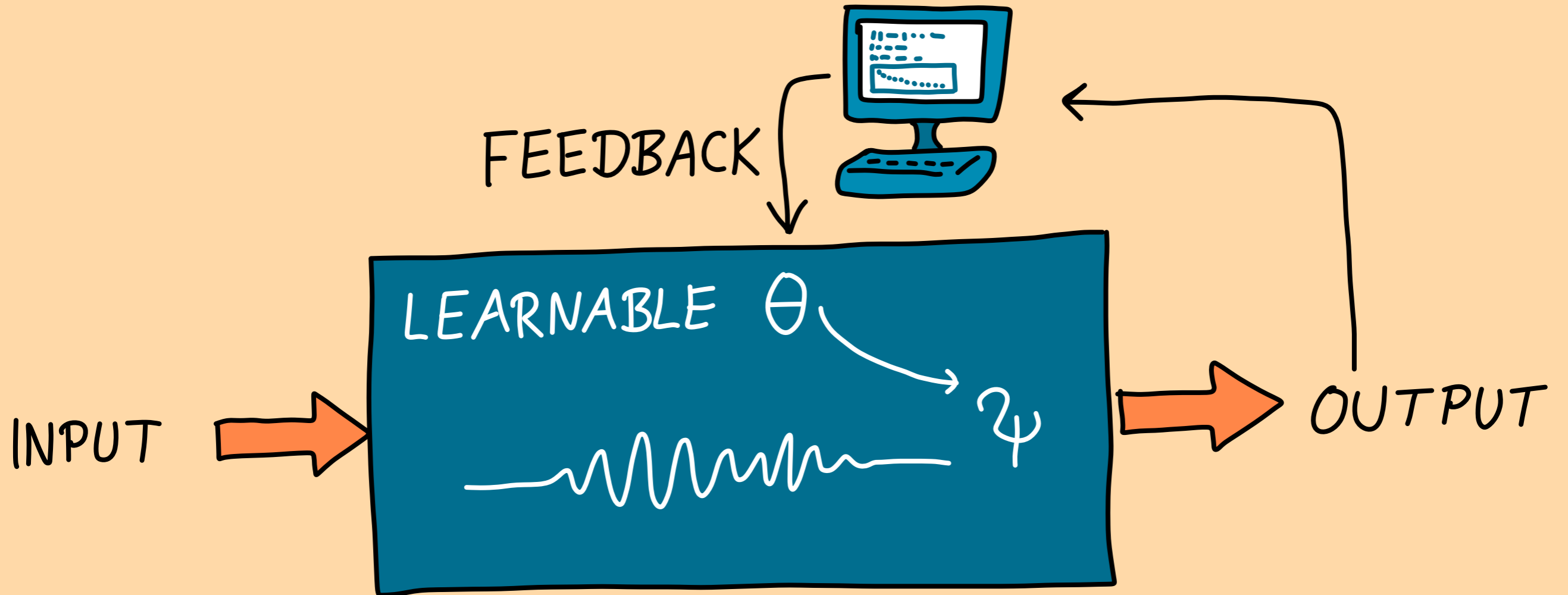
# PHYSICAL LEARNING MACHINE



HOW TO LEARN?

(FIND RIGHT  $\theta$  TO  
GET DESIRED INPUT  $\rightarrow$  OUTPUT)

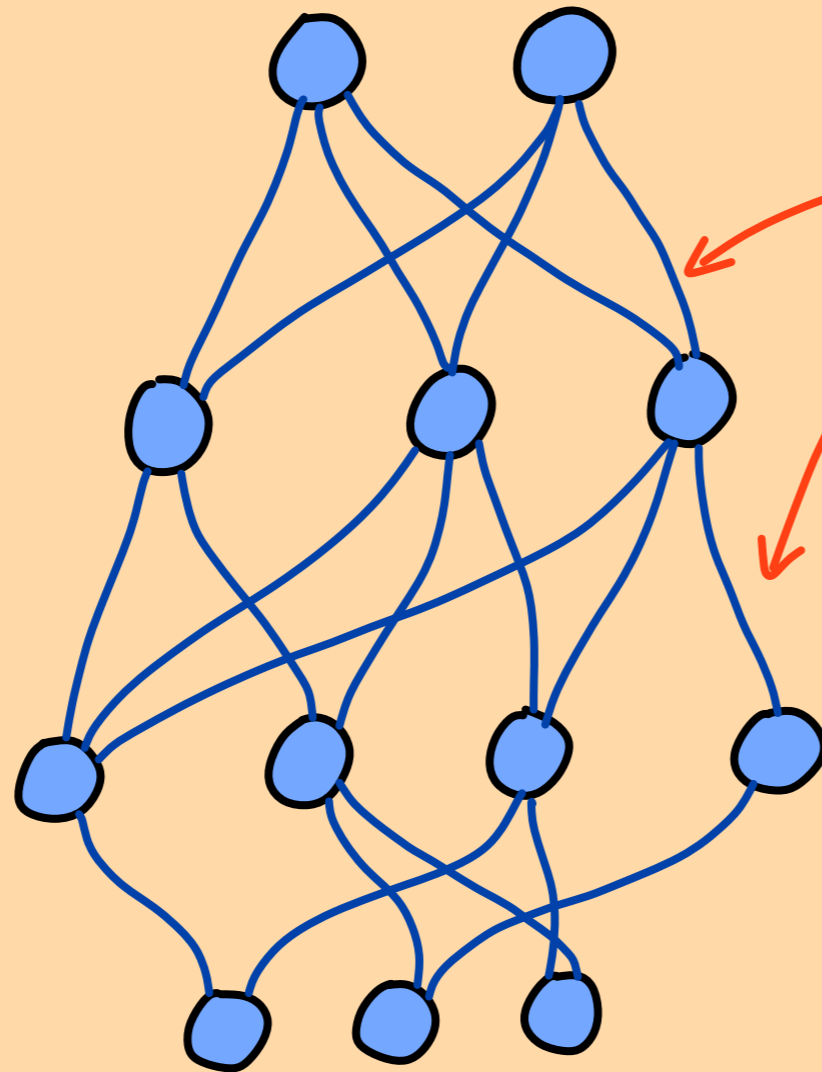
# PHYSICAL LEARNING MACHINE





# ARTIFICIAL NEURAL NETWORKS

OUTPUT  $y = F_{\theta}(x)$

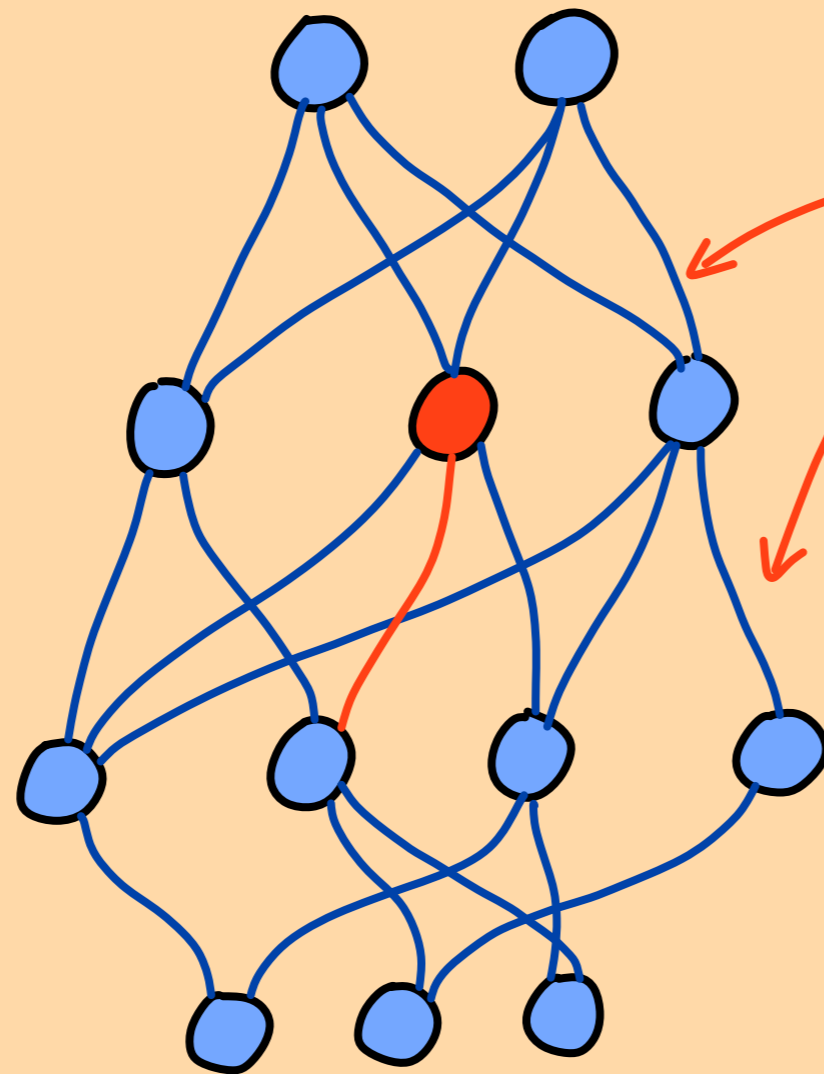


$\theta$  : CONNECTION WEIGHTS

INPUT  $x$

# ARTIFICIAL NEURAL NETWORKS

OUTPUT  $y = F_{\theta}(x)$

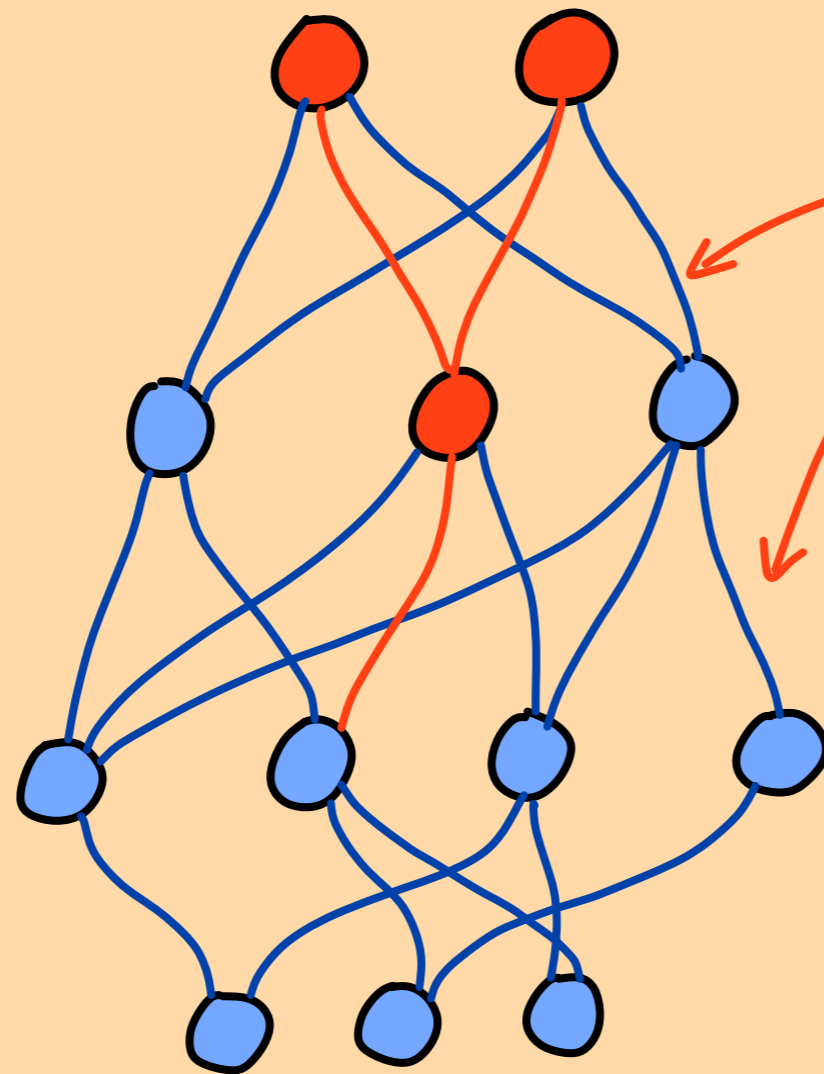


$\theta$  : CONNECTION WEIGHTS

INPUT  $x$

# ARTIFICIAL NEURAL NETWORKS

OUTPUT  $y = F_{\theta}(x)$

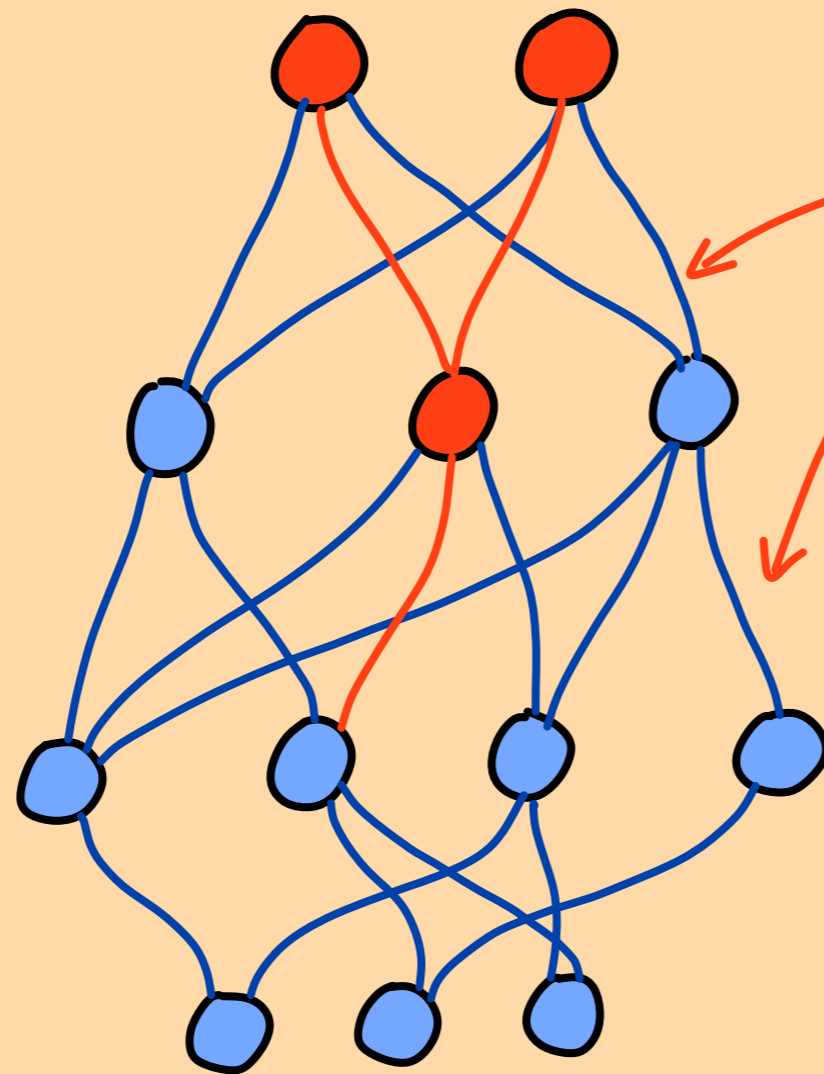


$\theta$  : CONNECTION WEIGHTS

INPUT  $x$

# ARTIFICIAL NEURAL NETWORKS

OUTPUT  $y = F_{\theta}(x)$



$\theta$ : CONNECTION WEIGHTS

PARAMETER SHIFT METHOD:

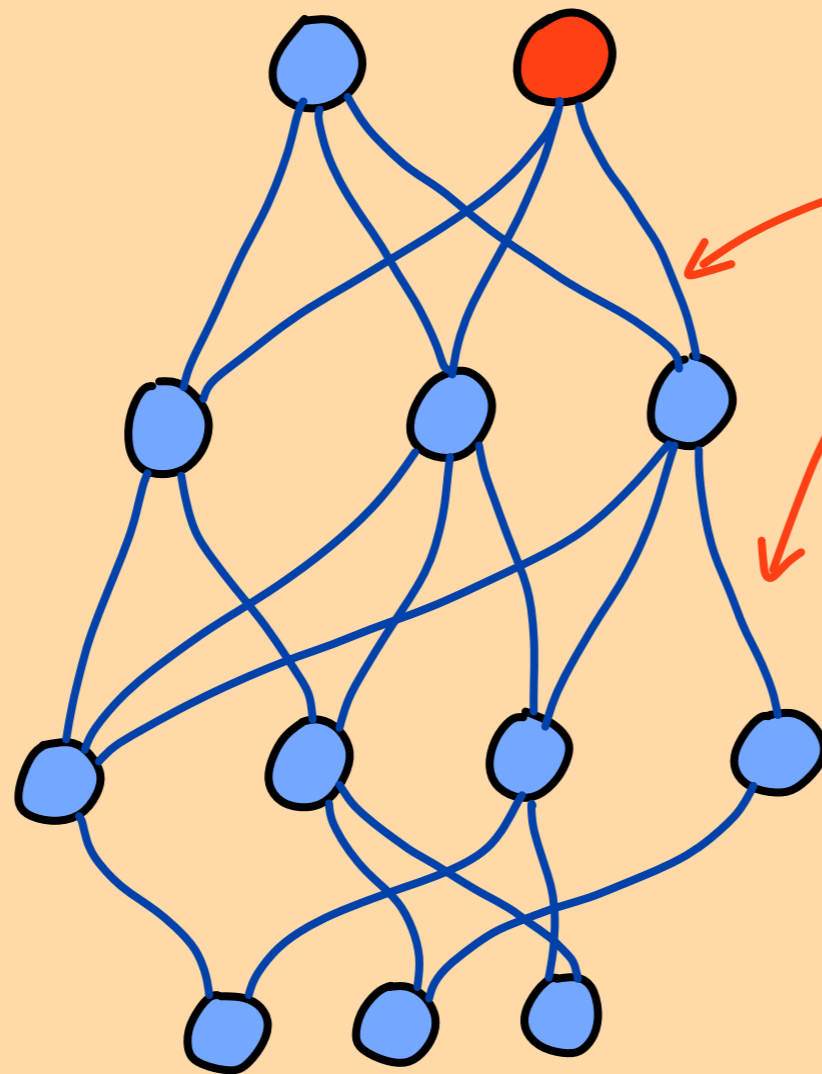
- ALWAYS POSSIBLE
  - VERY INEFFICIENT
- EFFORT  $\sim$  #PARAMS

