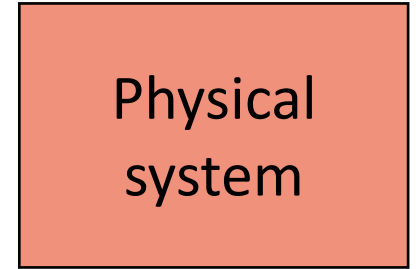
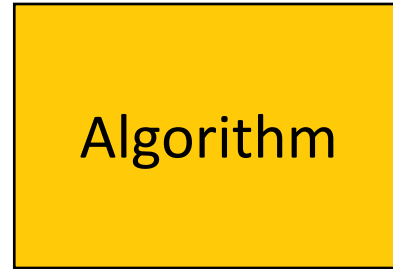
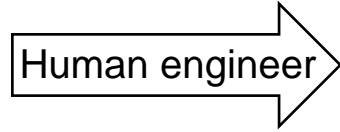
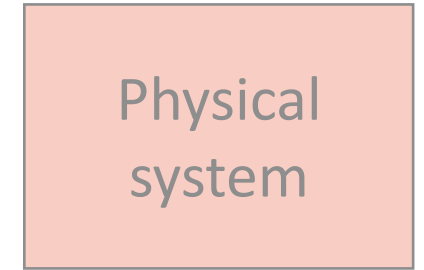
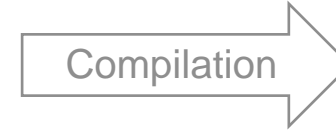
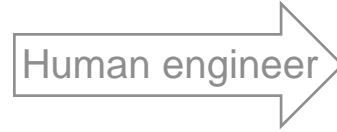




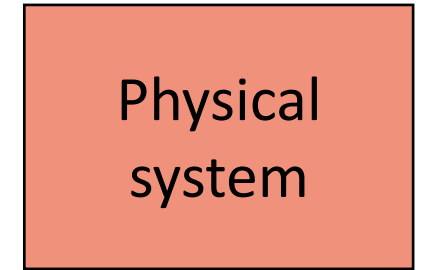
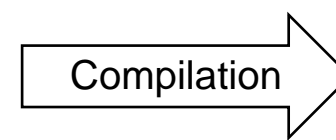
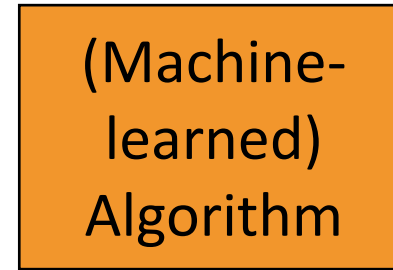
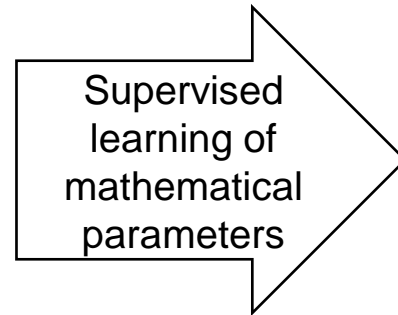
Traditional  
computer  
science