INPUT  $x$



# ARTIFICIAL NEURAL NETWORKS

OUTPUT  $y = F_{\theta}(x)$

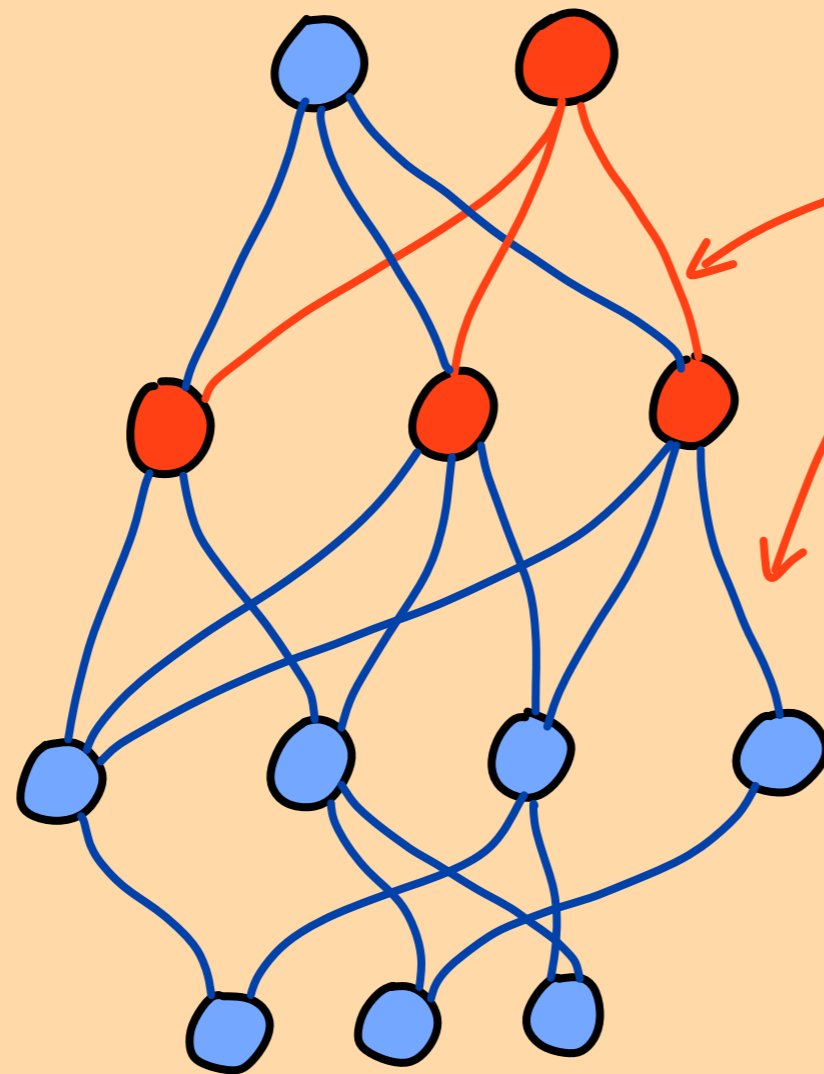


$\theta$  : CONNECTION WEIGHTS

INPUT  $x$

# ARTIFICIAL NEURAL NETWORKS

OUTPUT  $y = F_{\theta}(x)$

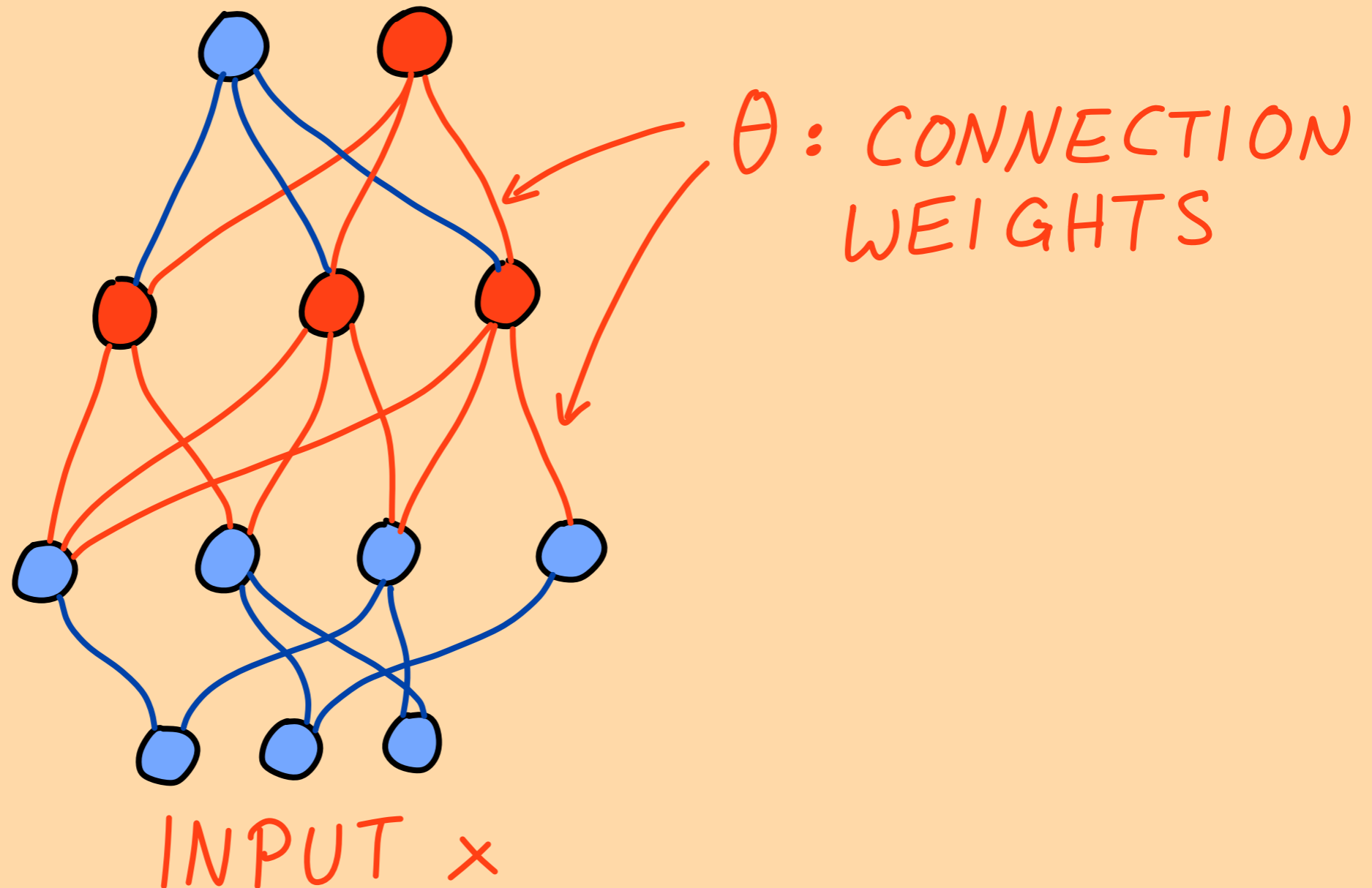


$\theta$  : CONNECTION WEIGHTS

INPUT  $x$

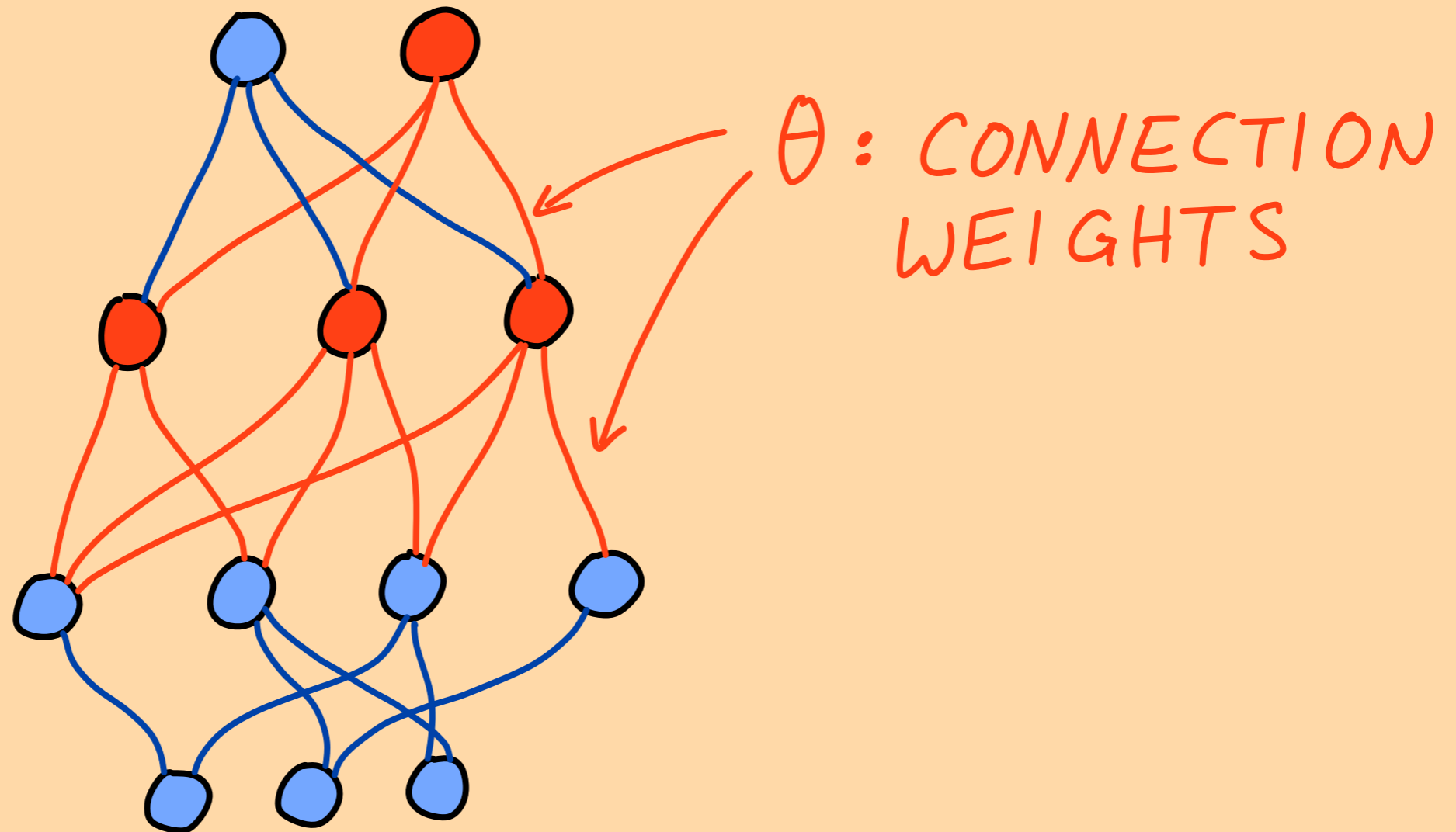
# ARTIFICIAL NEURAL NETWORKS

OUTPUT  $y = F_{\theta}(x)$



# ARTIFICIAL NEURAL NETWORKS

OUTPUT  $y = F_{\theta}(x)$

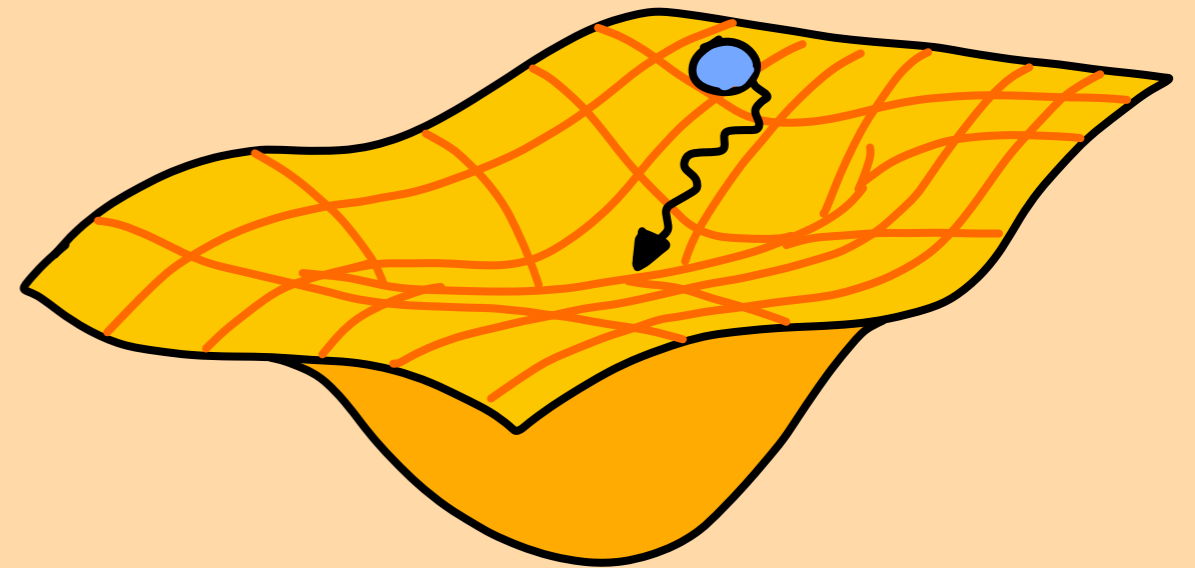


INPUT  $x$

"BACKPROPAGATION": ALL GRADIENTS  
FOR PRICE OF ONE EVALUATION

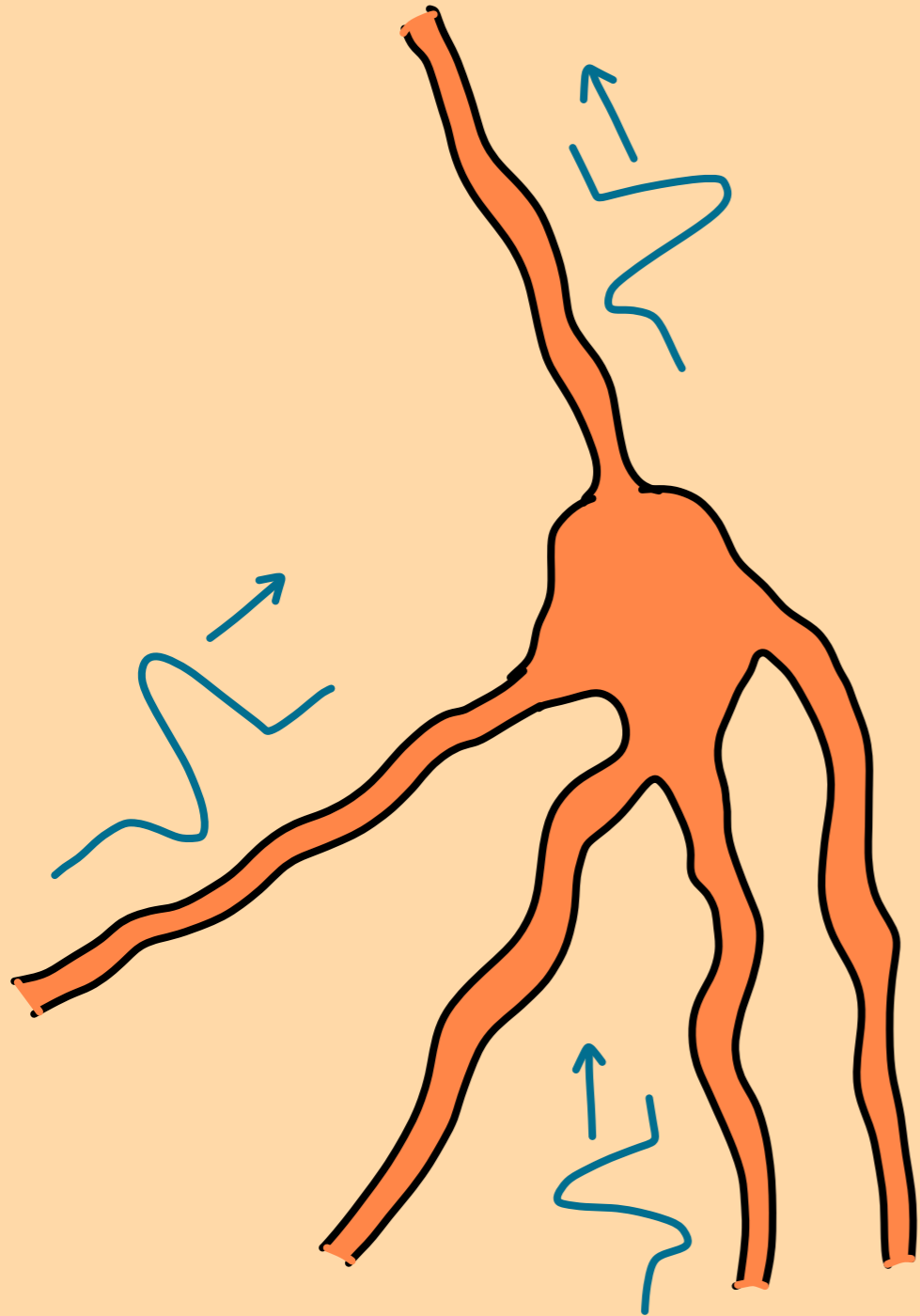


# OPTIMIZATION- BASED RULES



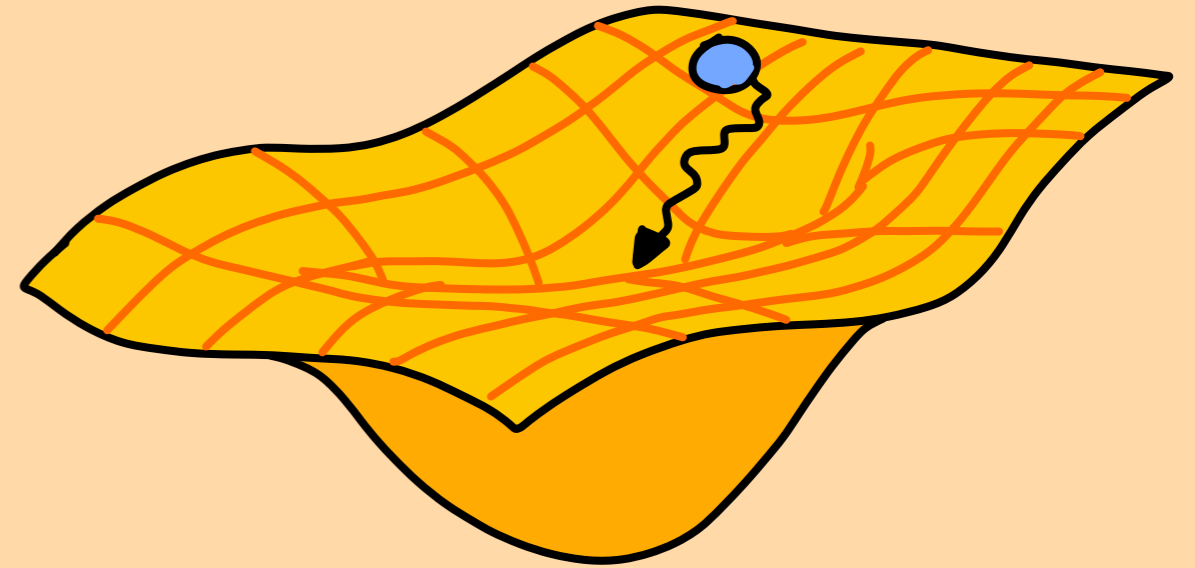
GRADIENT DESCENT  
OF COST FUNCTION

# BIOLOGY-INSPIRED LEARNING RULES



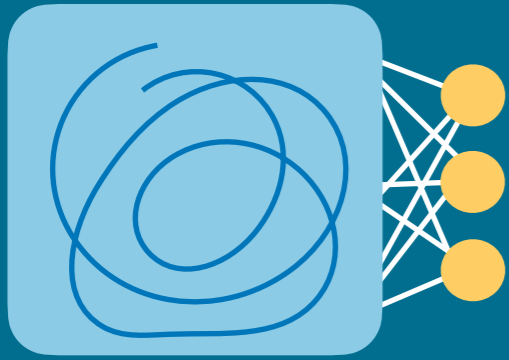
"NEURONS THAT  
FIRE TOGETHER  
WIRE TOGETHER"

# OPTIMIZATION- BASED RULES

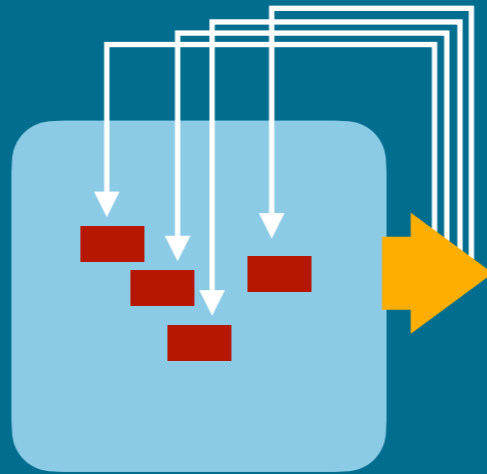


GRADIENT DESCENT  
OF COST FUNCTION

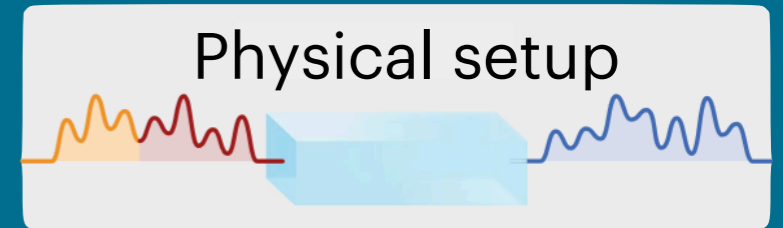
# Training neuromorphic devices



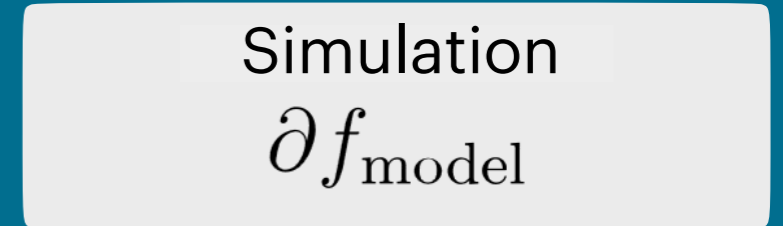
Reservoir computing



Parameter shift method



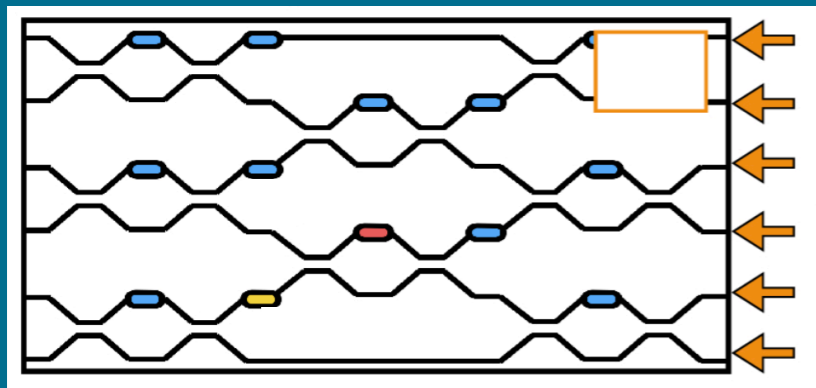
Physical setup



Simulation

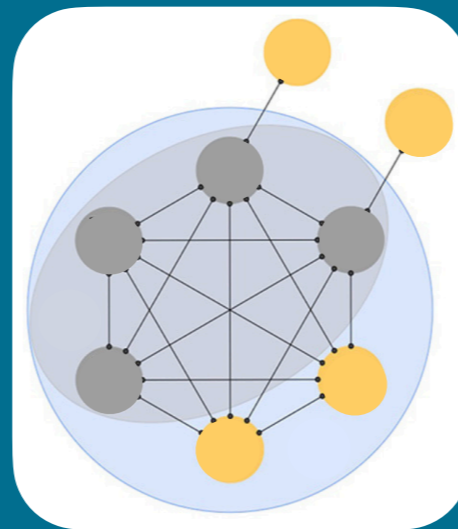
$$\partial f_{\text{model}}$$

Hybrid method  
Wright, Onodera, ...,  
McMahon 2022



Physical backprop. for special systems

Wagner & Psaltis 1987  
Hughes, ..., Fan 2018  
Guo, ..., Lvovsky 2021



Equilibrium Propagation

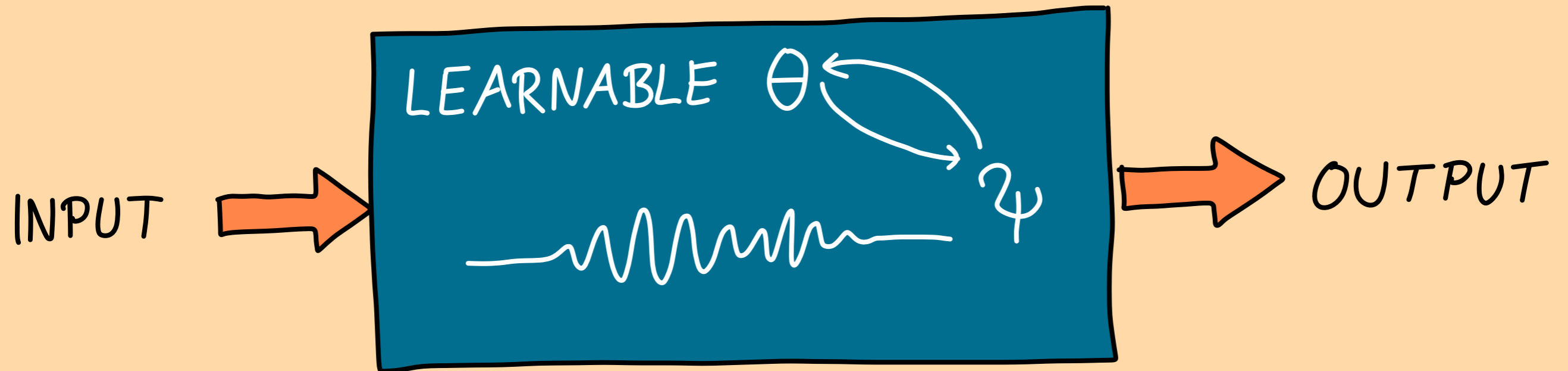
Scellier, ..., Bengio 2017  
Stern, ..., Liu 2021