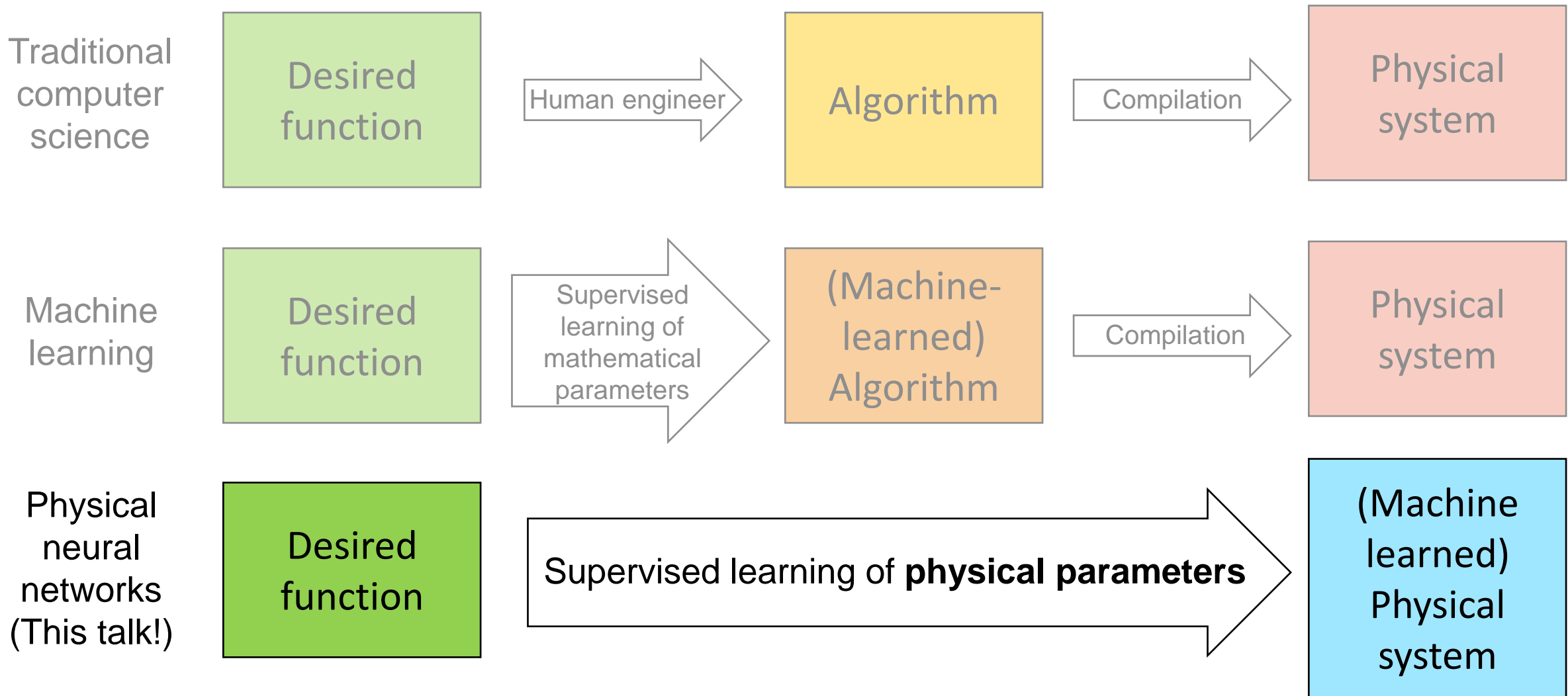


Traditional  
computer  
science

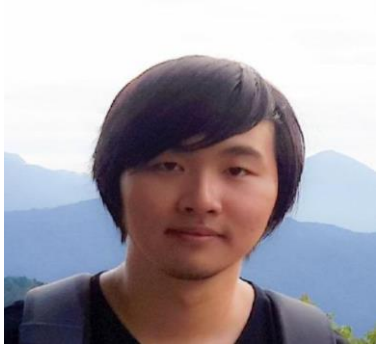


Machine  
learning





# Acknowledgments



**Tatsuhiro Onodera**  
(co-lead)



Martin Stein



Tianyu Wang



Darren Schachter



Zoey Hu



**Peter McMahon**  
(PI)



Maxwell  
Anderson



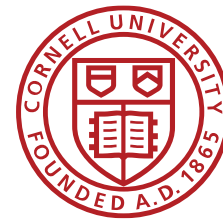
Mandar Sohoni



Shiyuan Ma

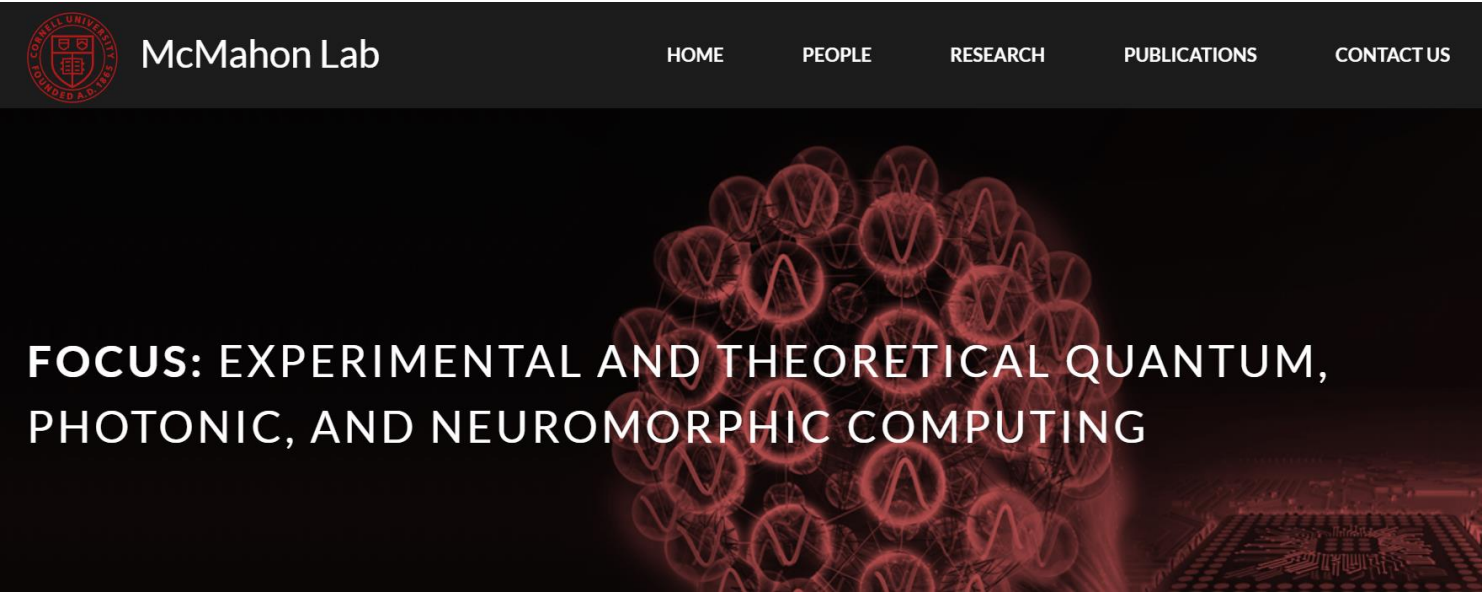


Jeremie  
Laydevant

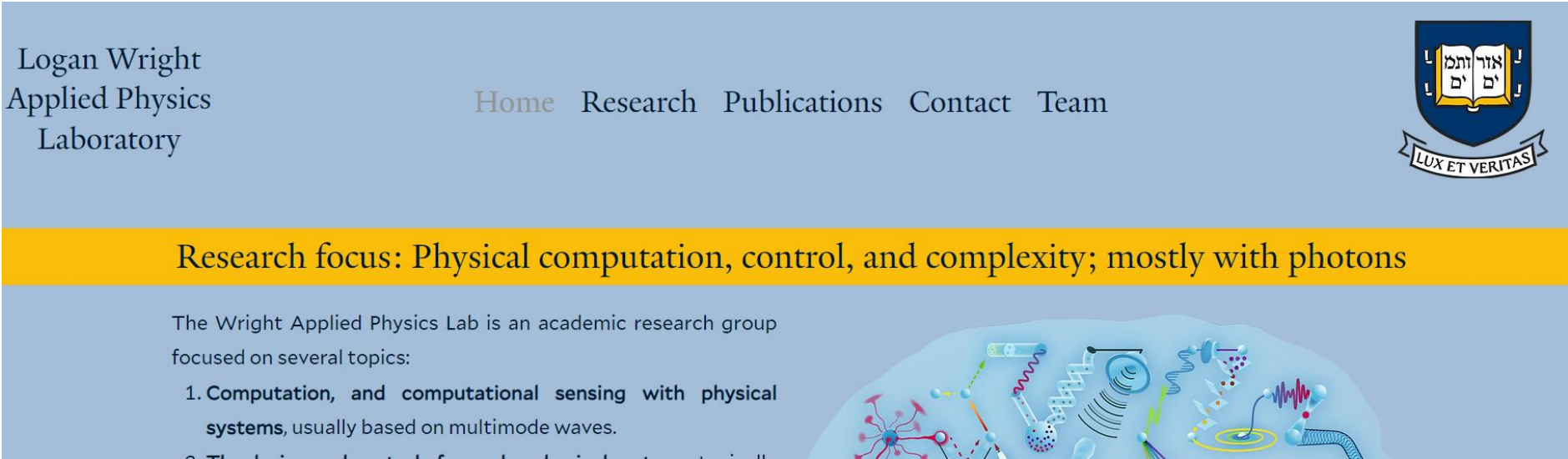
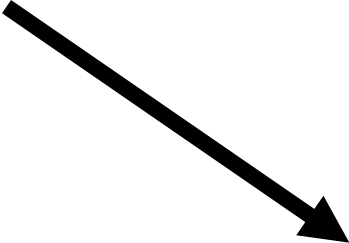
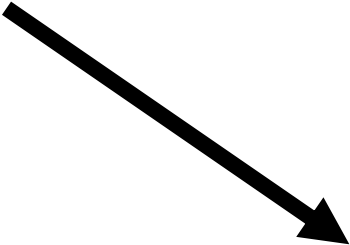