Physical backpropagation  
**and**  
Physical parameter update

# PHYSICAL SELF-LEARNING MACHINE

AUTONOMOUS, NO FEEDBACK



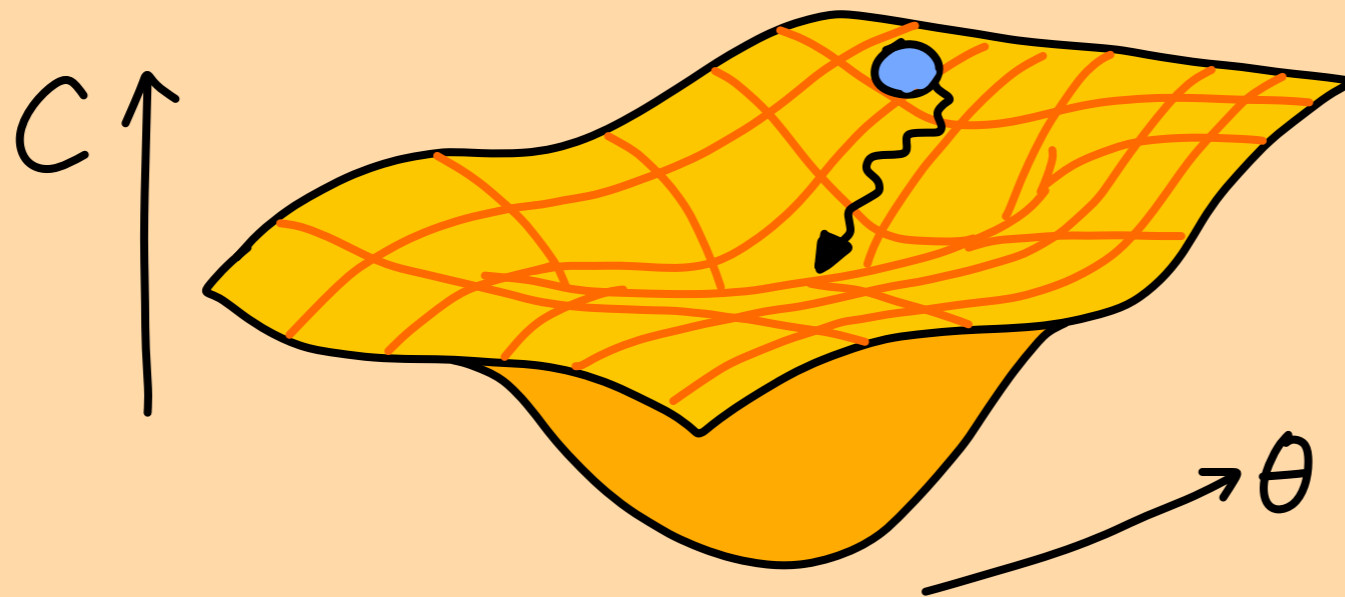
WE WANT: PHYSICAL BACKPROPAGATION  
AND PHYSICAL  
LEARNING UPDATE



GOAL: MINIMIZE COST FUNCTION

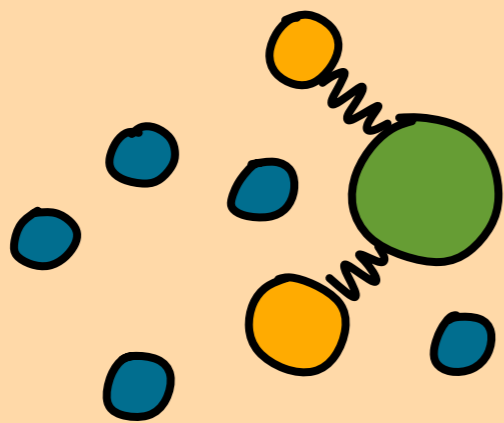
$$C = (\text{OUTPUT} - \text{TARGET})^2$$

$$\theta_{\text{NEW}} = \theta_{\text{OLD}} - \eta \left( \frac{\partial C}{\partial \theta} \right) \text{ GRADIENT DESCENT}$$



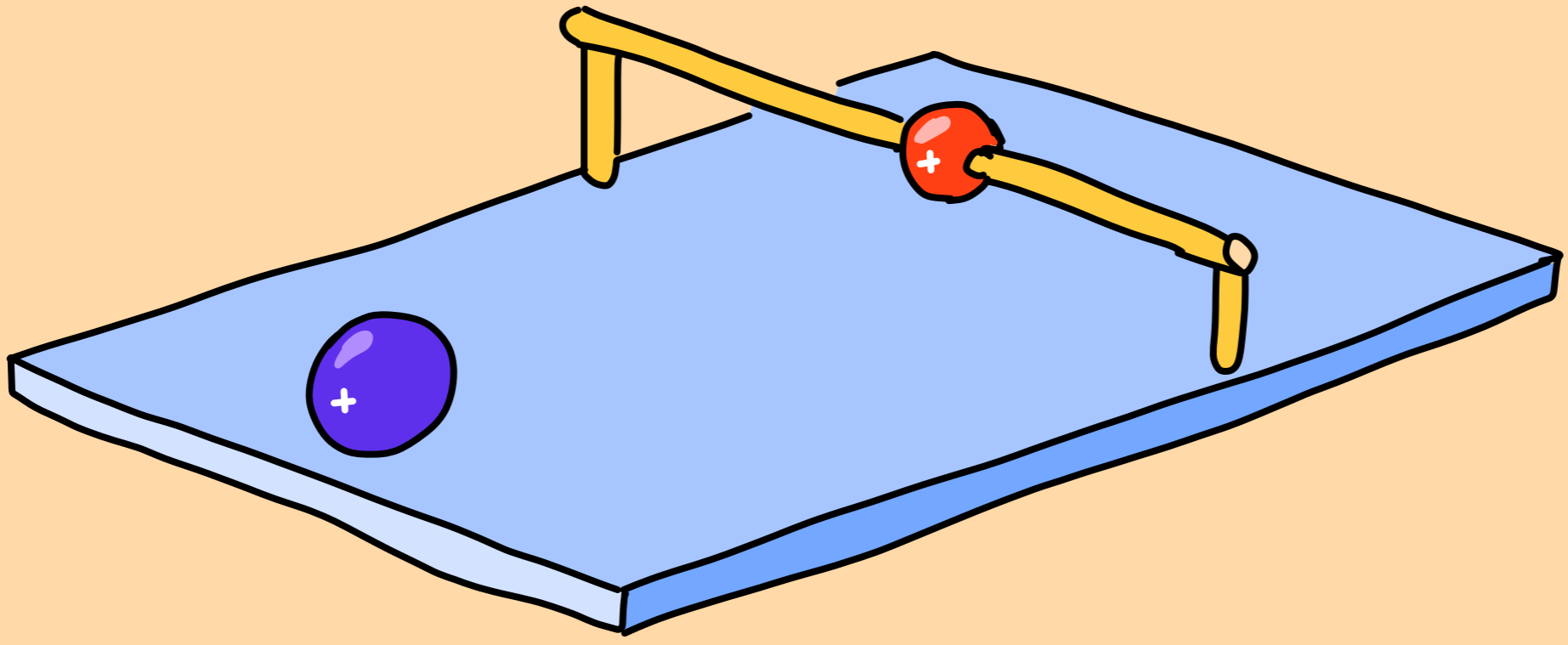
HERE:

ARBITRARY  
TIME-REVERSAL-  
INVARIANT  
HAMILTONIAN

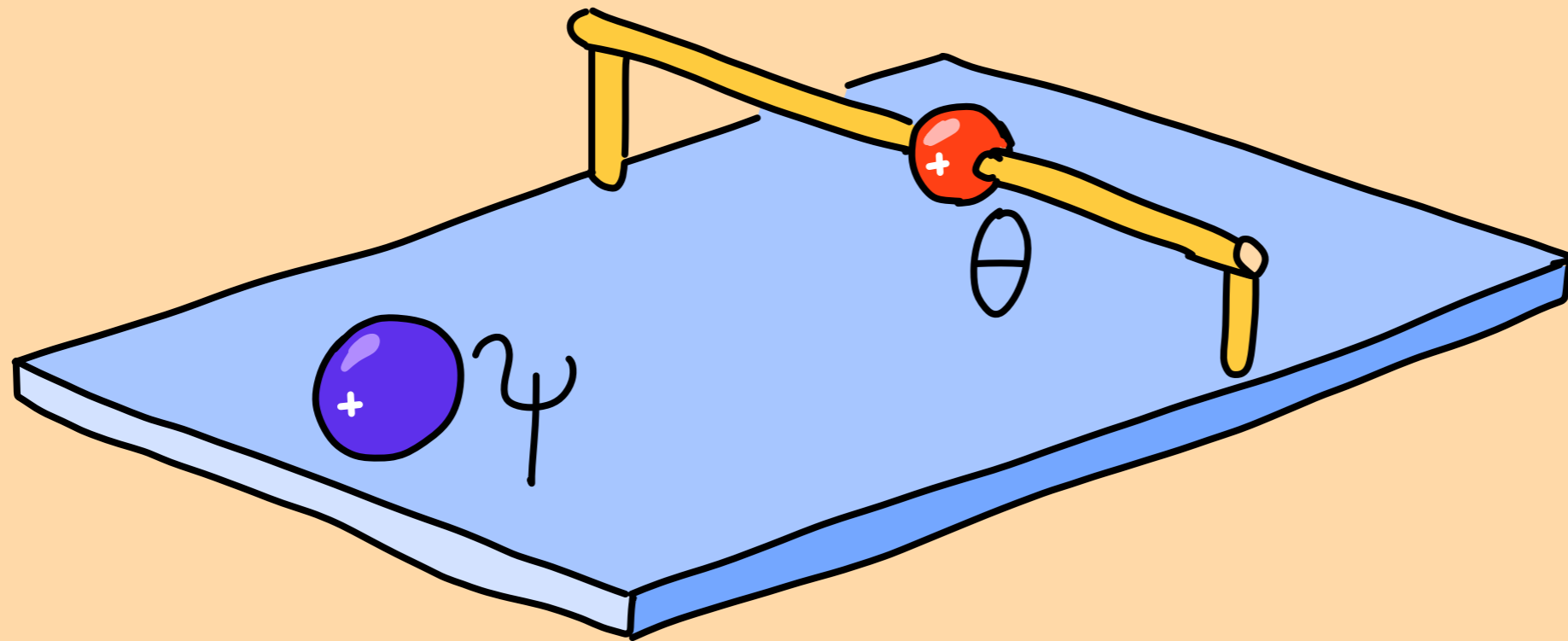


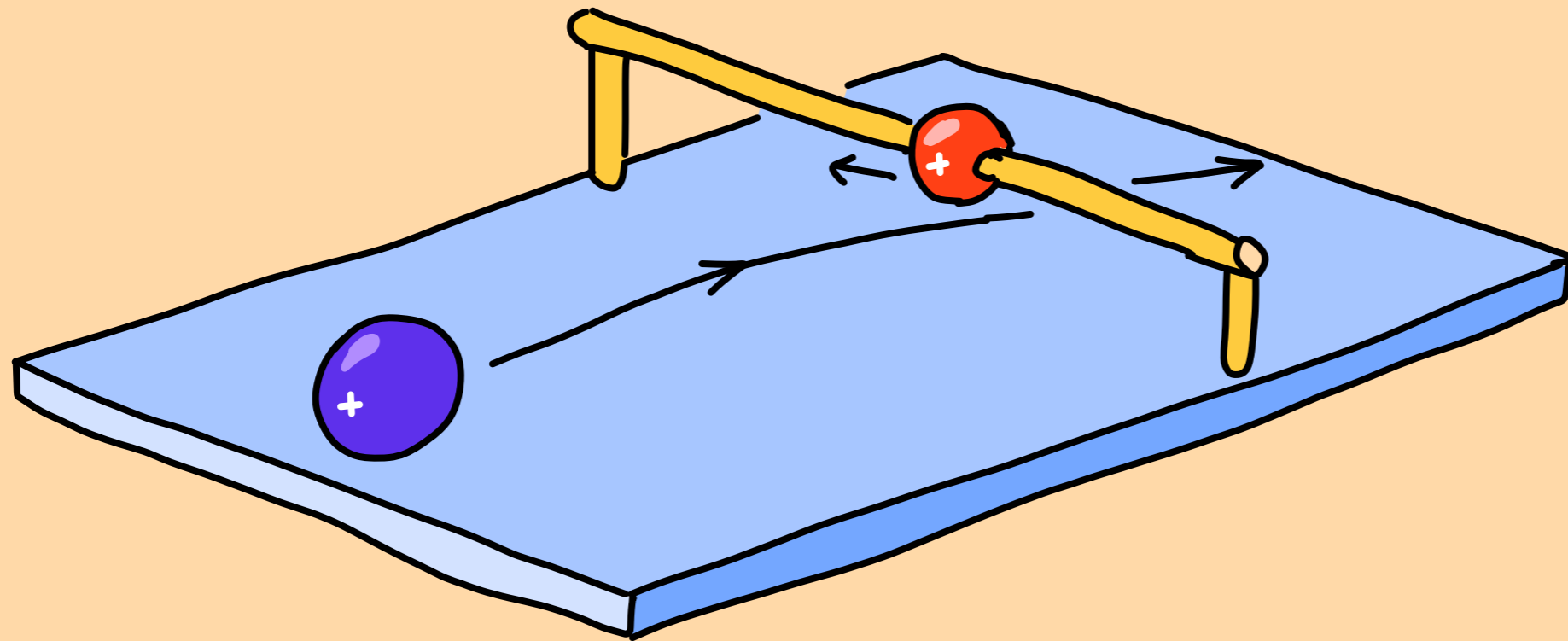
WITH TIME-REVERSAL  
OPERATION (!)

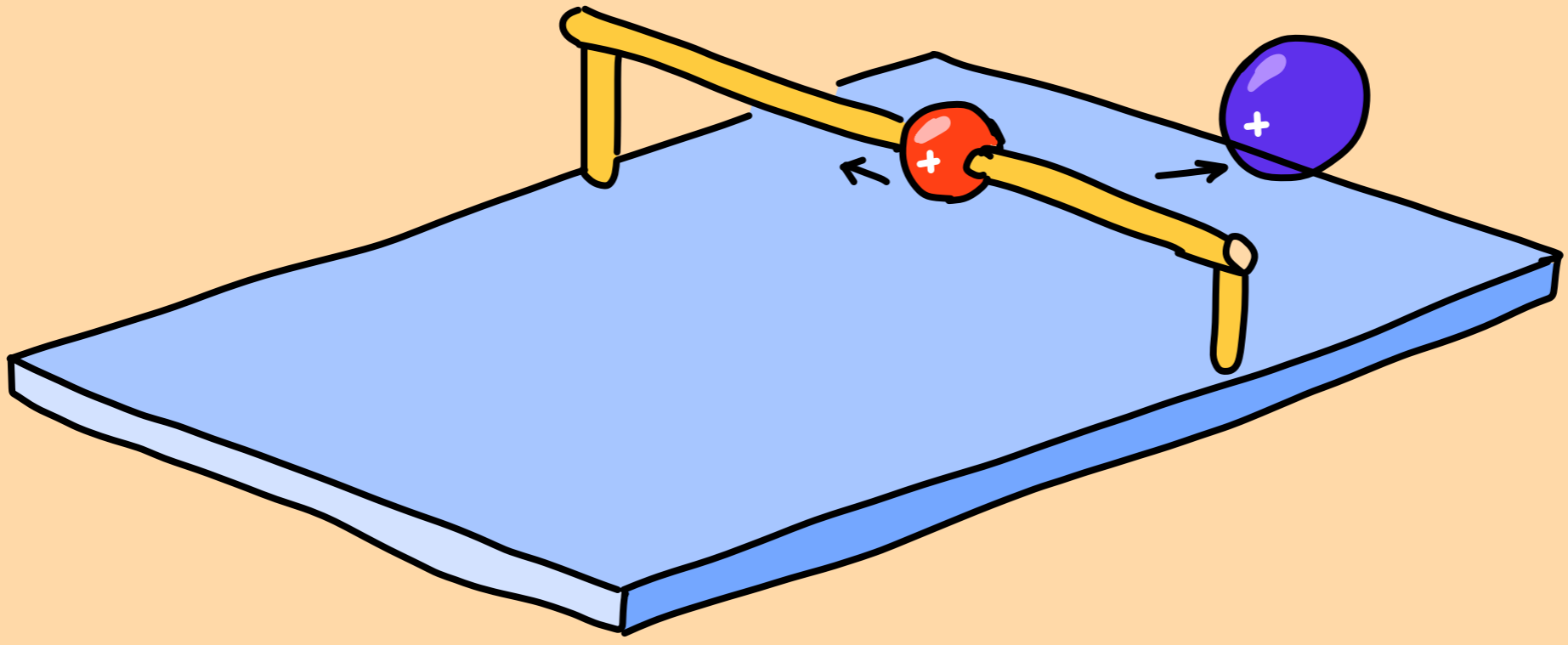
# THE SELF-LEARNING PINBALL MACHINE



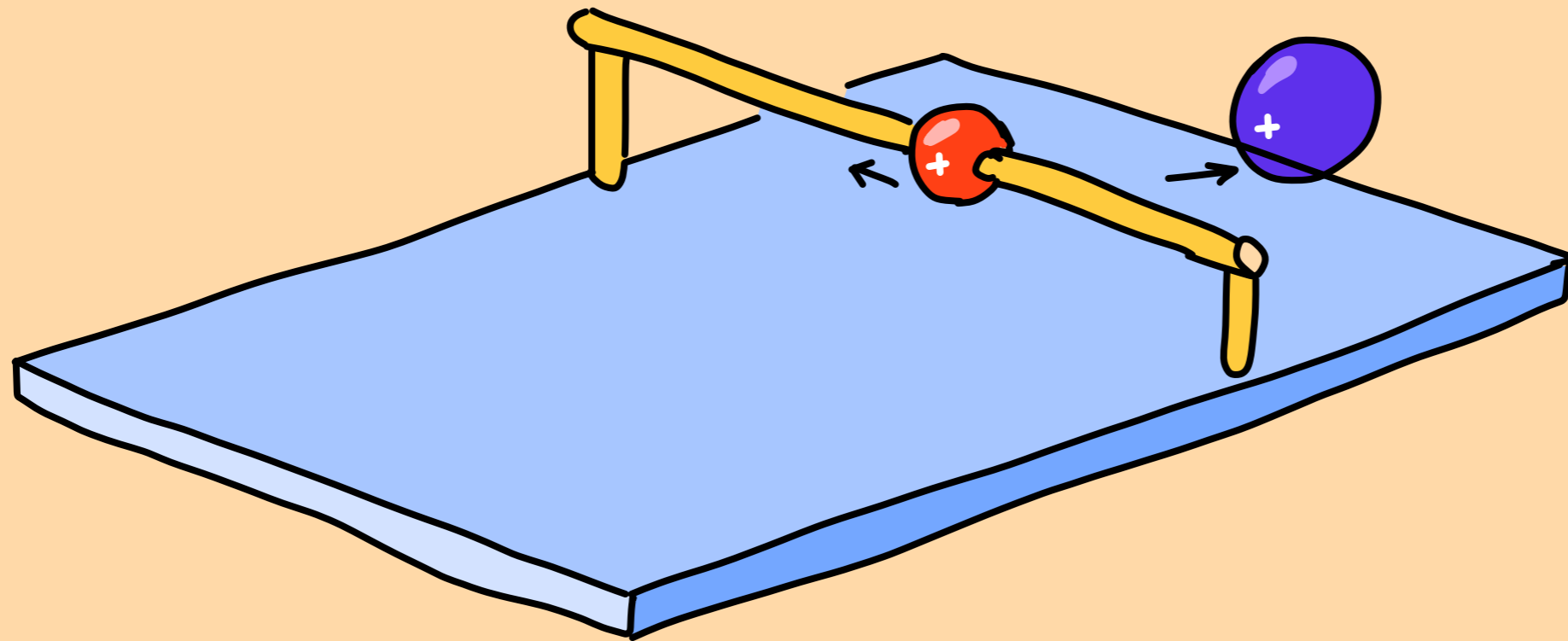


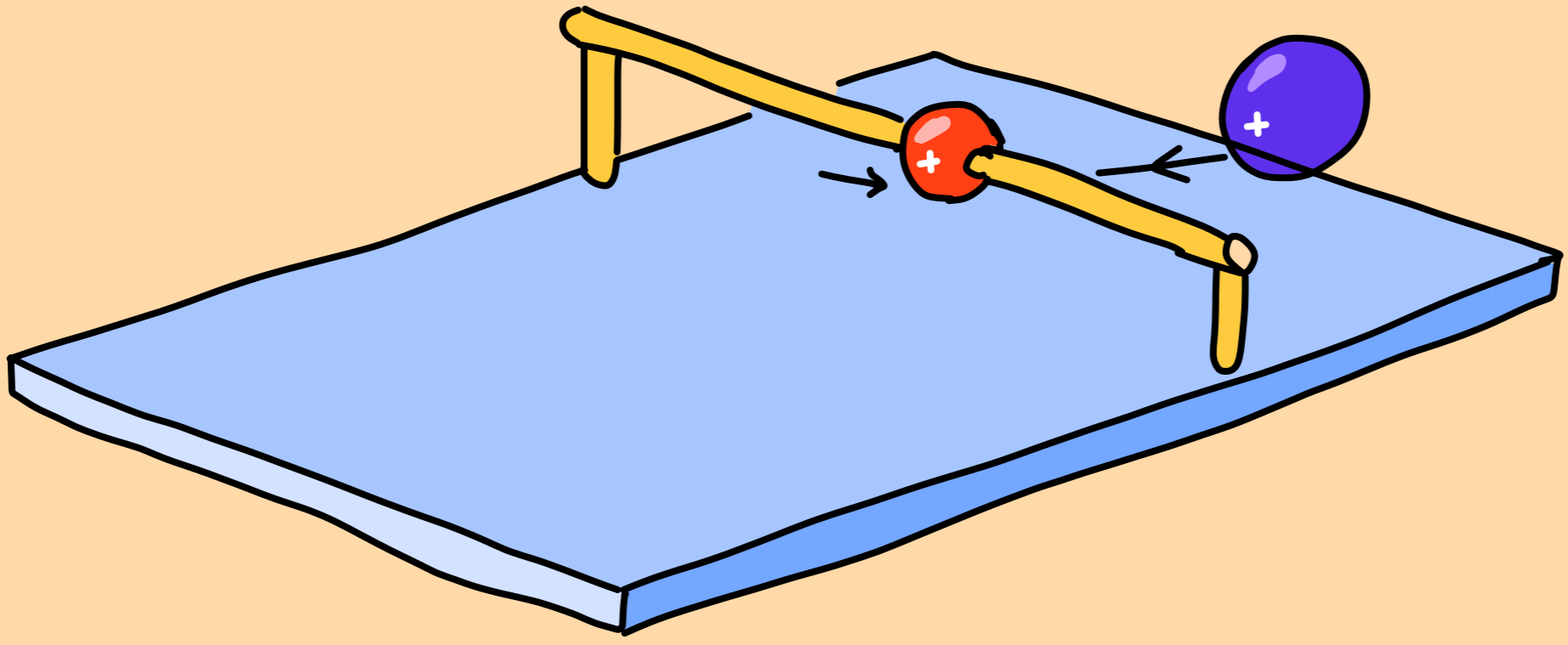


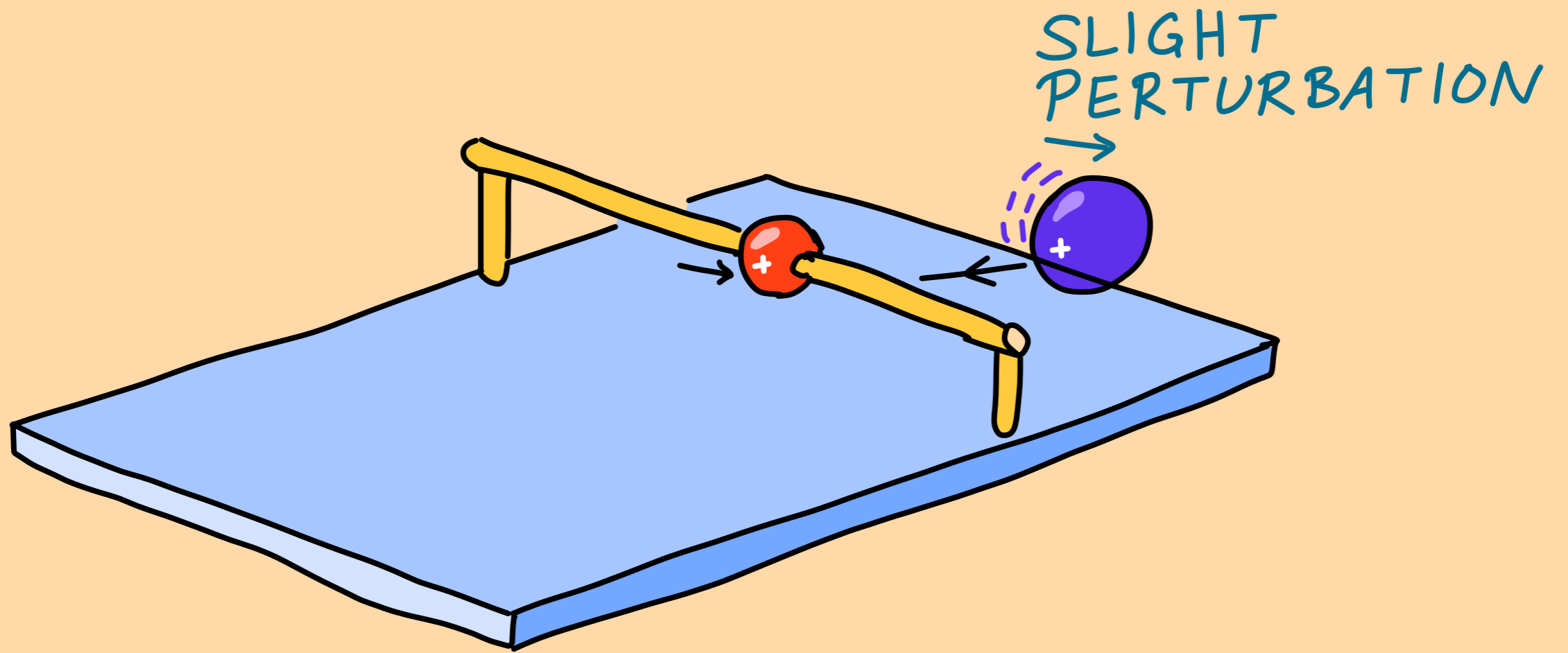


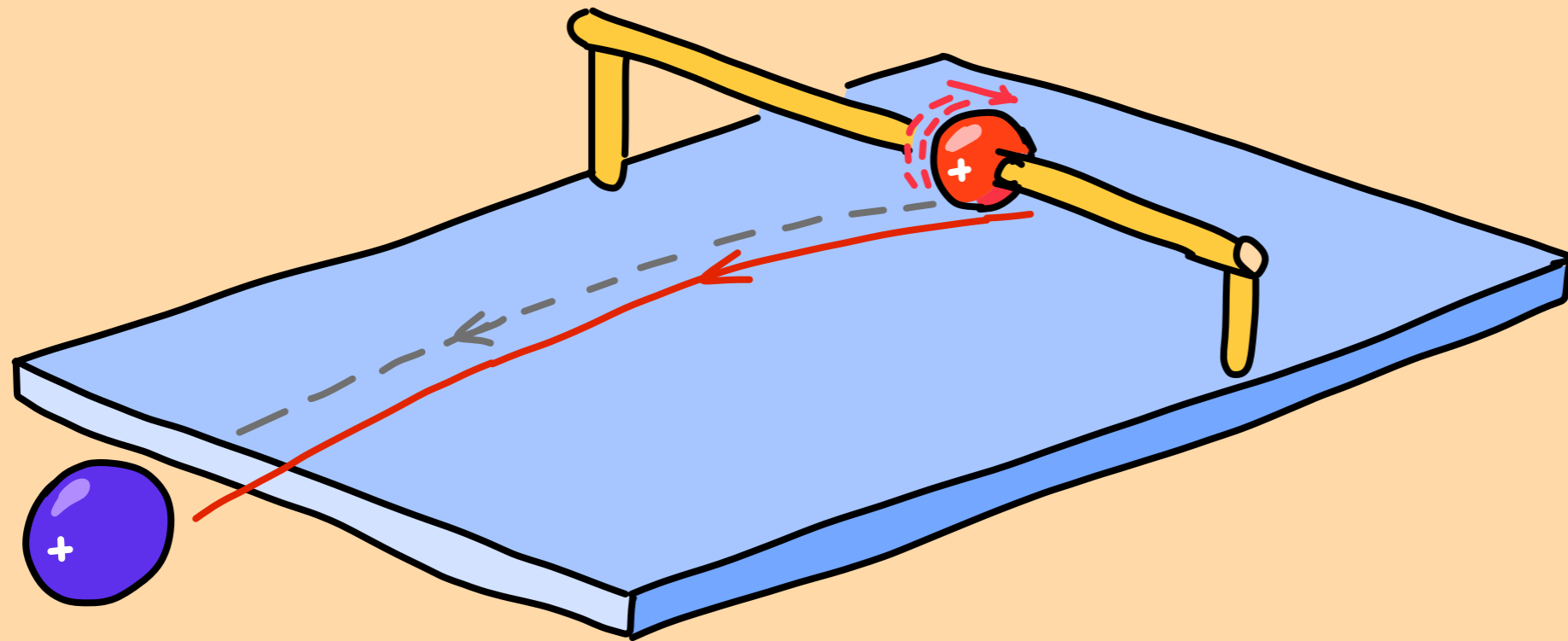


NOW: TIME-REVERSAL  
OPERATION

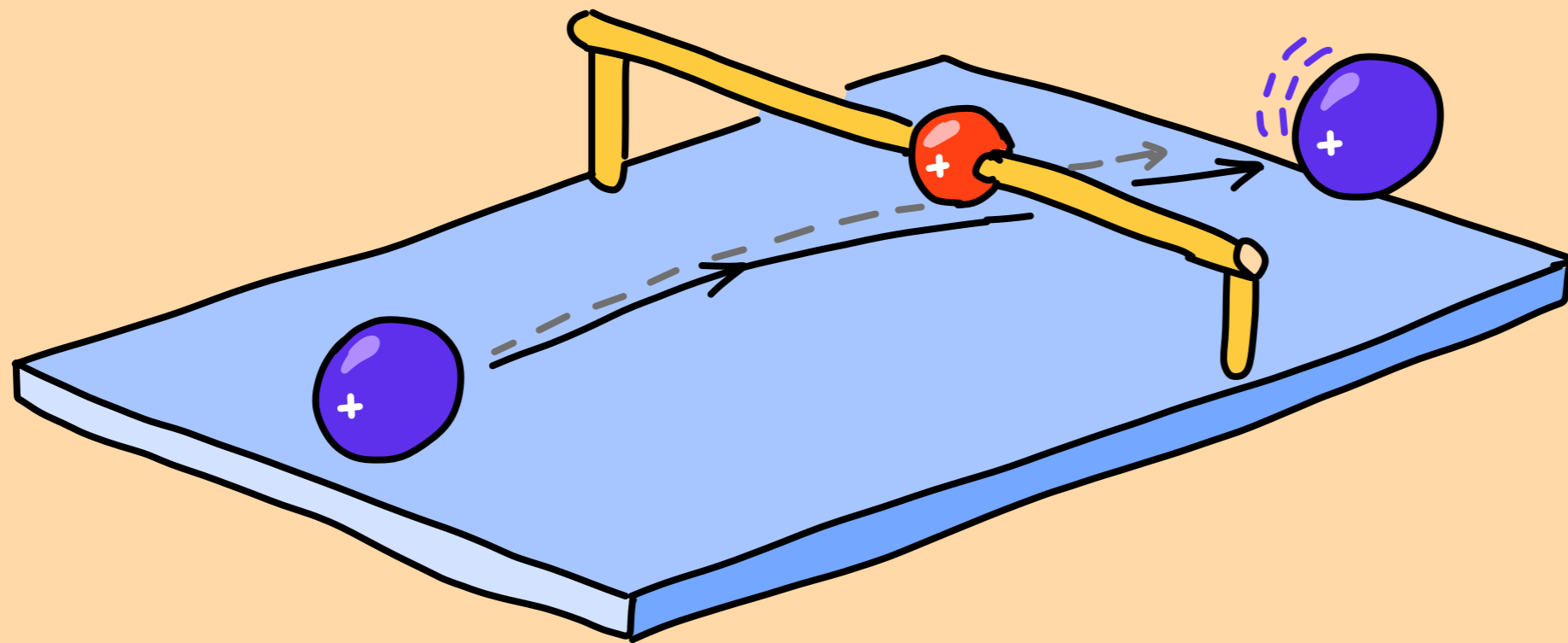




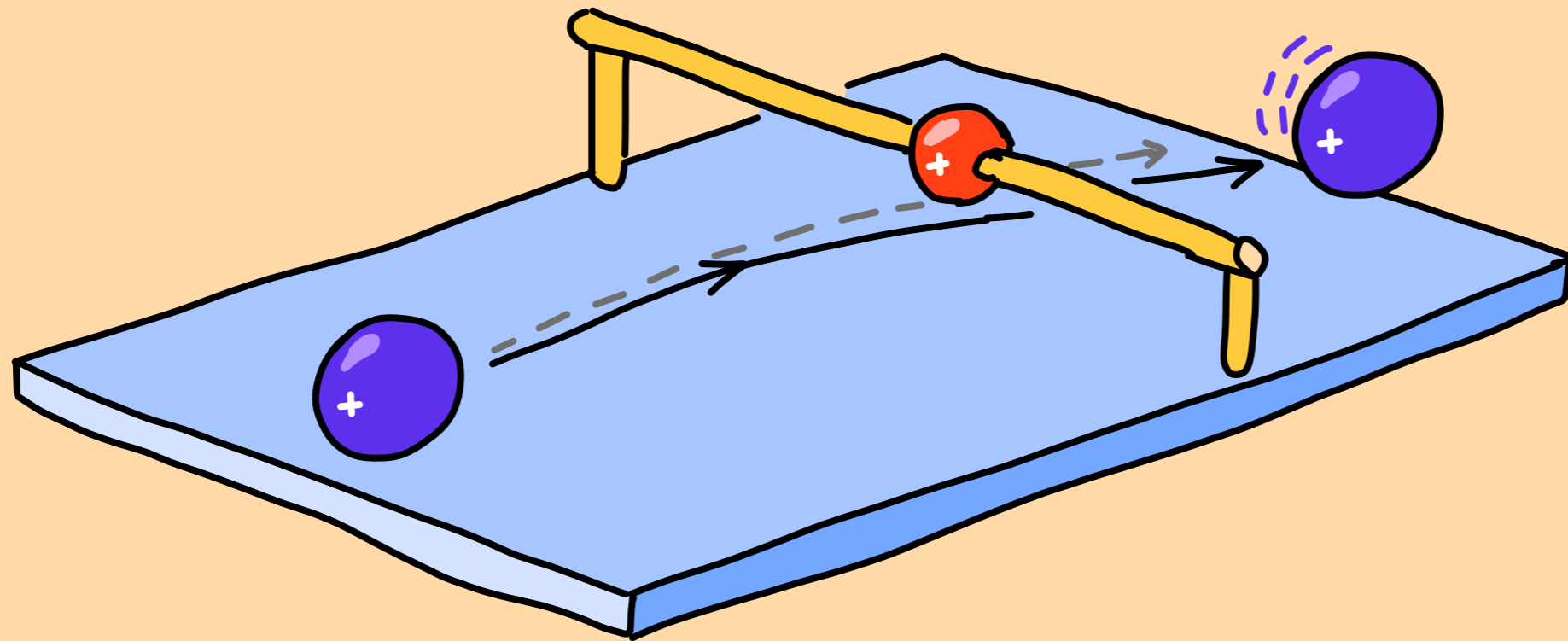


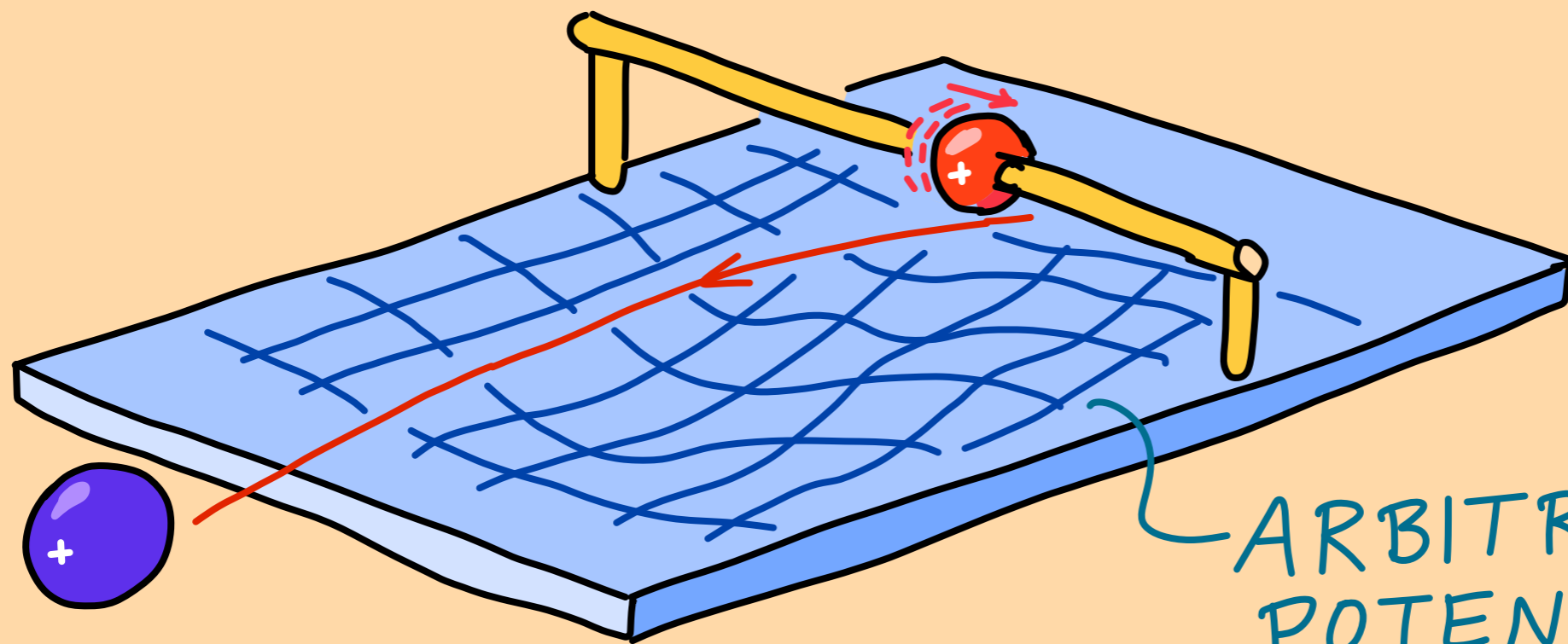






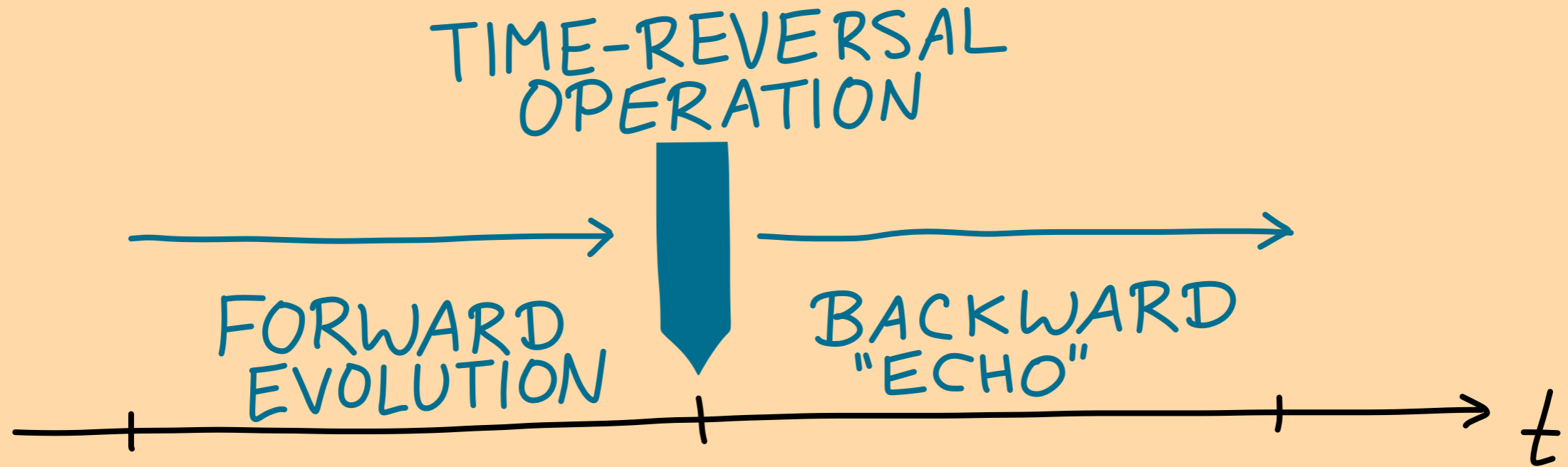
DYNAMICS CHANGED IN  
THE RIGHT WAY  $\Rightarrow$  "LEARNING"!



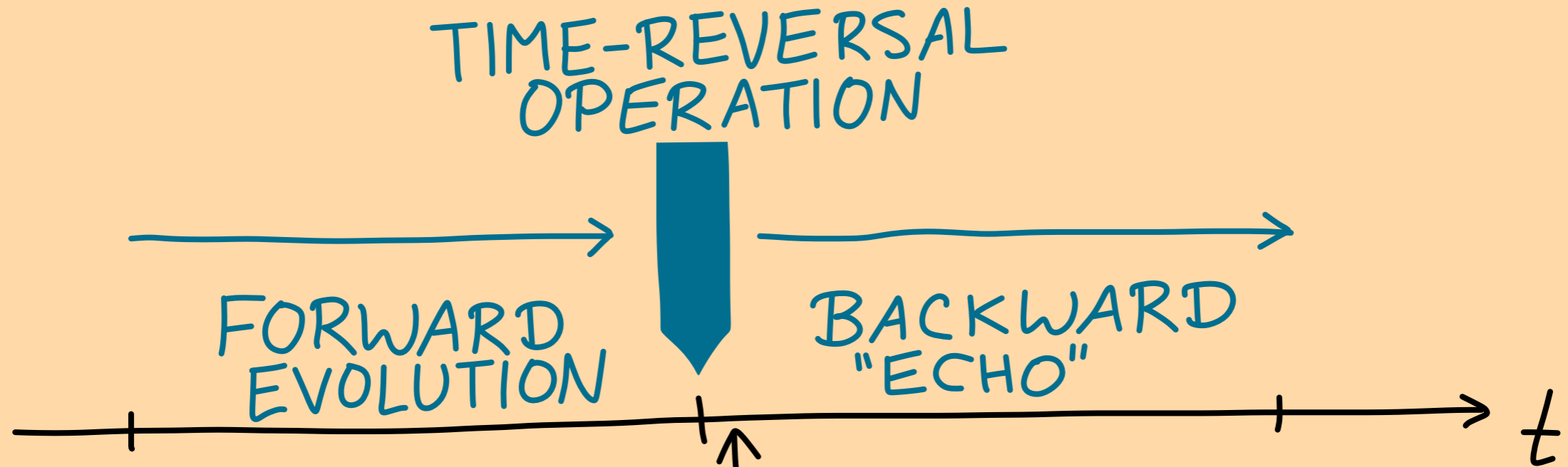


ARBITRARY  
POTENTIAL

# HAMILTONIAN ECHO BACKPROPAGATION



# HAMILTONIAN ECHO BACKPROPAGATION

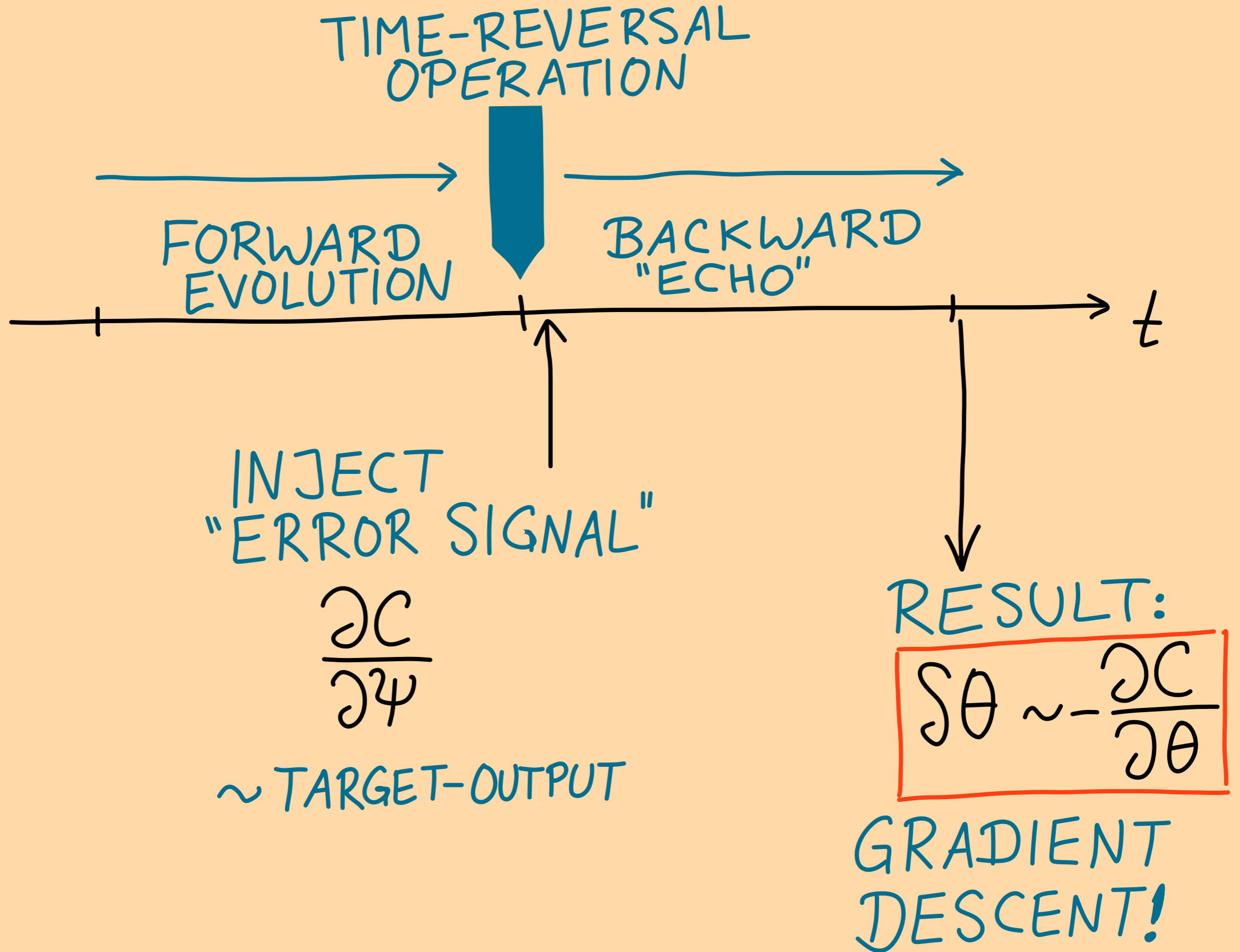


INJECT  
"ERROR SIGNAL"