# New lab at Cornell → New lab at Yale

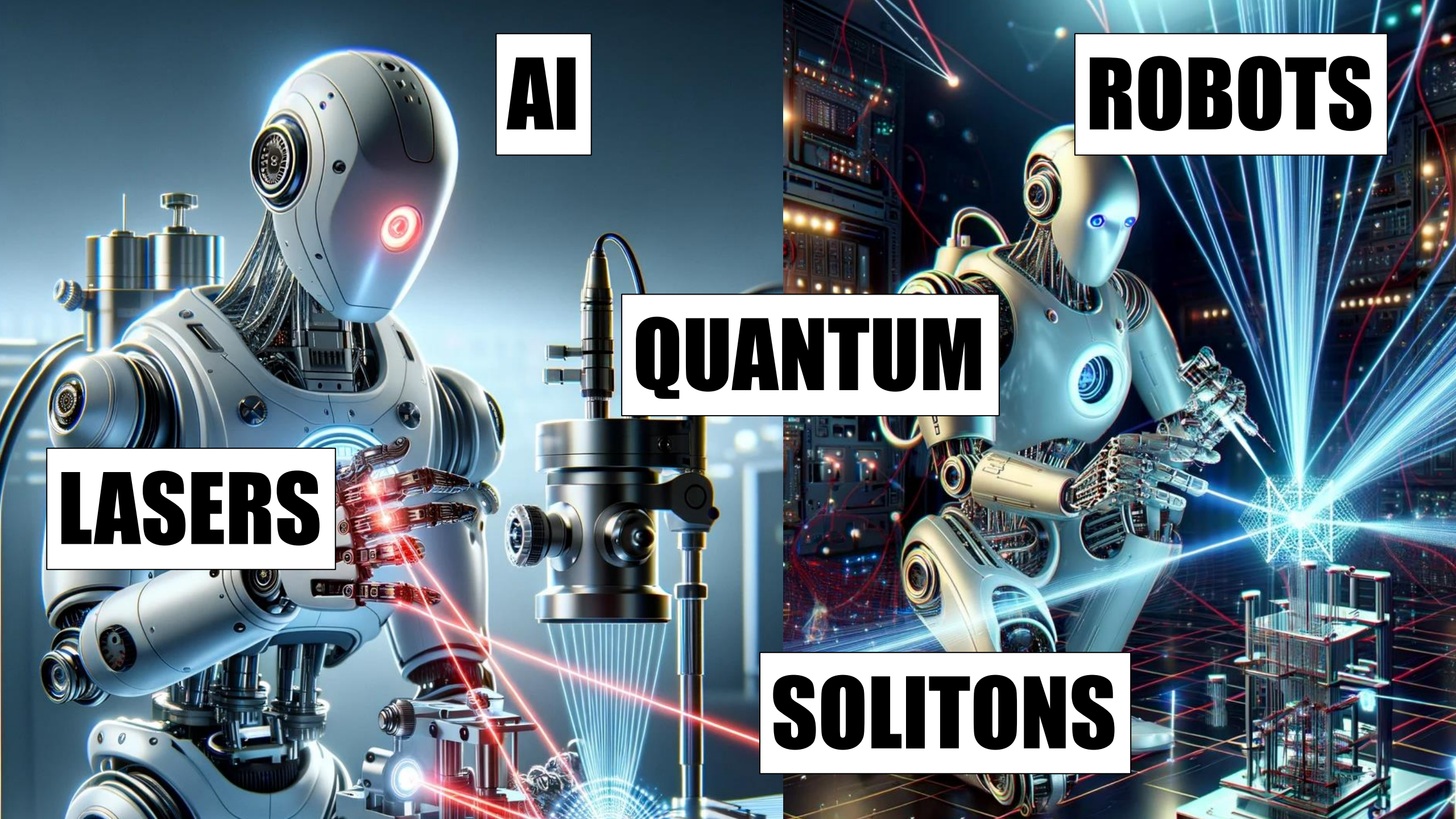


The screenshot shows the top portion of the McMahon Lab website. On the left is the Cornell University logo. To its right is the text "McMahon Lab". Further right is a navigation menu with the items: HOME, PEOPLE, RESEARCH, PUBLICATIONS, and CONTACT US. Below the navigation is a large banner with a dark background and a red, glowing, abstract pattern of interconnected nodes and lines. Overlaid on this banner is the text: "FOCUS: EXPERIMENTAL AND THEORETICAL QUANTUM, PHOTONIC, AND NEUROMORPHIC COMPUTING".



The screenshot shows the top portion of the Logan Wright Applied Physics Laboratory website. On the left is the text: "Logan Wright Applied Physics Laboratory". To the right is a navigation menu with the items: Home, Research, Publications, Contact, and Team. On the far right is the Yale University logo, which includes a shield with Hebrew text and a banner below it that reads "LUX ET VERITAS". Below the navigation is a yellow banner with the text: "Research focus: Physical computation, control, and complexity; mostly with photons". Below this is a paragraph: "The Wright Applied Physics Lab is an academic research group focused on several topics:" followed by a list item: "1. Computation, and computational sensing with physical systems, usually based on multimode waves." At the bottom right is a colorful illustration of various scientific concepts like atoms, waves, and circuits.