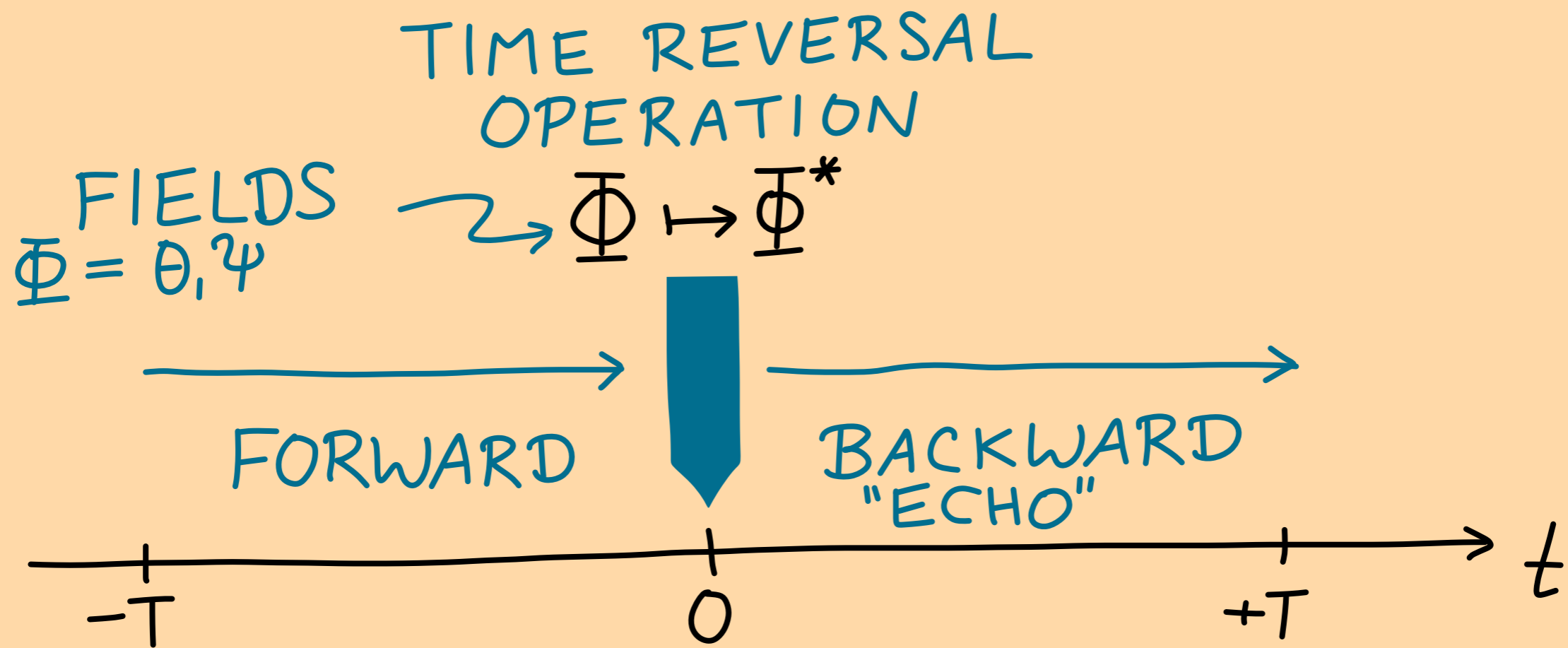
$$\frac{\partial C}{\partial \psi}$$

~ TARGET-OUTPUT

# HAMILTONIAN ECHO BACKPROPAGATION



# BRIEFLY : THE MATH



TIME-REVERSAL INVARIANCE

$$\Rightarrow \underline{\Phi}_{\text{ECHO}}(t) = \Phi^*(-t)$$



$$\frac{\partial C}{\partial \theta} = ?$$

NEEDED:  
PERTURBED  
FORWARD  
EVOLUTION

ACCESSIBLE:  
PERTURBED  
BACKWARD  
EVOLUTION

$\mathcal{Y}_{\Phi}(0, -T)^+$   
GREEN'S  
FUNCTION

→  
RELATED  
DUE TO  
TIME-REVERSAL-  
INVARIANCE

$\mathcal{Y}_{\Phi_{\text{ECHO}}}(T, 0)$

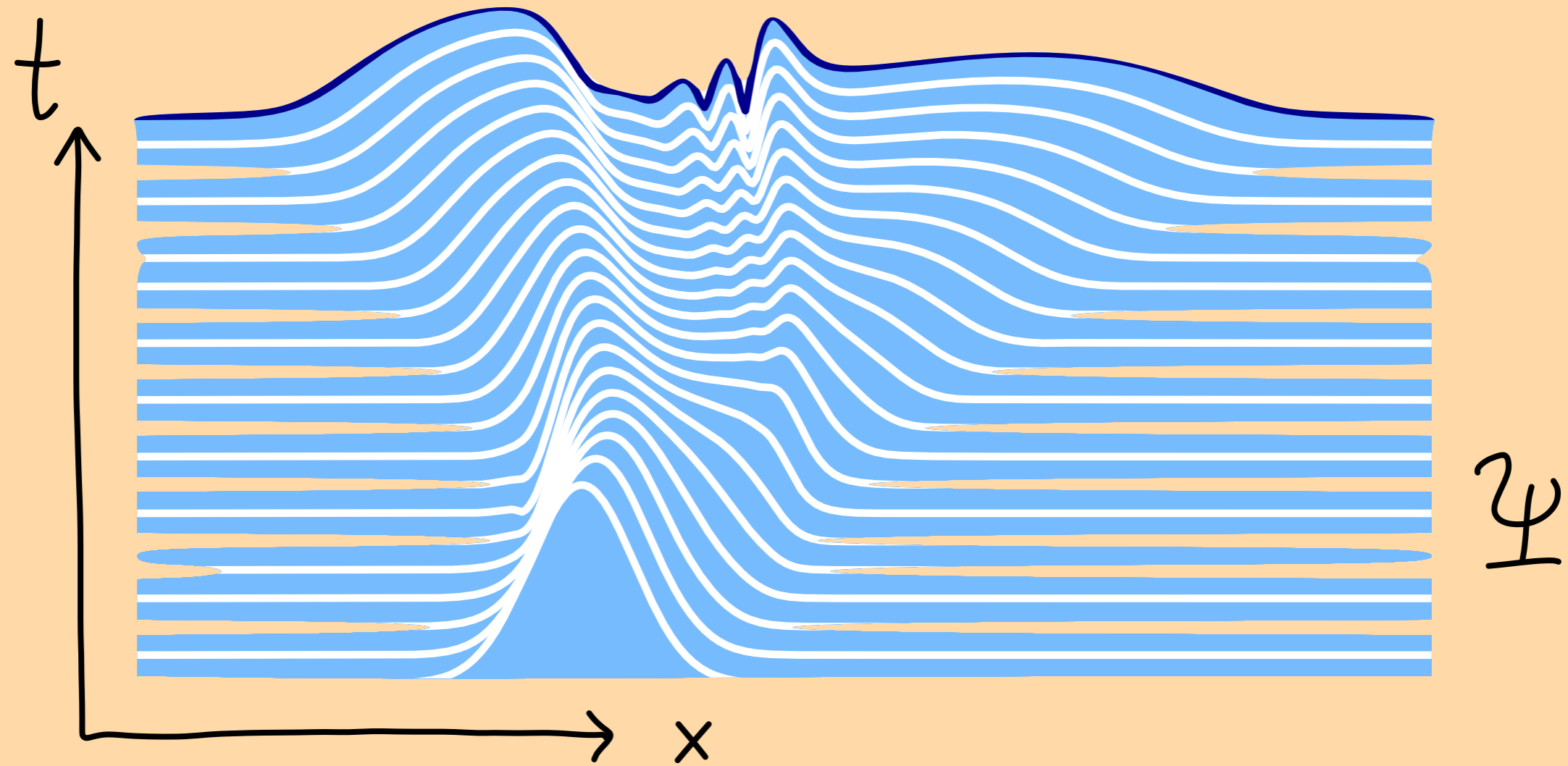
⇒ ... ⇒

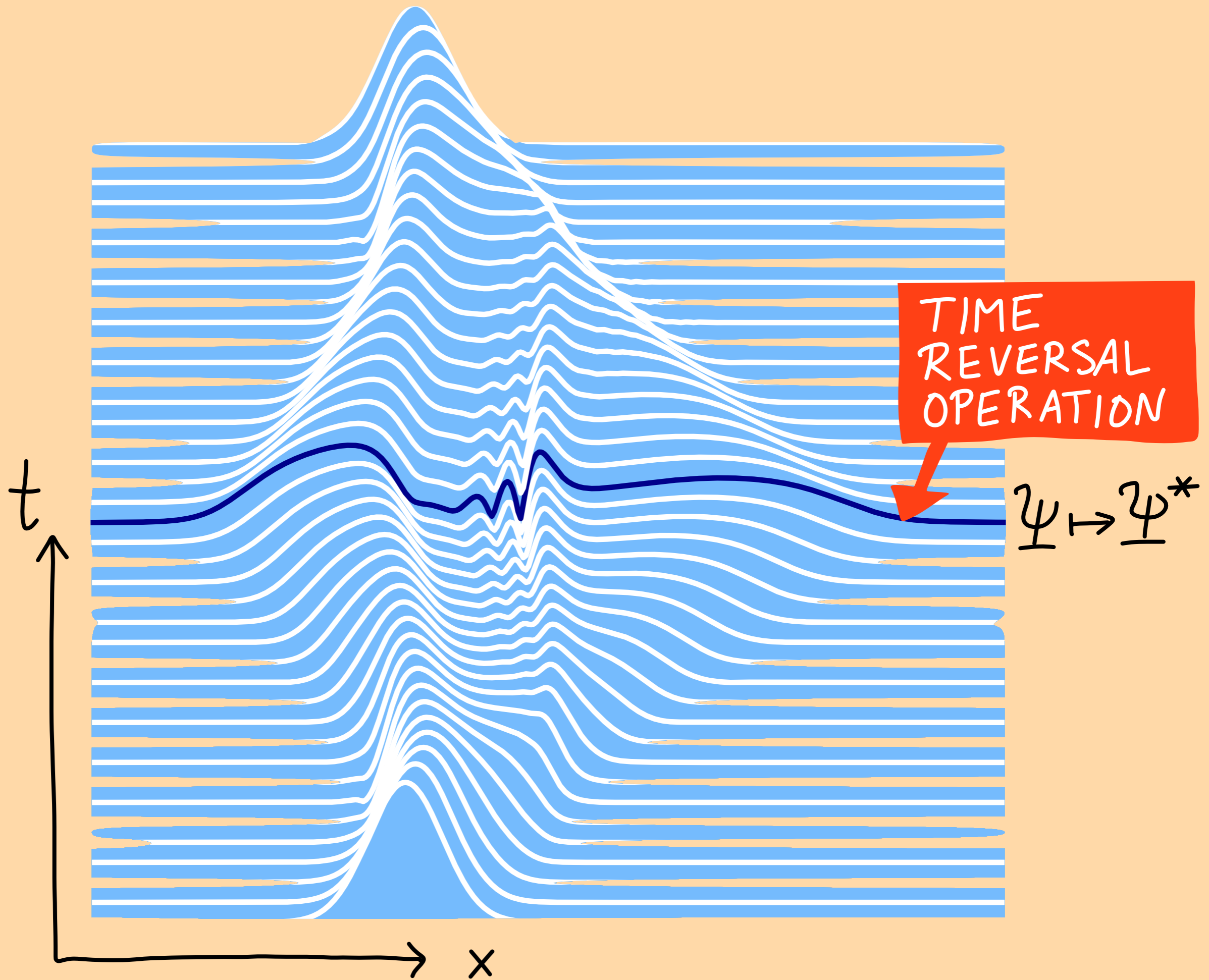
RESULT:

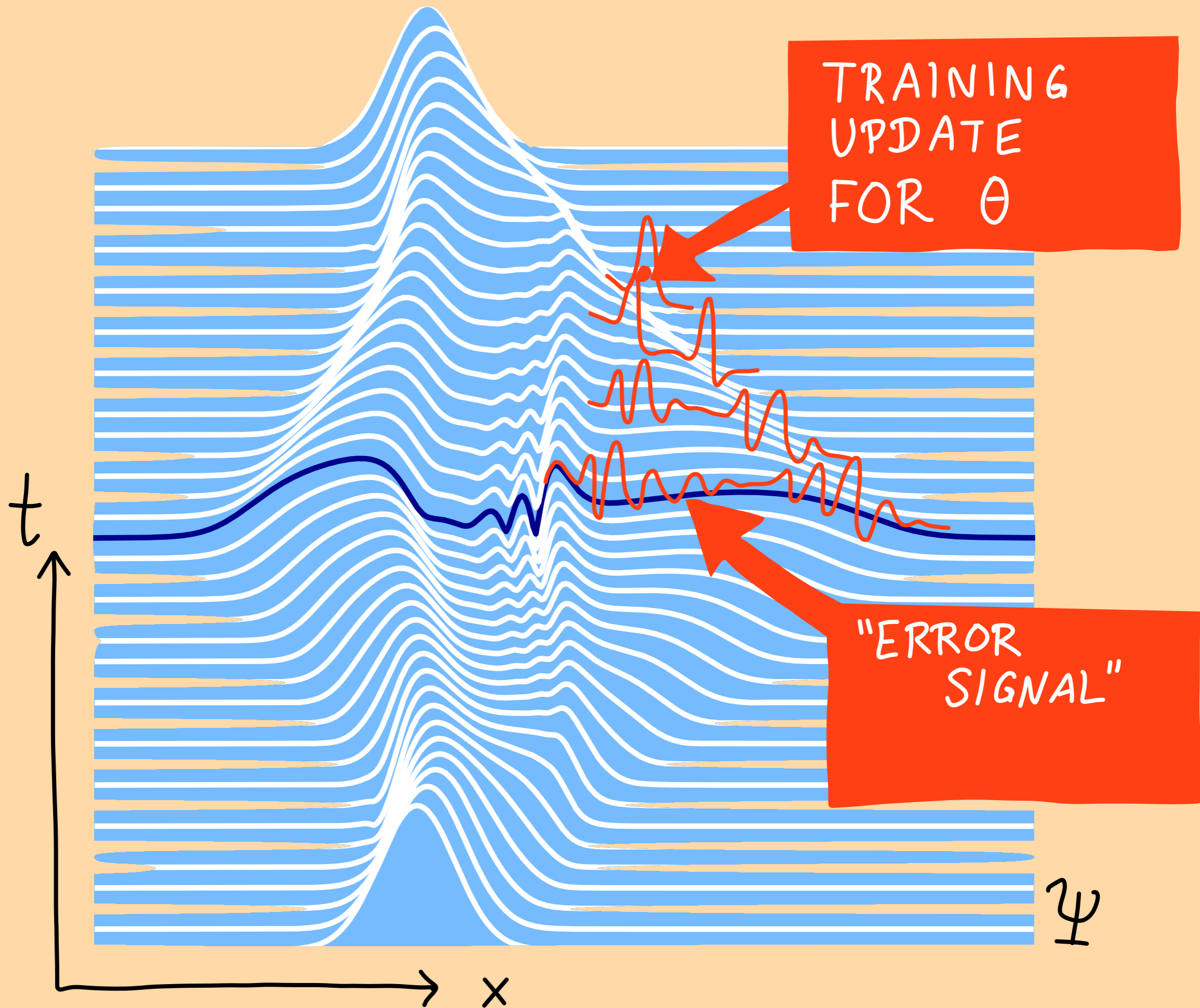
$$\delta\theta \sim -\frac{\partial C}{\partial \theta}$$

cf adjoint  
method

SELF-LEARNING  
NONLINEAR  
WAVE FIELDS

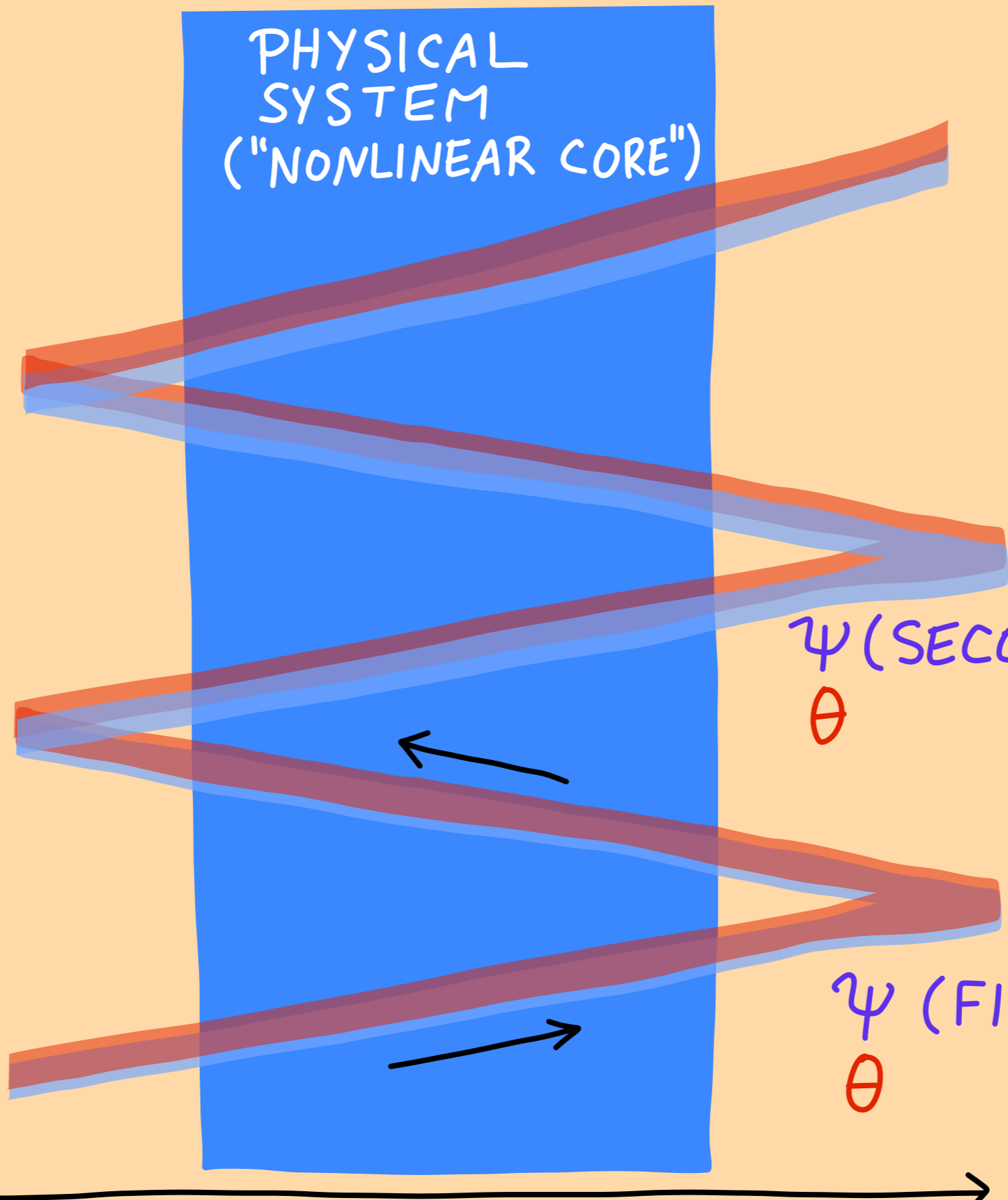






$t$

PHYSICAL SYSTEM  
("NONLINEAR CORE")



$\psi$  (SECOND SAMPLE)  
 $\theta$

$\psi$  (FIRST SAMPLE)  
 $\theta$

$x$

# COMPARE ...

PSALTIS ET AL  
(1987 #)

NONLIN. OPTICS  
SELF-LEARNING

BUT: NEED TO  
ENGINEER  
FORWARD vs  
BACKWARD  
TRANSMISSION

HUGHES, ..., FAN  
(2018)

GENERAL PHYSICAL  
BACKPROP

BUT: NO PHYSICAL  
UPDATE

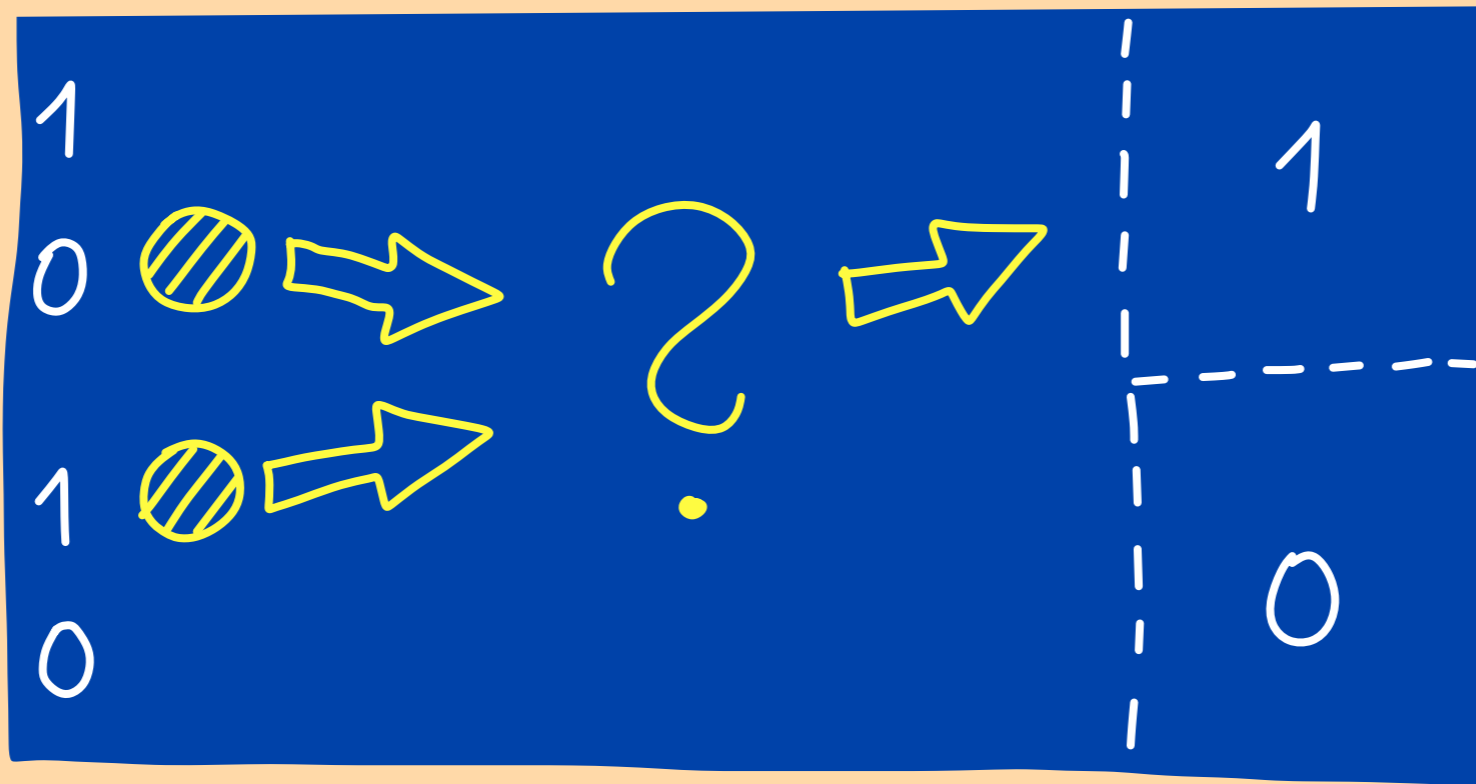


# SUMMARY: HAMILTONIAN ECHO BACKPROPAGATION

- ✓ PHYSICAL BACKPROPAGATION
- ✓ PHYSICAL LEARNING UPDATE  
(VIA INTRINSIC DYNAMICS)
- ✓ HAMILTONIAN-INDEPENDENT  
(ANY TIME-REVERSAL-INVARIANT  
SYSTEM)
- ✓ NO ACCESS TO INTERNALS  
OF "NONLINEAR CORE" = PHYSICAL SYSTEM  
NEEDED
- ✓ AGNOSTIC OF PHYSICS PLATFORM