**AI**

**ROBOTS**

**QUANTUM**

**LASERS**

**SOLITONS**



(Hiring!)

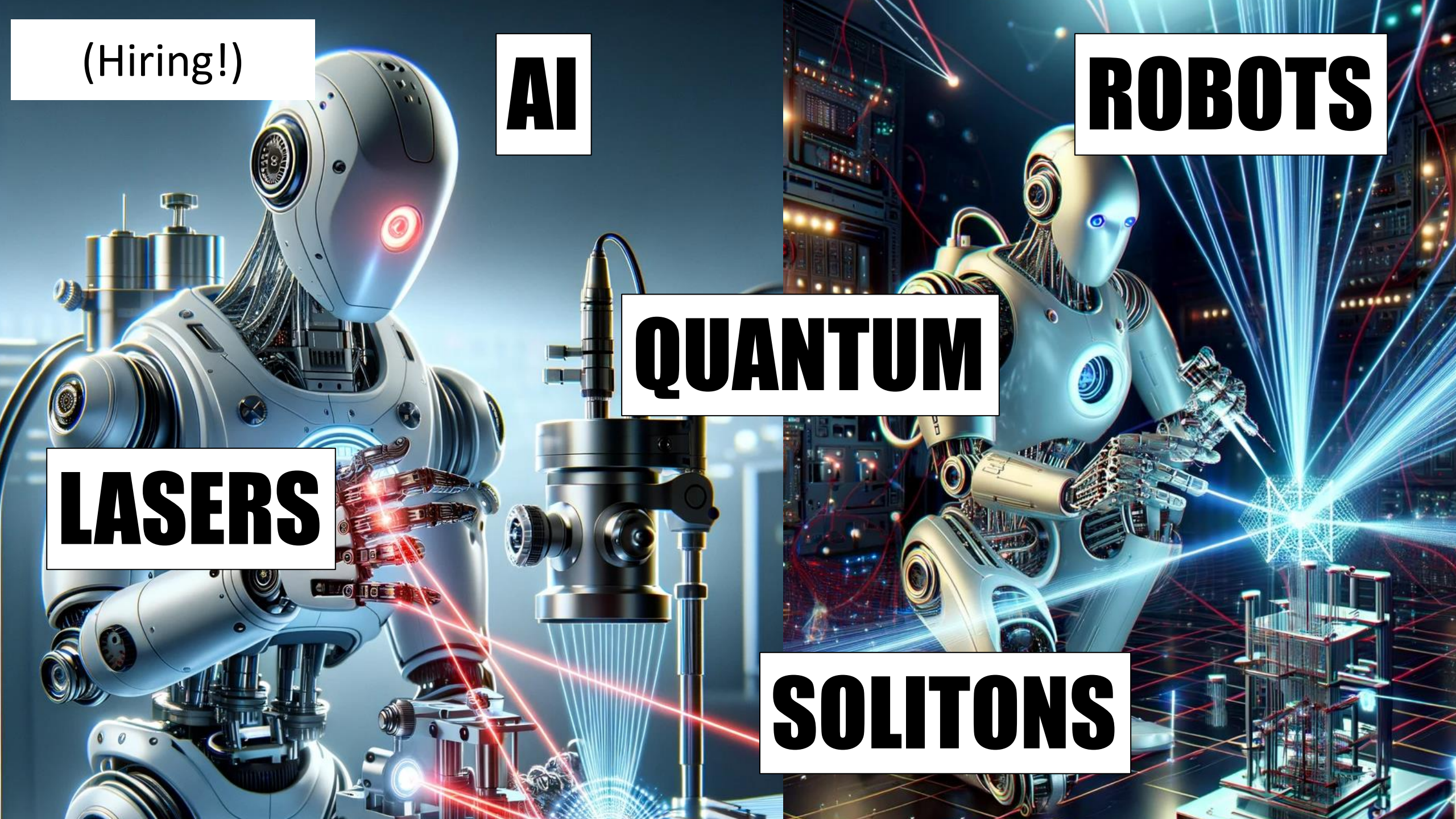
**AI**

**ROBOTS**

**LASERS**

**QUANTUM**

**SOLITONS**





(Mathematical) neural networks

# Deep learning: “just” high-dimensional curve-fitting\*



$\vec{x}$   
Input

$\vec{\theta}_1$     $\vec{\theta}_2$     $\vec{\theta}_3$

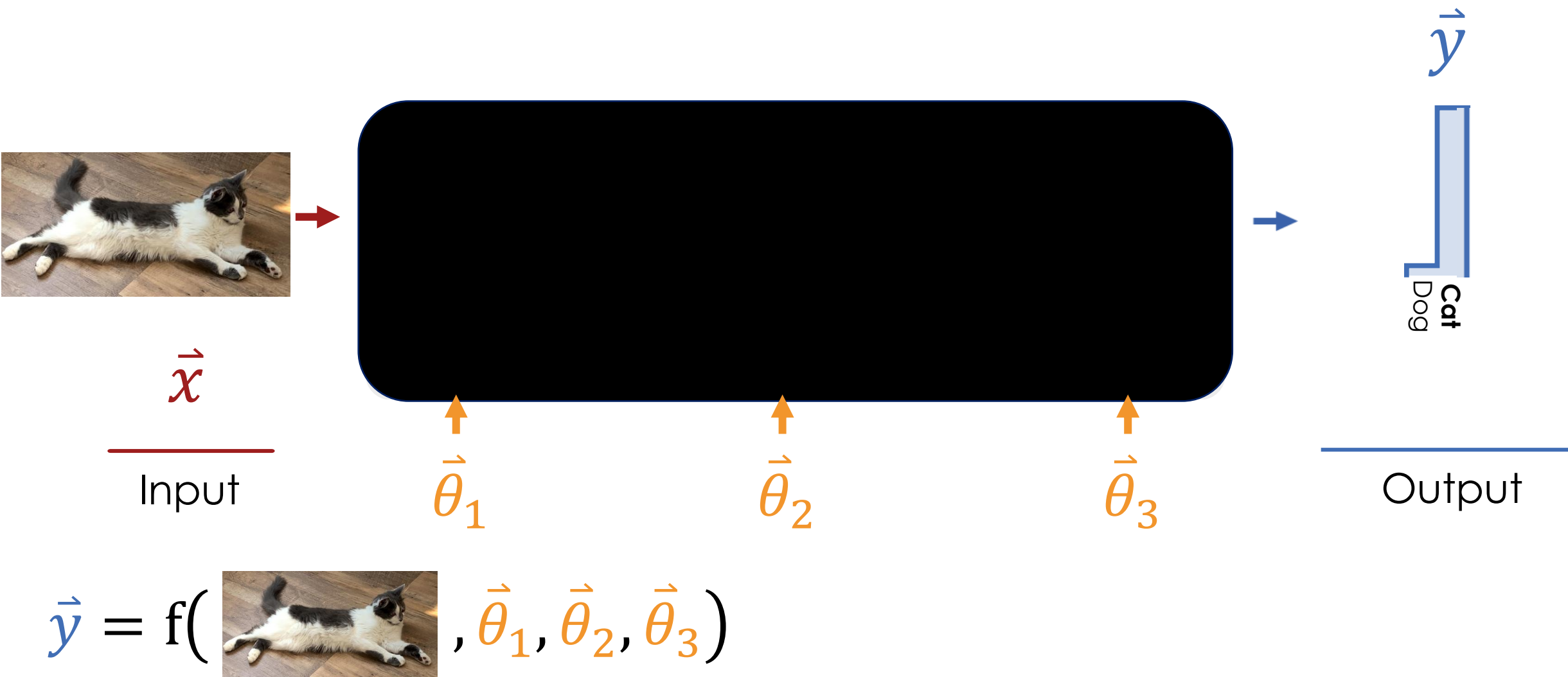
Output

$$\vec{y} = f(\text{dog image}, \vec{\theta}_1, \vec{\theta}_2, \vec{\theta}_3)$$

\*This intro blatantly copied from S. Dillavou

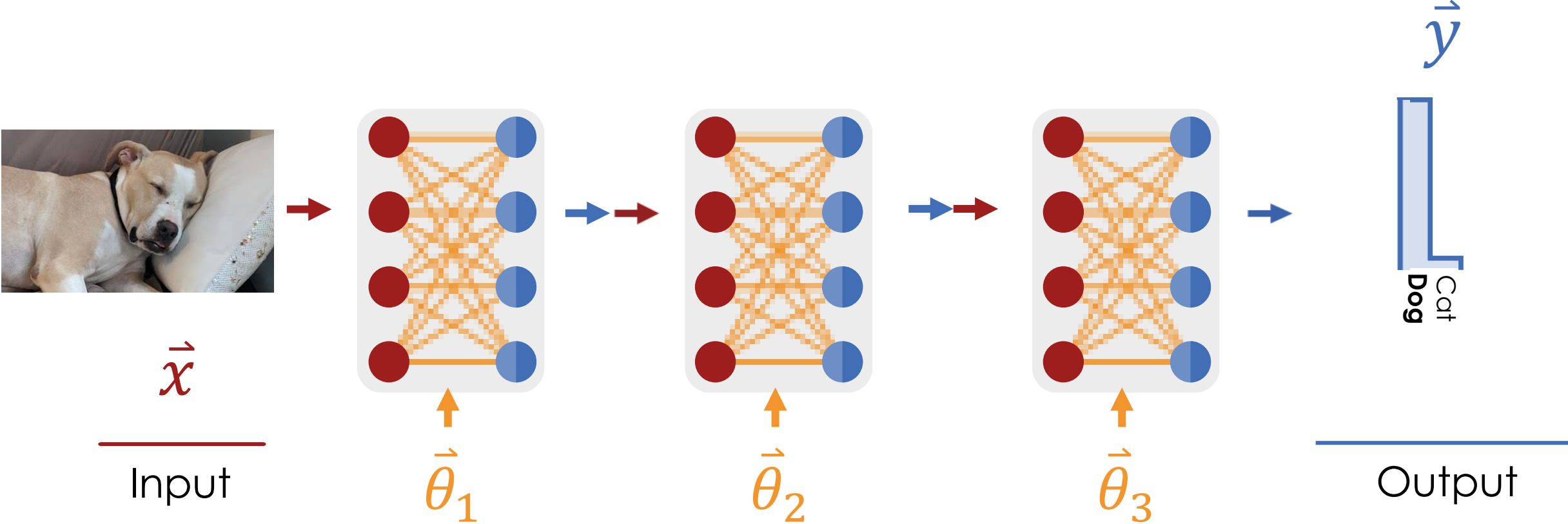


# Deep learning: “just” high-dimensional curve-fitting\*



\*This intro blatantly copied from S. Dillavou

# Deep learning: the 'deep' means multi-layer neural networks

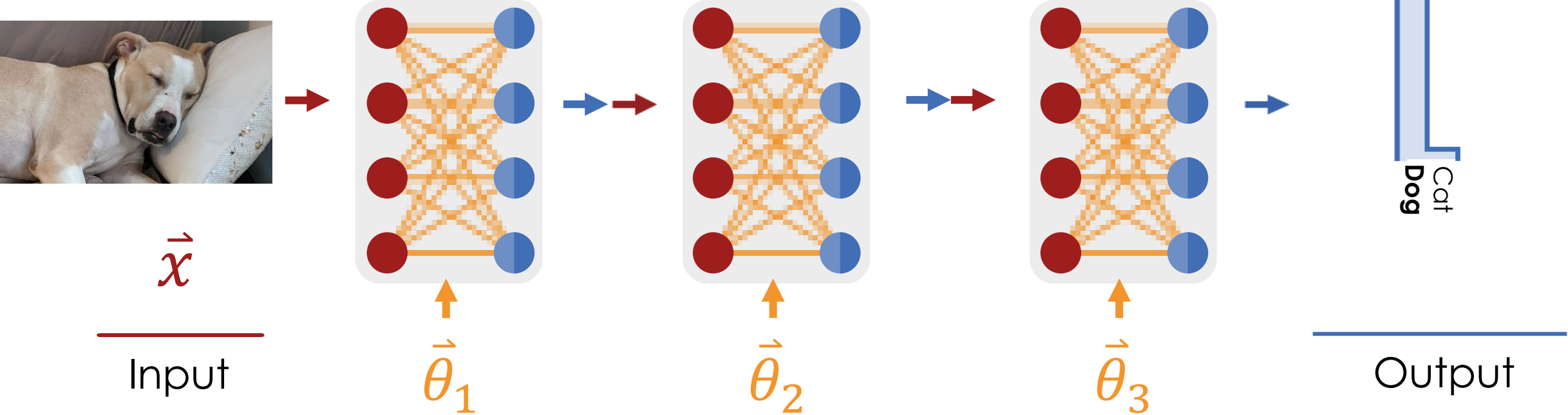


$$\vec{y} = f(\text{Image of Dog}, \vec{\theta}_1, \vec{\theta}_2, \vec{\theta}_3)$$