# FIRST NUMERICAL EXAMPLES

# LEARNING XOR



## COUPLED NONLINEAR WAVES

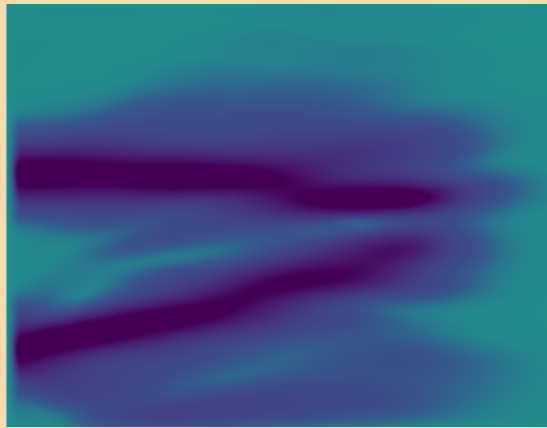
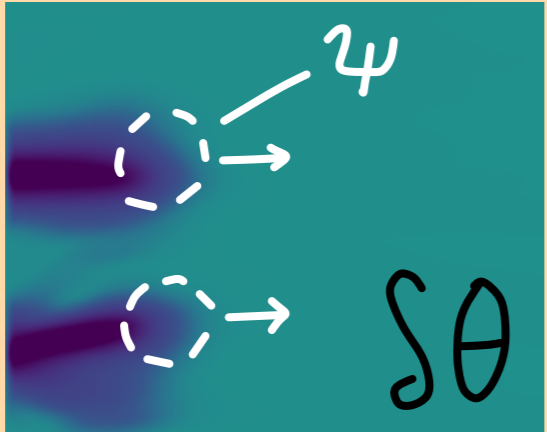
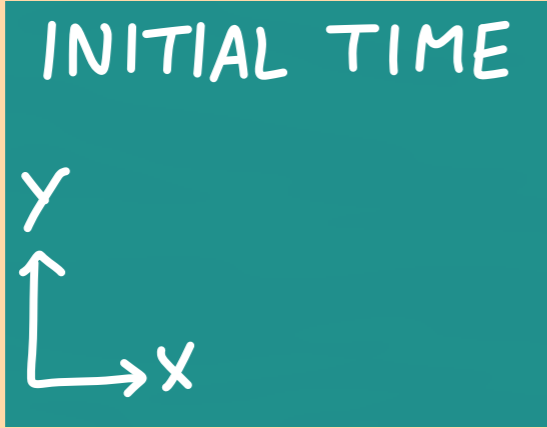
$$i\dot{\Psi} = \frac{\beta}{2} \Delta^2 \Psi + (\chi\theta + \underbrace{g|\Psi|^2}_{\text{KERR}}) \Psi$$

$$i\dot{\Theta} = i\Omega_L \pi_\theta + \chi|\Psi|^2$$



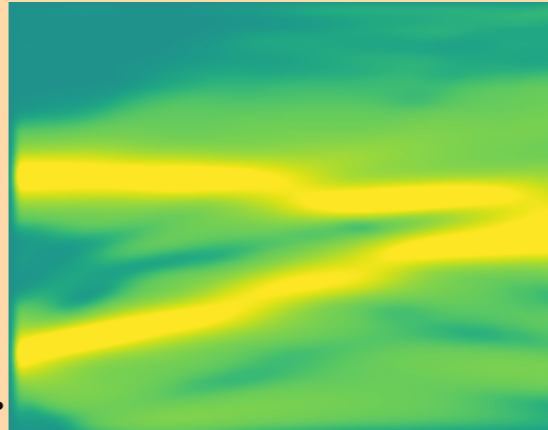
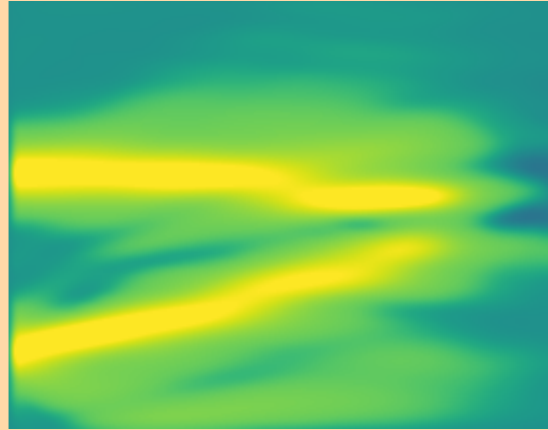
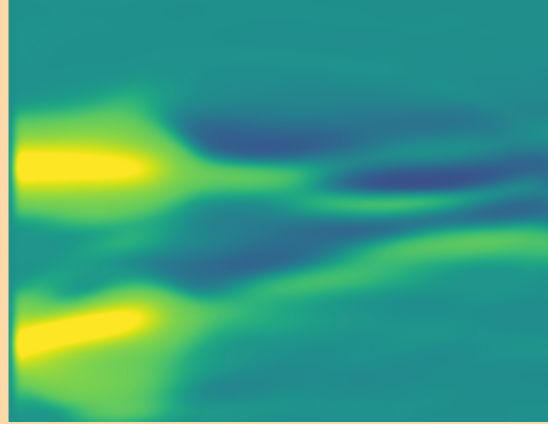
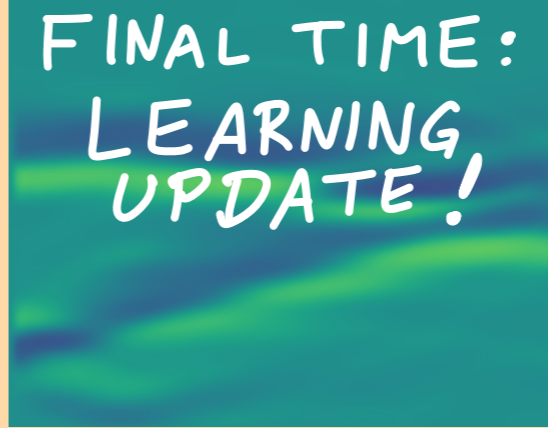
FORWARD

TIME



TIME REVERSAL OPERATION

+ ERROR SIGNAL



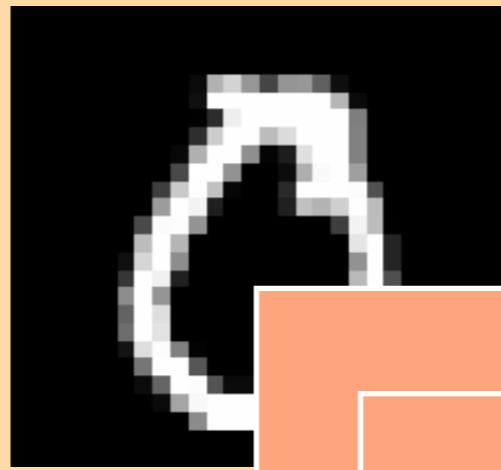
TIME

BACKWARD

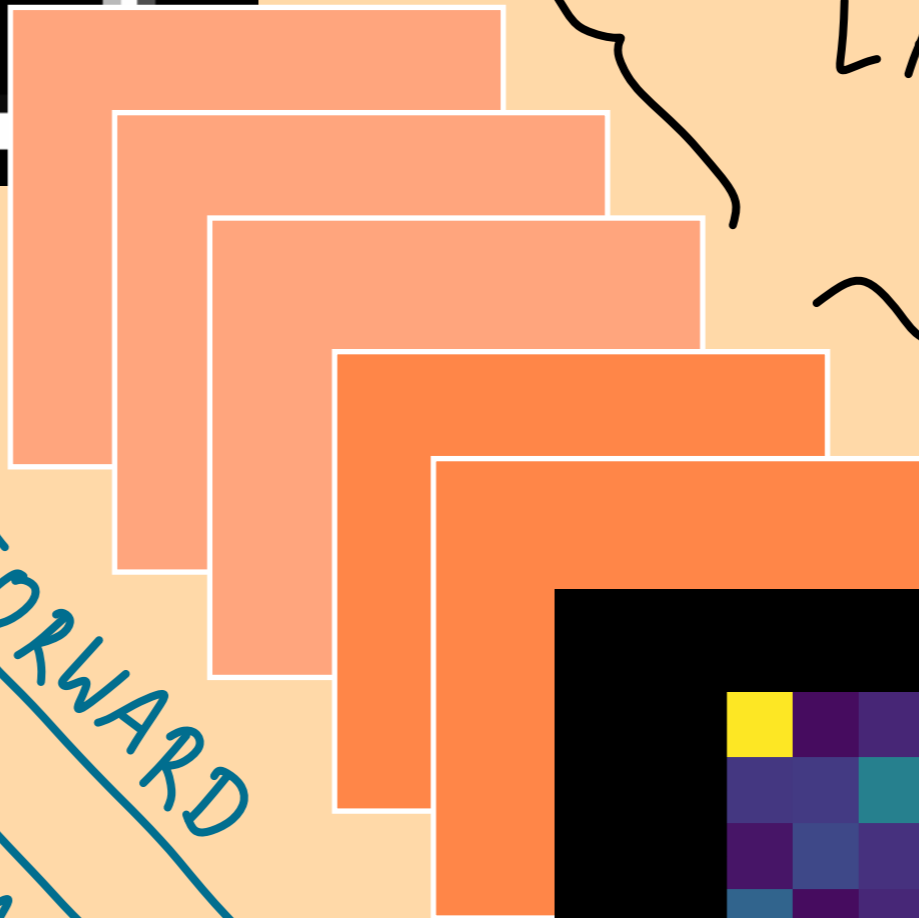


# IMAGE CLASSIFICATION

INPUT

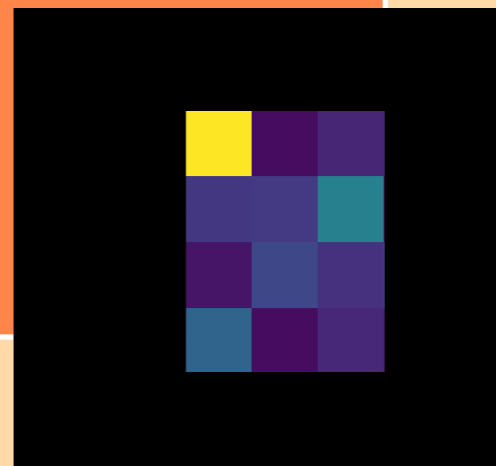


CONVOLUTIONAL  
LAYERS (DFT)



FULLY  
CONNECTED  
LAYERS

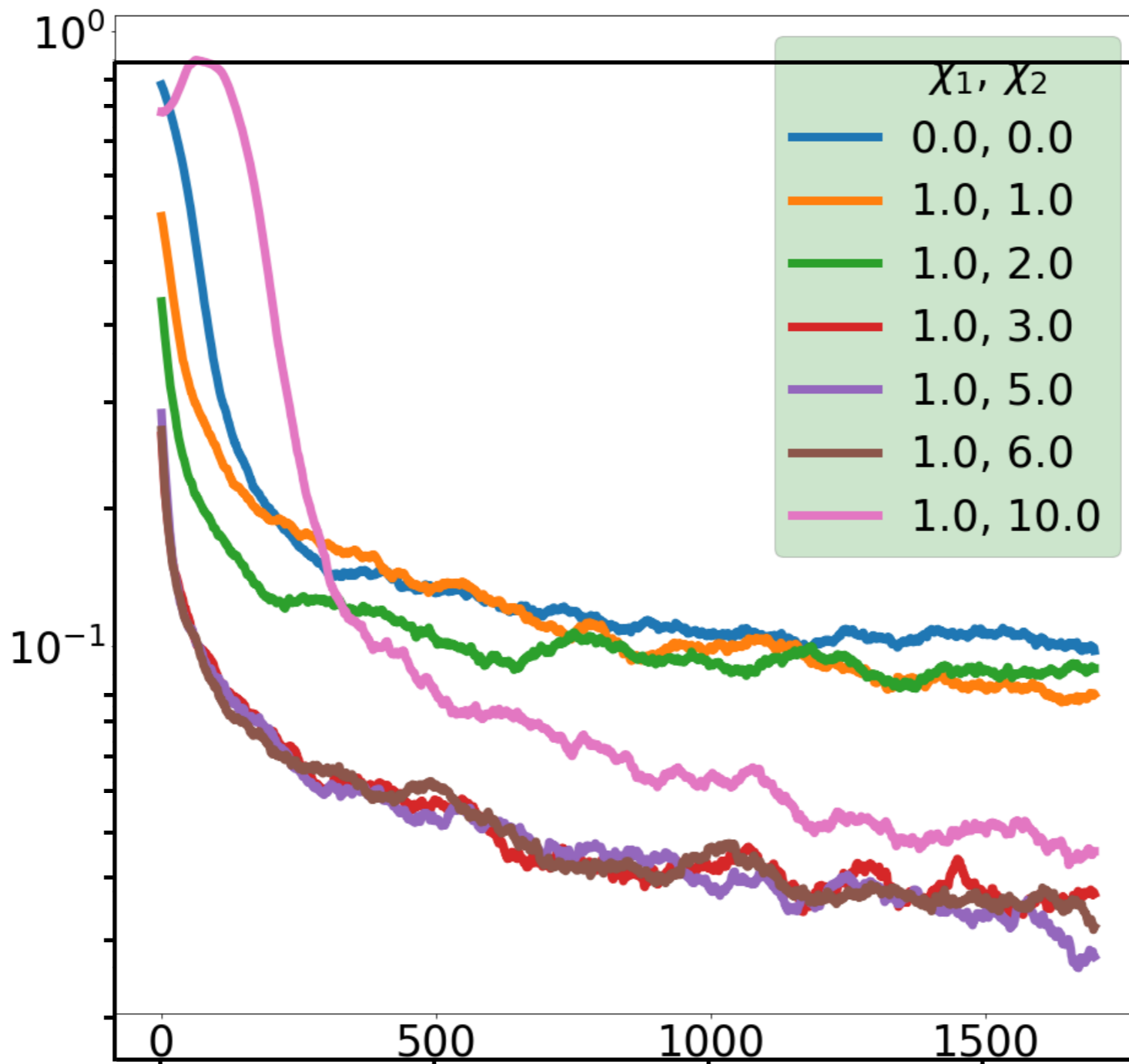
FORWARD  
← BACKWARD



OUTPUT  
("ONE-HOT")

MNIST DATA SET

TRAINING ERROR  $\longrightarrow$



TRAINING ITERATION  $\longrightarrow$



POSSIBLE EXPERIMENTAL  
PLATFORMS

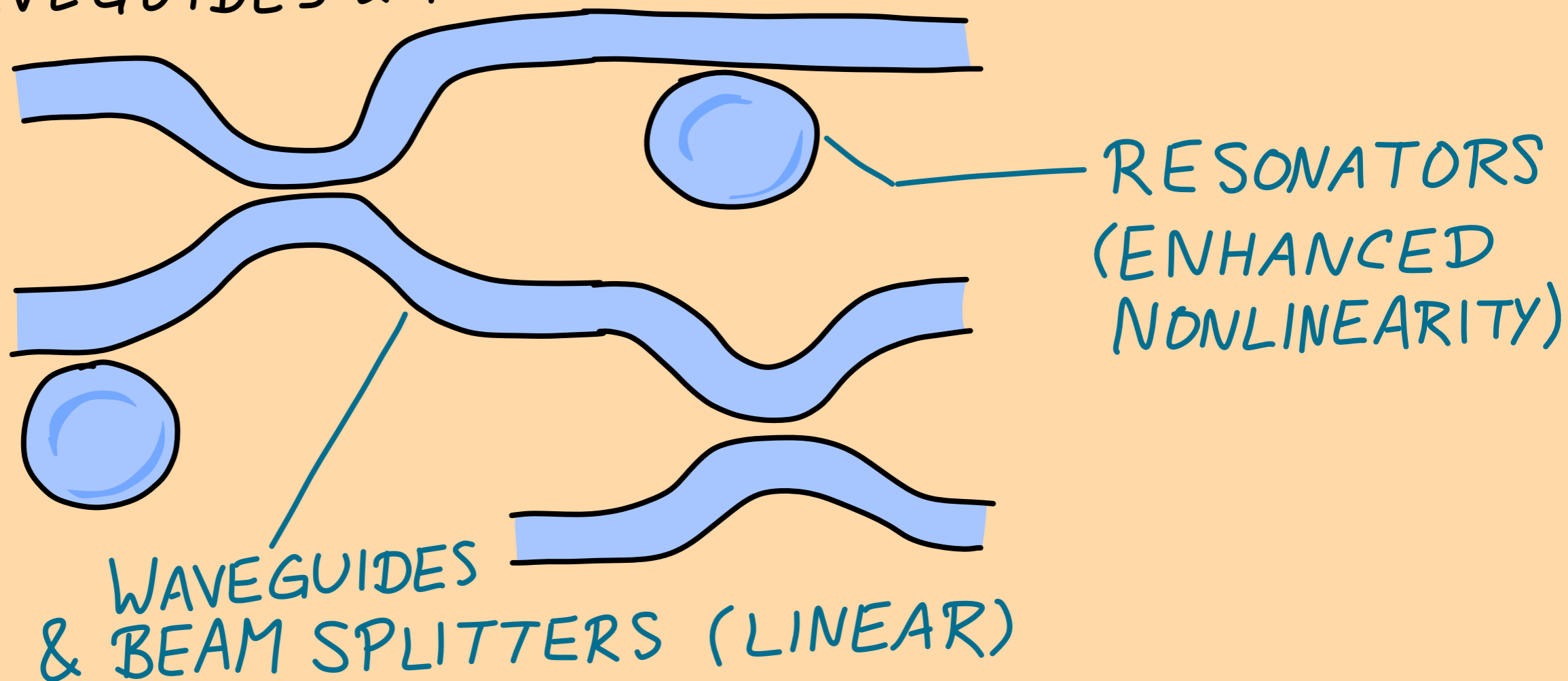
# REQUIREMENTS & CHALLENGES

- NONLINEAR
- LOW LOSS  
(→ RE-AMPLIFICATION)
- TIME-REVERSAL OPERATION [ & "DECAY STEP" ]
- NOISE, NONIDEALITY IN THESE OPERATIONS  
(→ CALIBRATION, ROBUSTNESS)
- LONG-TERM STORAGE OF LEARNING FIELD  
(→ READOUT)

# NONLINEAR OPTICS

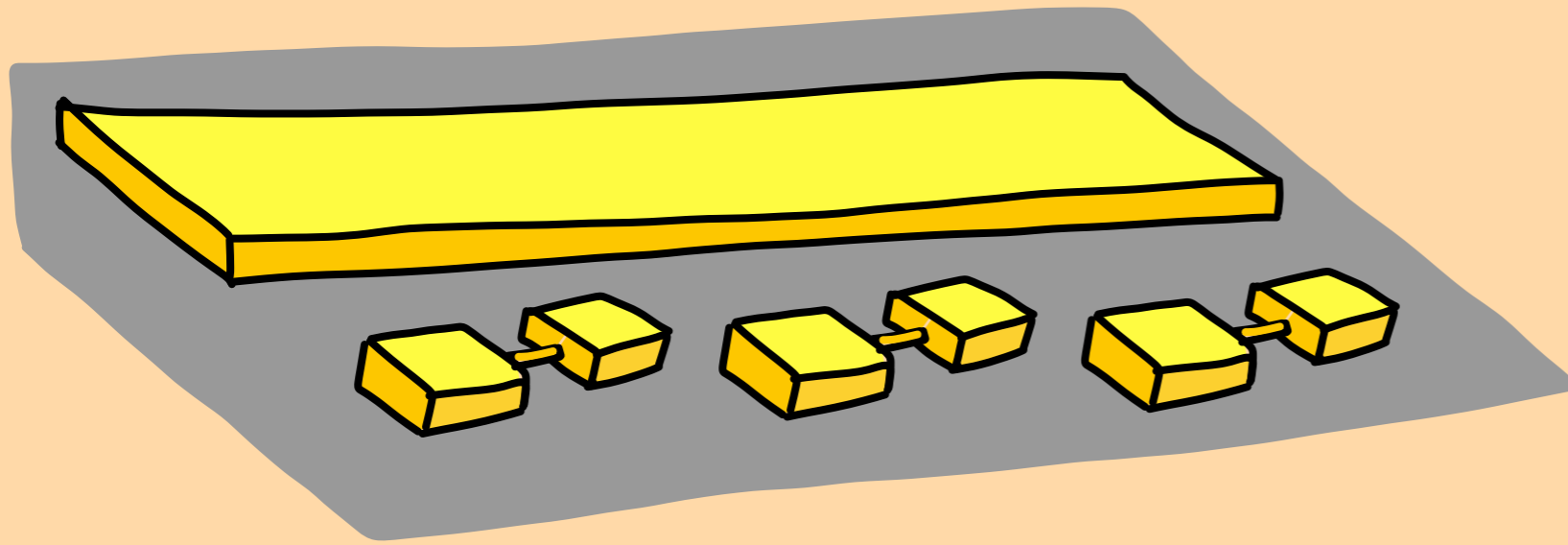
EXAMPLE: INTEGRATED PHOTONICS

WAVEGUIDES & NONLINEAR RESONATORS

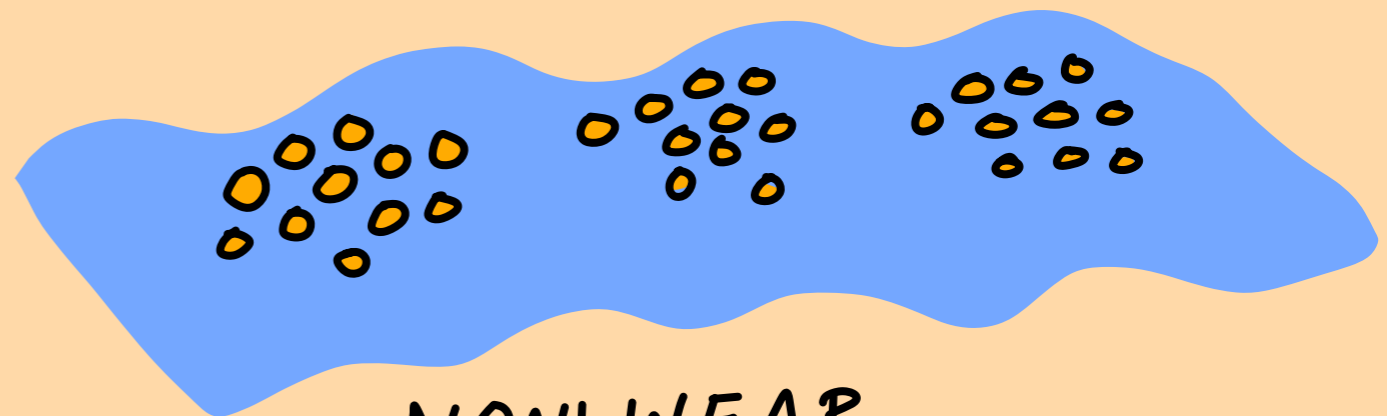


BUILD ON OPTICAL NEURAL NETWORKS:

WAGNER & PSALTIS (1987ff.), SKINNER ET AL (1995),  
SHEN,..., ENGLUND, SOLJACIC (2017), HUGHES,..., FAN (2018),  
GUO,..., LVOVSKY (2019), FELDMAN,..., PERNICE (2019), ...  
REVIEW: WETZSTEIN ET AL (2020)



SUPERCONDUCTING  
MICROWAVE CIRCUITS



NONLINEAR  
MATTER WAVES

↑↑↑↑↑↑↑↑↑↑↑↑↑↑↑↑  
SOME SPIN WAVES

(TIME-REVERSAL SYMMETRY!)