# Deep learning: the 'deep' means multi-layer neural networks

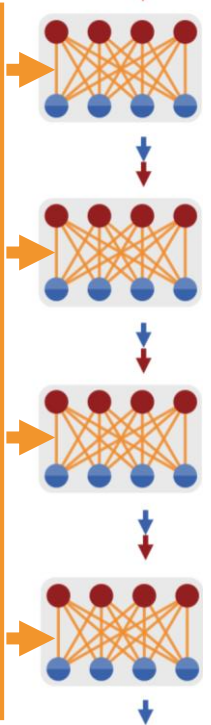
Deep neural networks learn **hierarchical** computations



$$\vec{y} = f(\text{Image of Dog}, \vec{\theta}_1, \vec{\theta}_2, \vec{\theta}_3) = f(f(f(\text{Image of Dog}, \vec{\theta}_1), \vec{\theta}_2), \vec{\theta}_3)$$

# Deep neural networks: training versus inference

Untrained



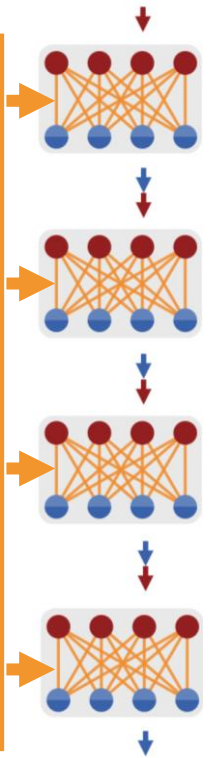
Untrained  
Parameters

Nonsense



# Deep neural networks: training versus inference

Untrained

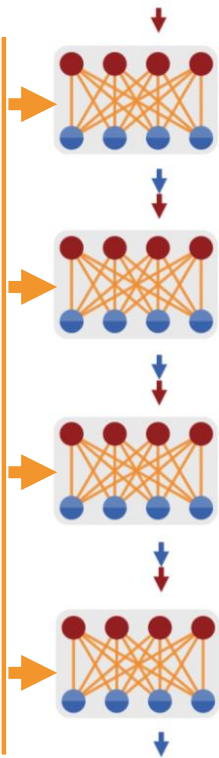


Nonsense

Untrained  
Parameters

Training

Training input data



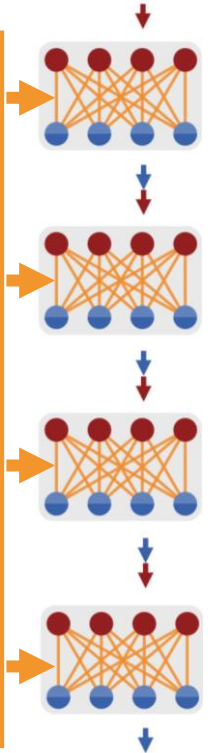
"Cat"

Parameters  
are **changed**

$$\vec{\theta} \rightarrow \vec{\theta} + d\vec{\theta}$$

# Deep neural networks: training versus inference

Untrained



Untrained Parameters

Nonsense

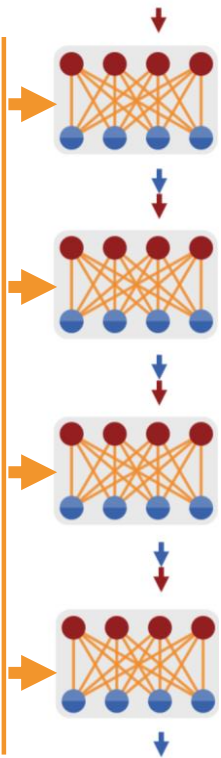
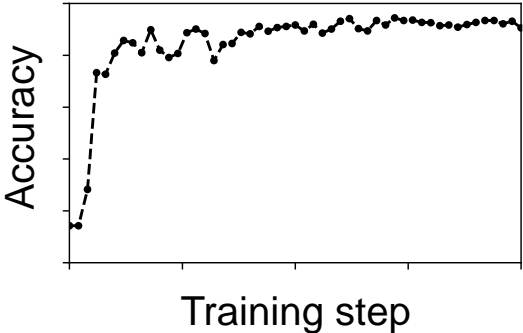
Training

Training input data



Parameters are **changed**

$$\vec{\theta} \rightarrow \vec{\theta} + d\vec{\theta}$$

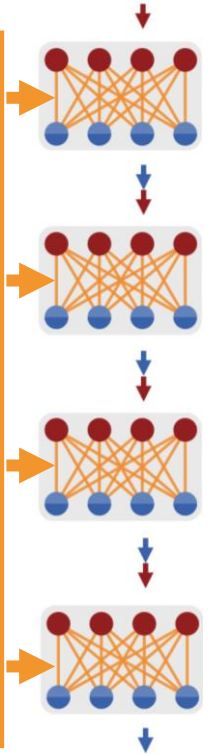


"Cat"



# Deep neural networks: training versus inference

## Untrained



Nonsense

Untrained Parameters

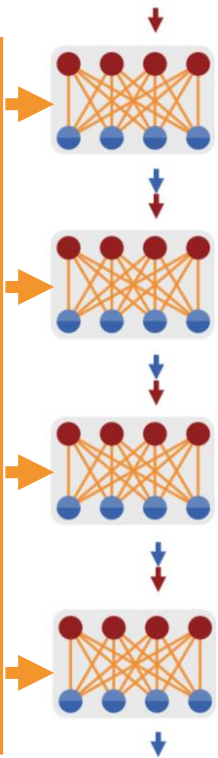
## Training

Training input data



Parameters are **changed**

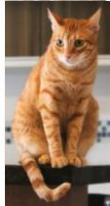
$$\vec{\theta} \rightarrow \vec{\theta} + d\vec{\theta}$$