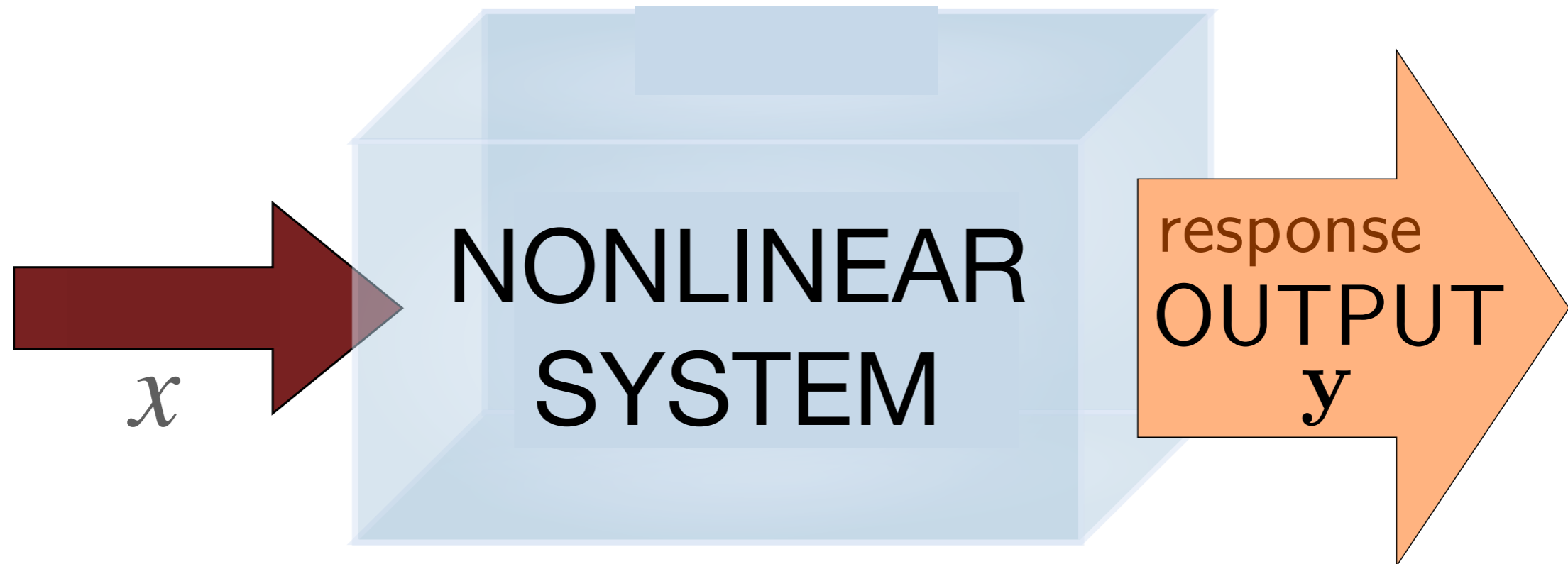
# **Nonlinear neuromorphic system from linear wave scattering**

Clara Wanjura & F.M. [arXiv 2308.16181](https://arxiv.org/abs/2308.16181)



# typical optical neuromorphic system

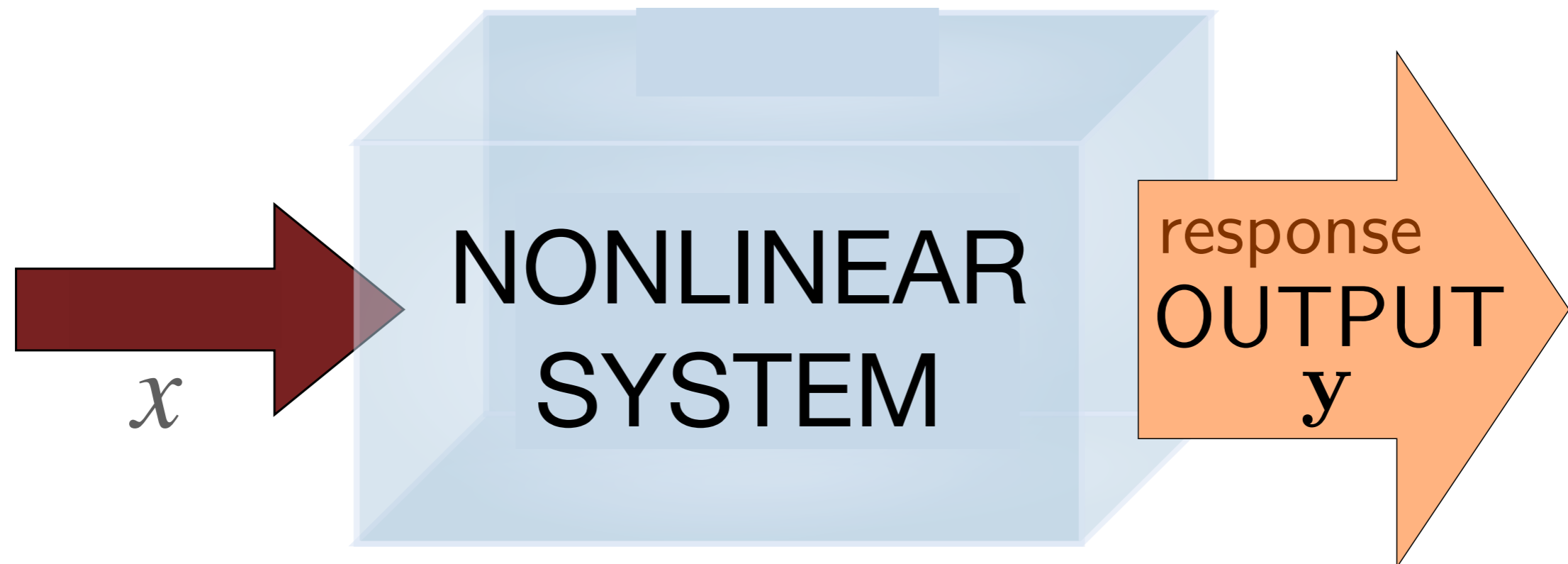
nonlinearity for expressivity



$$y = f(x)$$

# typical optical neuromorphic system

**nonlinearity for expressivity**



$$y = f(x)$$

optical nonlinearities (but: power levels)  
optoelectronics (but: delays, power)



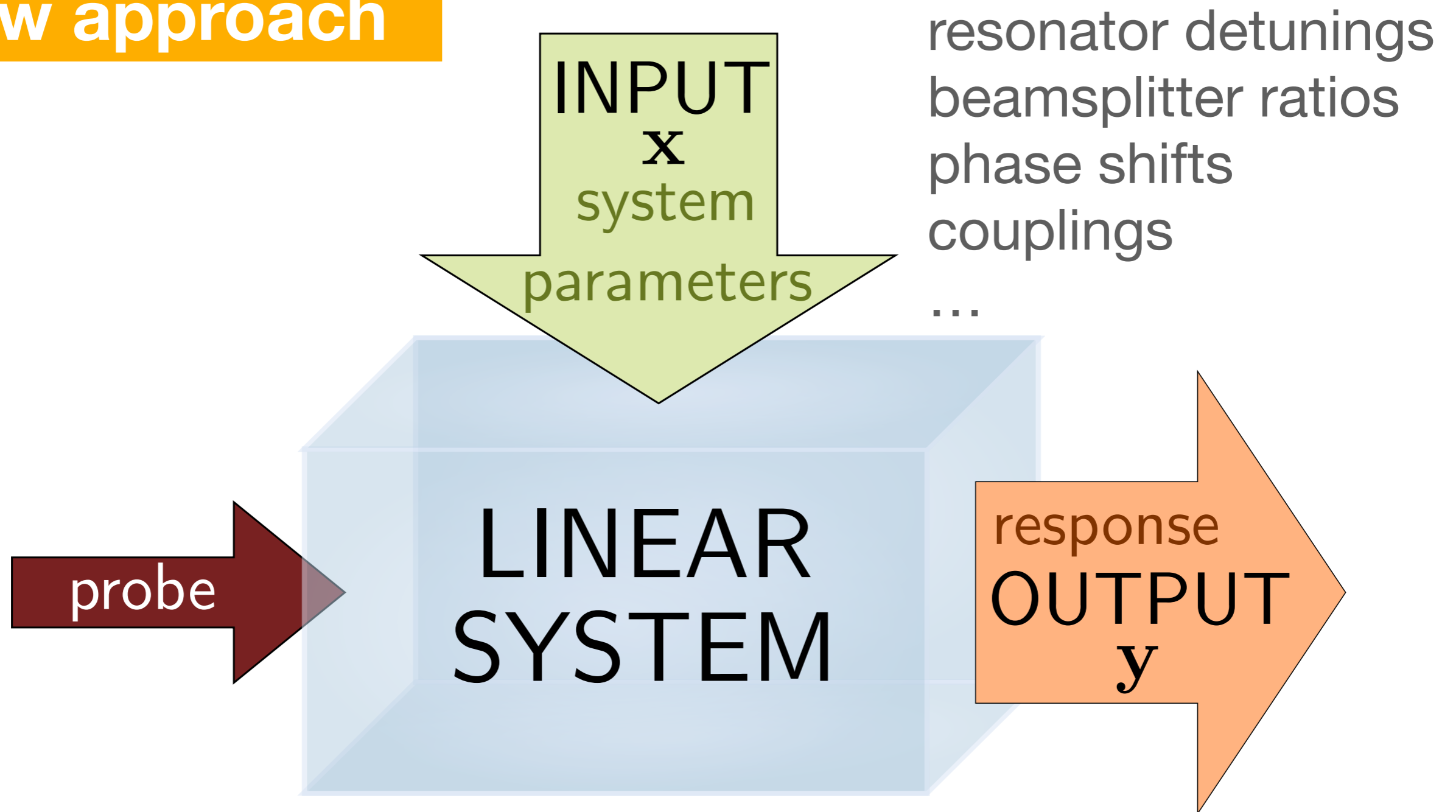




$$y = S(\omega)a_{\text{probe}}$$

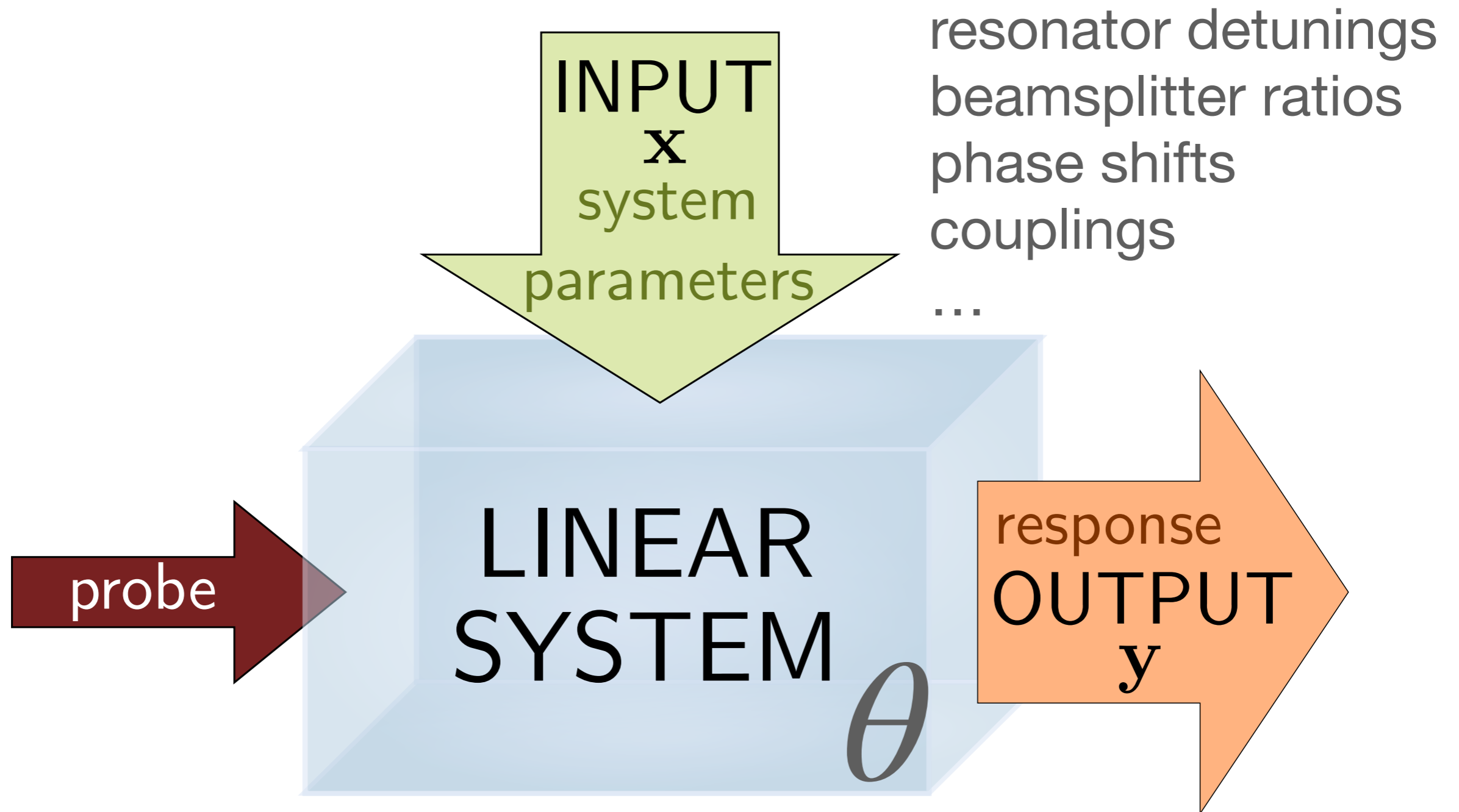
**Scattering Matrix**

# new approach



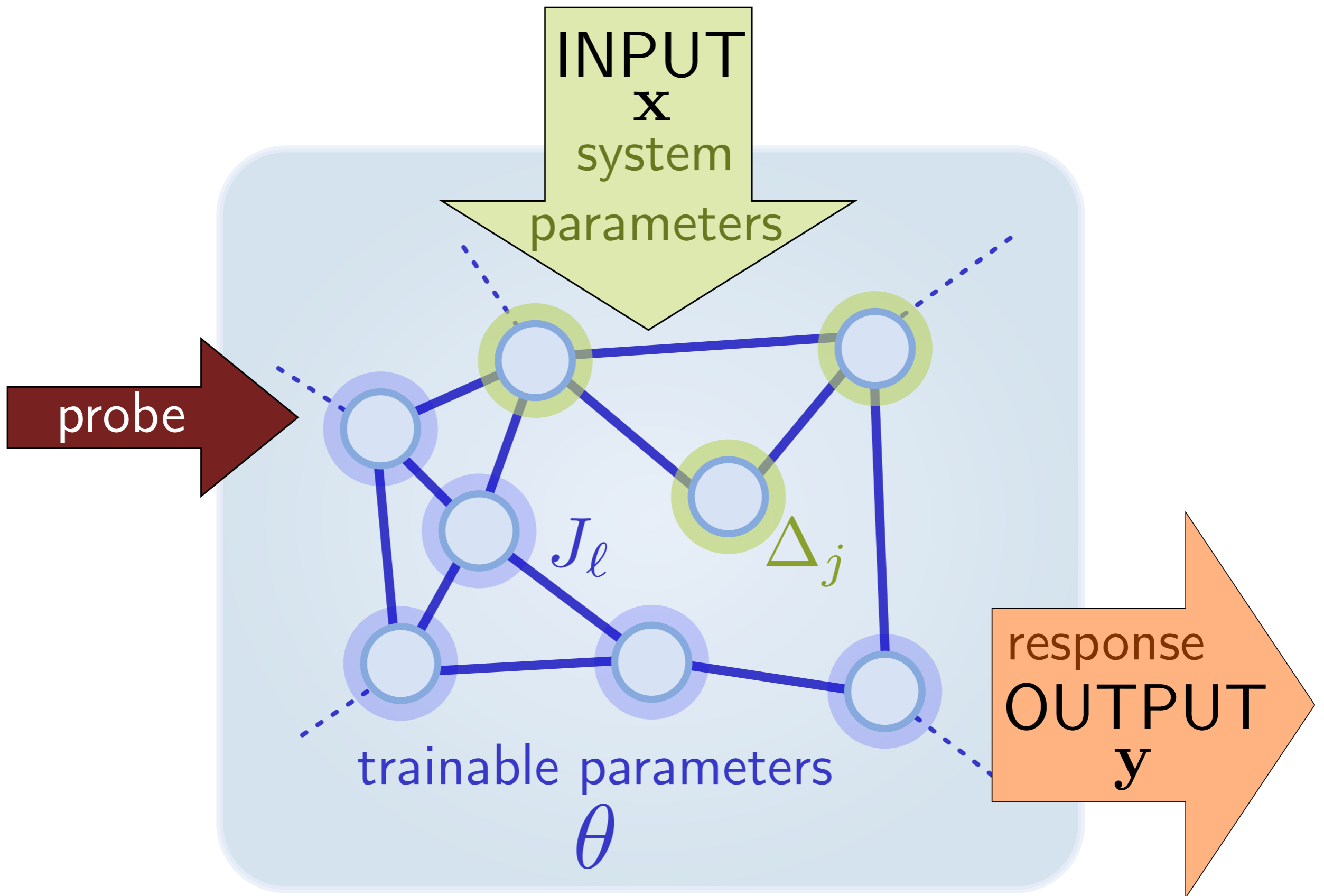
$$y = S(x, \omega) a_{\text{probe}}$$

**nonlinear** function of **input  $x$**



$$y = S(x, \theta, \omega) a_{\text{probe}}$$

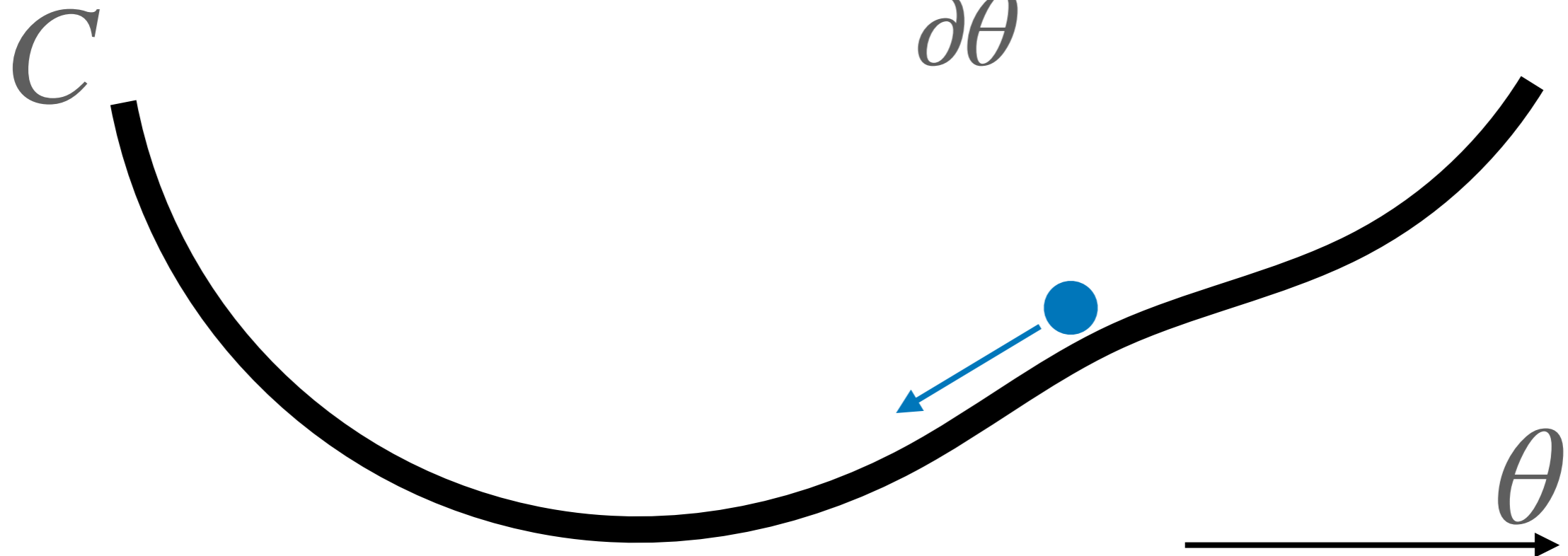
**nonlinear trainable function of input  $x$**



# Training

## Gradient descent on cost function

$$\delta\theta = -\frac{\partial C}{\partial\theta}$$



# Training

## Gradient descent on cost function

$$\delta\theta = -\frac{\partial C}{\partial\theta}$$

**Challenge: obtain gradients efficiently for a physical system!**

Backpropagation on a model (but: model?)

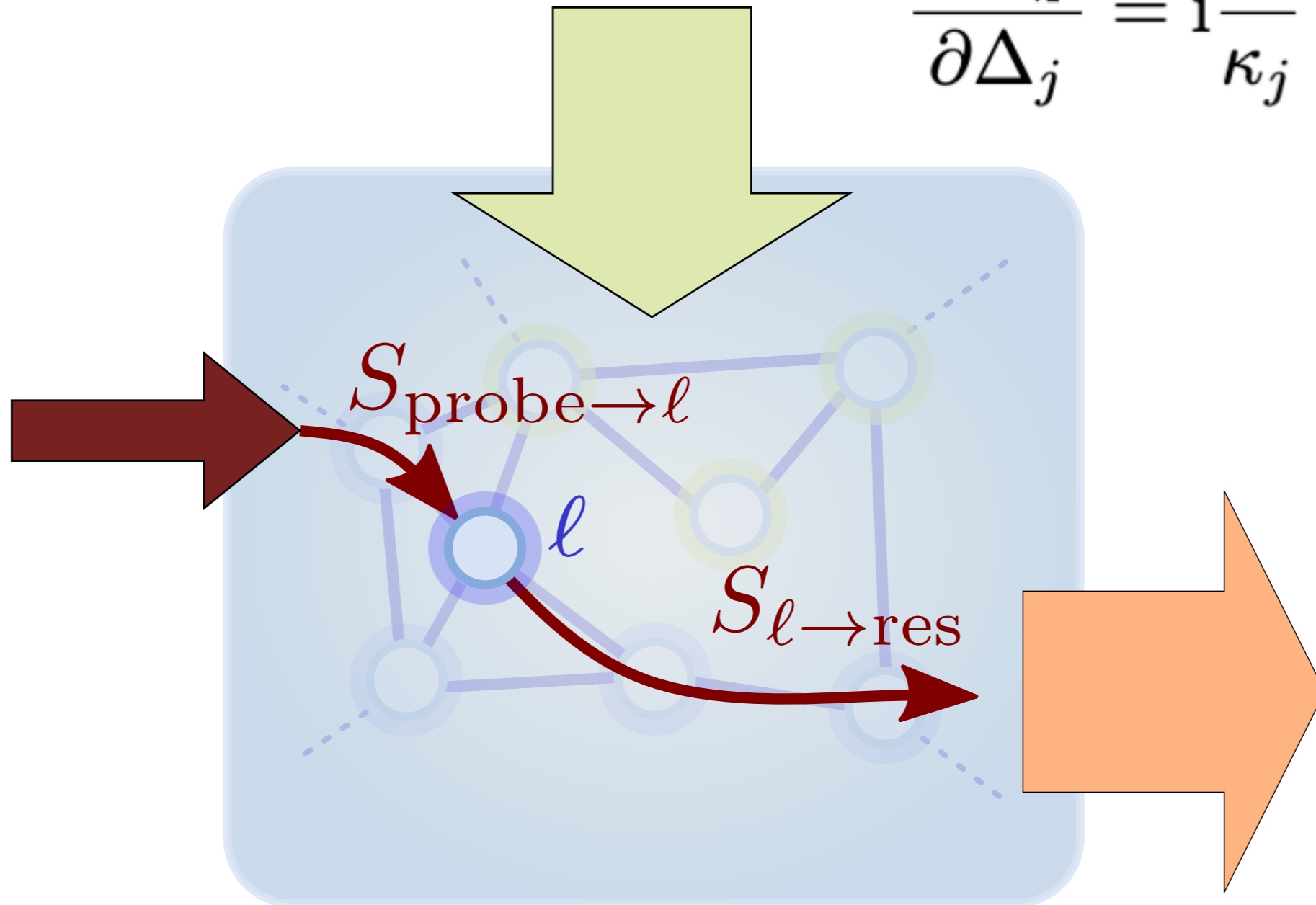
Hamiltonian Echo Backpropagation (time-reversal)

Equilibrium propagation (relaxation system)

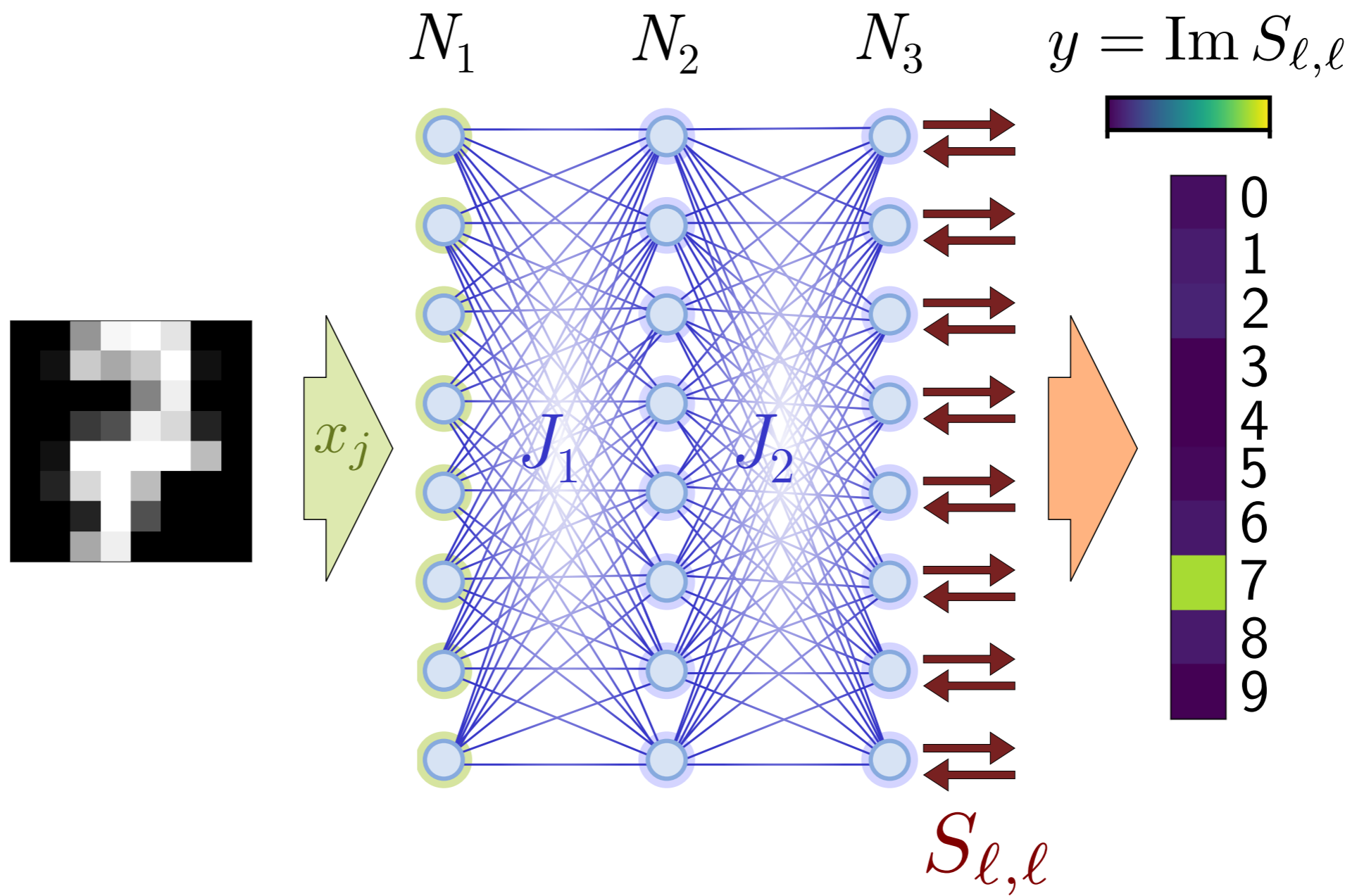
# Training

Here: Gradients from simple scattering matrix measurements!

$$\frac{\partial S_{r,p}}{\partial \Delta_j} = i \frac{1}{\kappa_j} G_{j,p} G_{r,j}$$



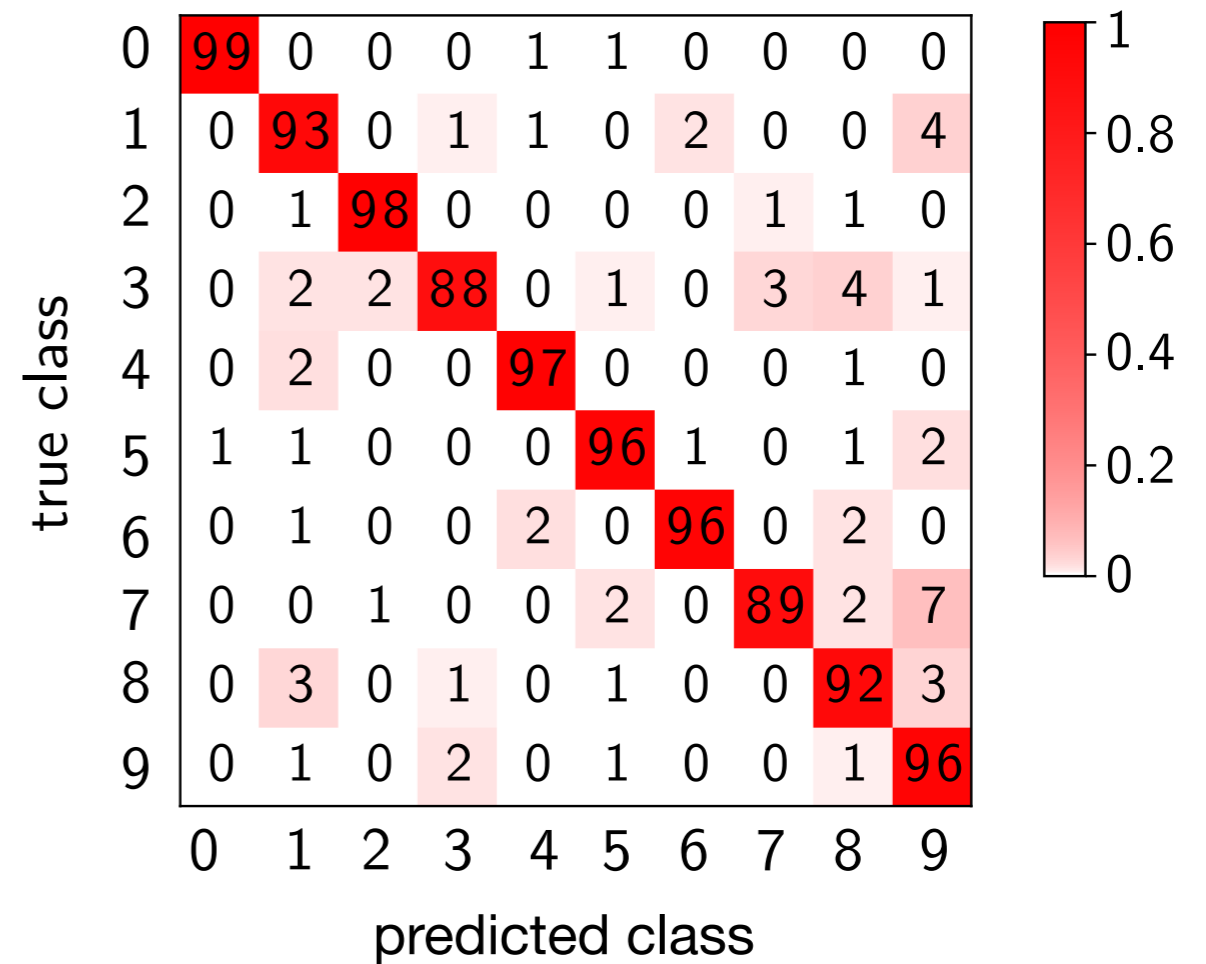
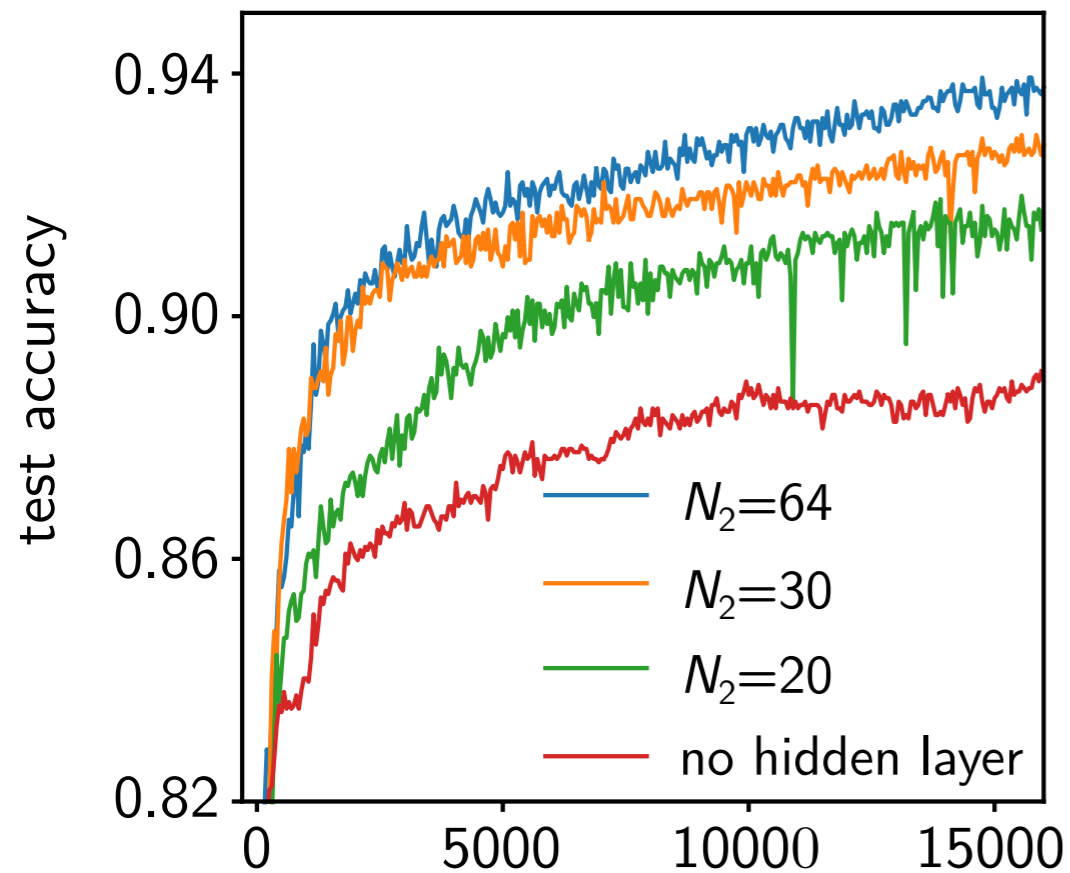
# Simple tight-binding model





# Simple tight-binding model

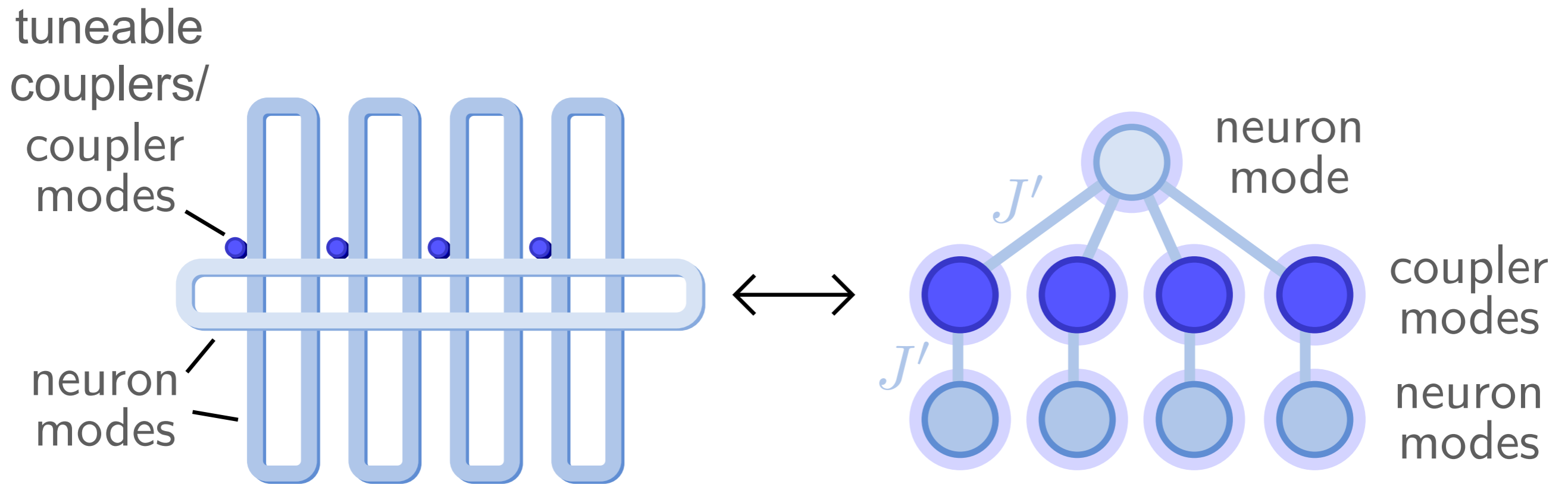
Training on handwritten digits



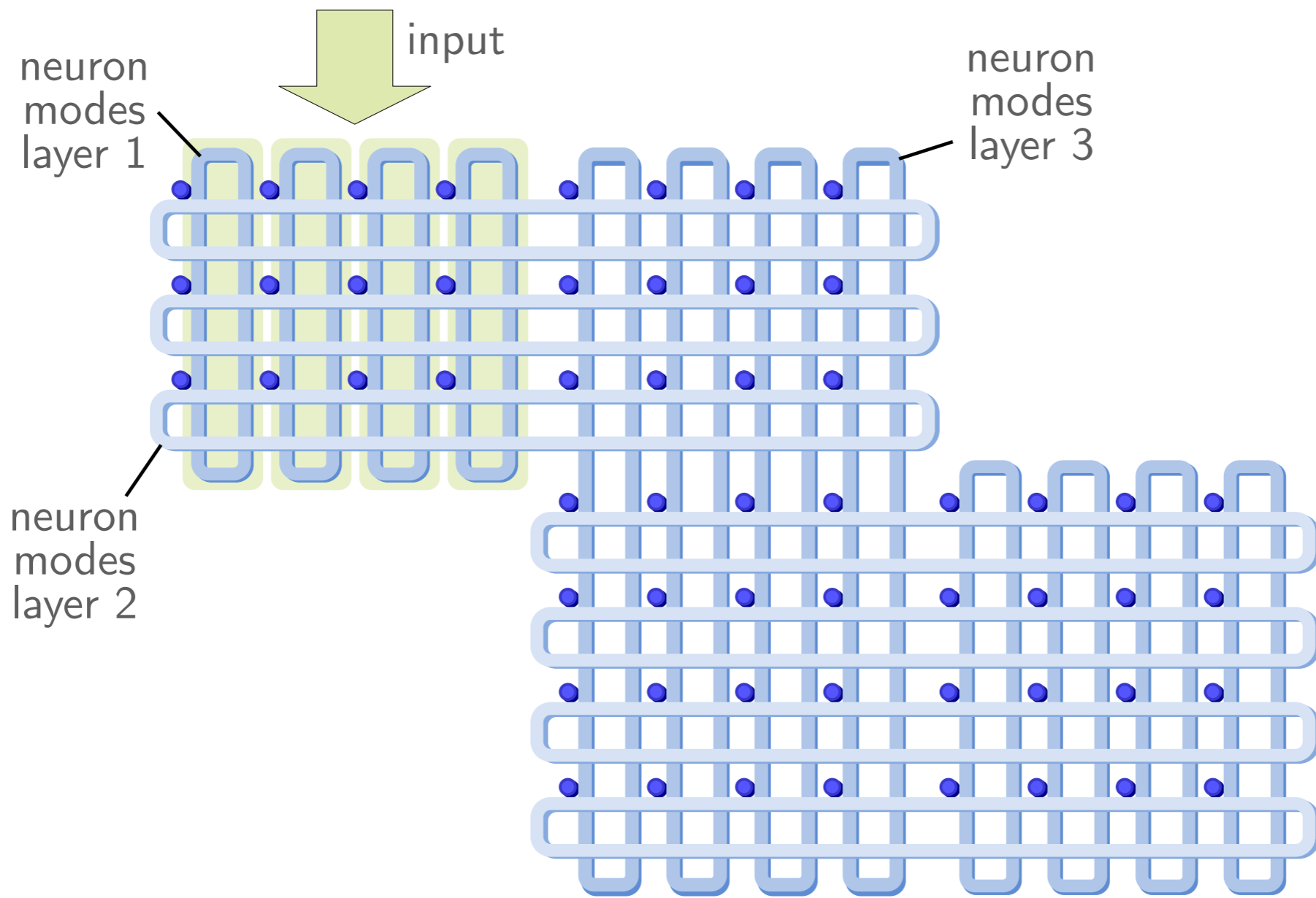
Better accuracy than purely linear neural network

# Possible optical implementation

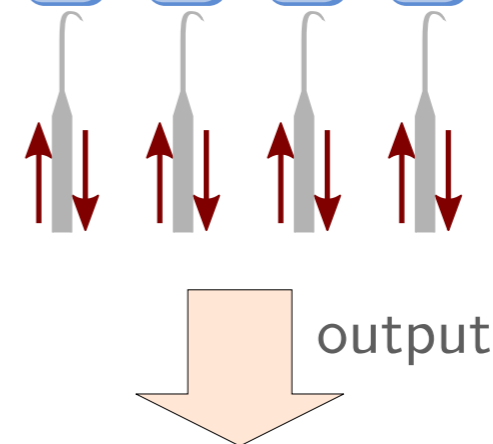
## racetrack resonators



# Possible optical implementation



**read off gradients needed  
for training:  
grating tap monitors**



# Fully nonlinear neuromorphic learning machine based on linear wave scattering

...should work in many platforms  
simple training, simple inference

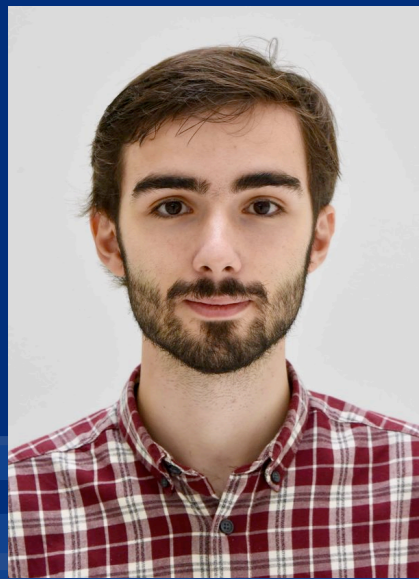
C. Wanjura, F. Marquardt arXiv: 2308.16181

similar ideas & free-space experiments:

M. Yildirim, N. U. Dinc, I. Oguz, D. Psaltis,  
and C. Moser, arXiv:2307.08533

F. Xia, K. Kim, Y. Eliezer, L. Shaughnessy, S. Gigan,  
and H. Cao, arXiv:2307.08558

# Physical self-learning machines as new tools for machine learning



## **Hamiltonian Echo Backpropagation**

General physical training procedure

Victor Lopez-Pastor & F.M.

Phys. Rev. X 13, 031020

## **Nonlinear neuromorphic system via linear waves**

Suitable for any linear platform

Clara Wanjura & F.M. arXiv 2308.16181