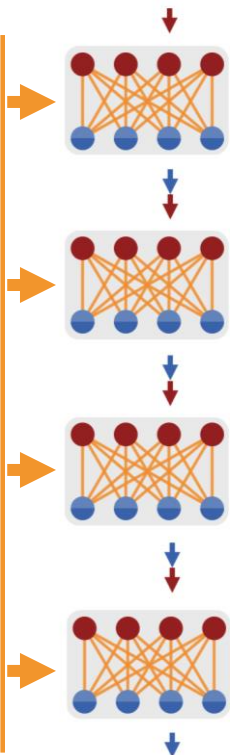
"Cat"

## Inference

Unseen new input data



Parameters are **fixed**

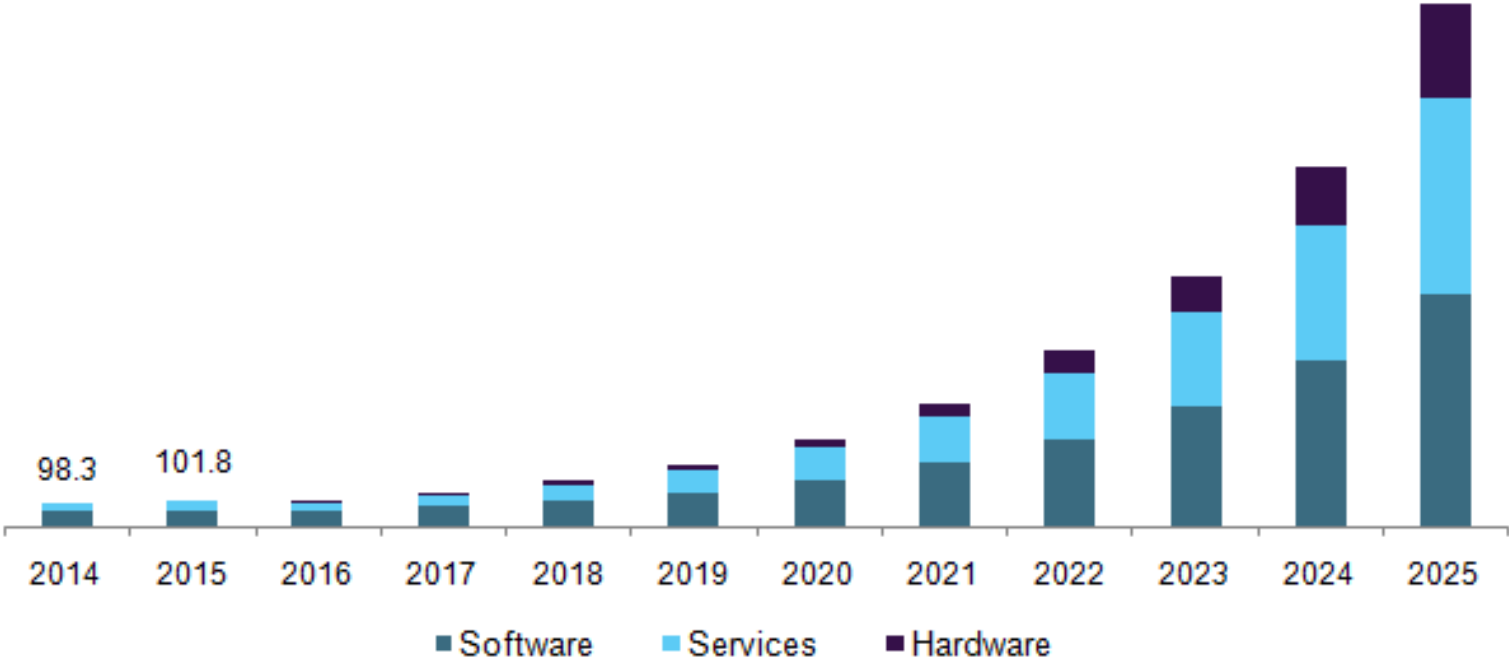


"Cat"

# Deep learning is growing rapidly

Exponential growth of:

Market size

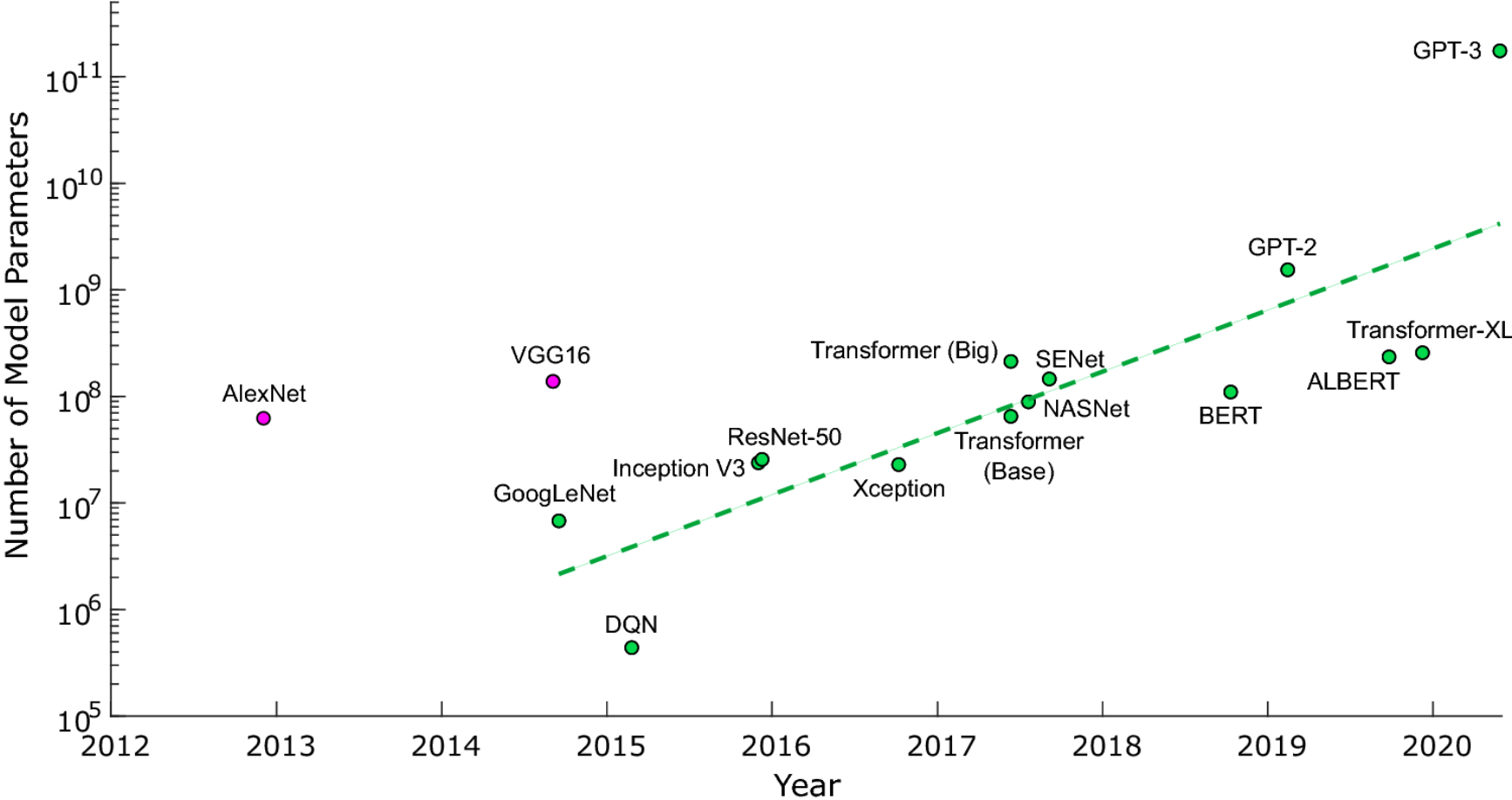


# Deep learning is growing rapidly

Exponential growth of:

Market size

Parameters



Bernstein, L., et al. "Freely scalable and reconfigurable optical hardware for deep learning." *Scientific Reports* (2021)



# Deep learning is growing rapidly

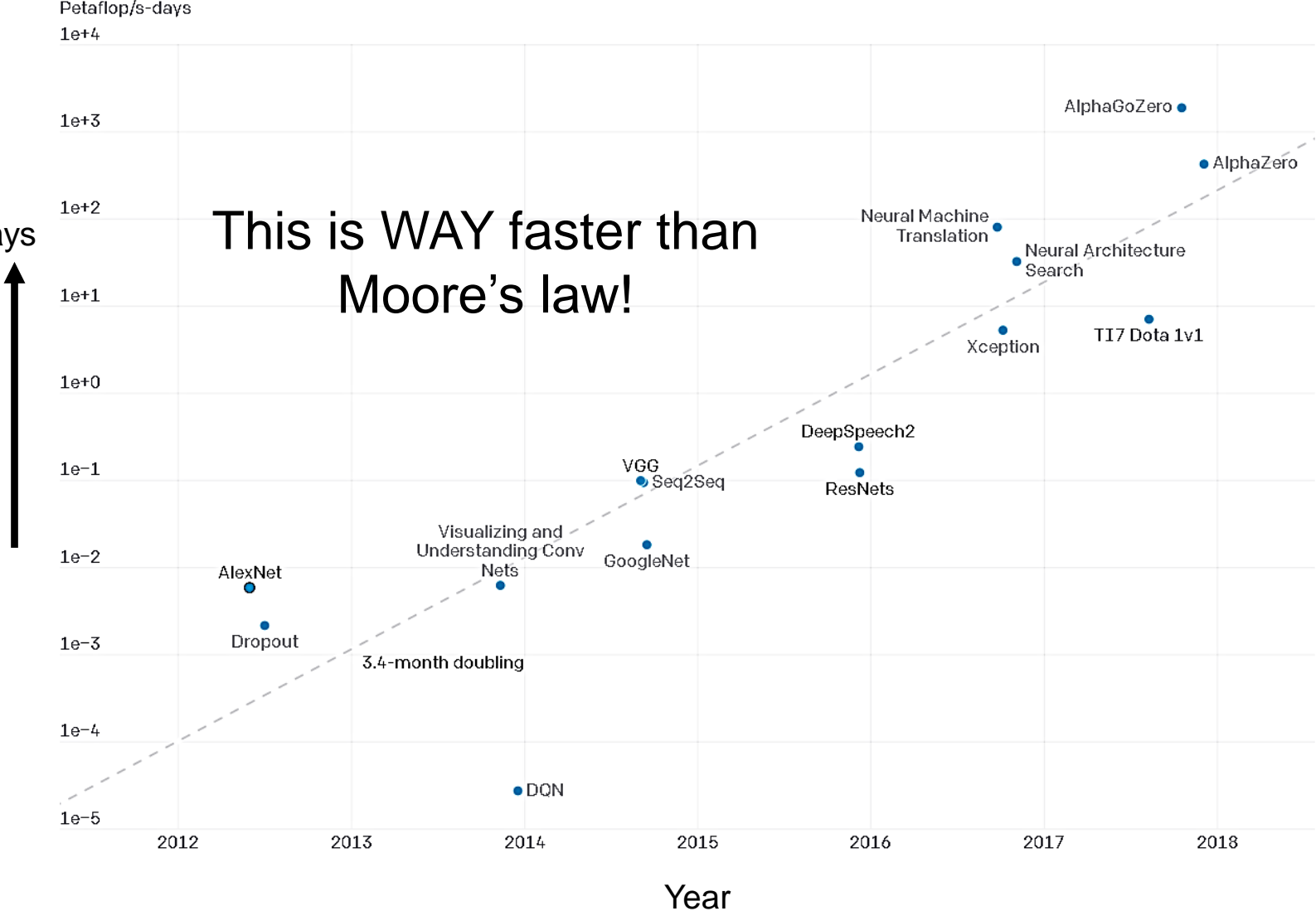
Exponential growth of:

Market size

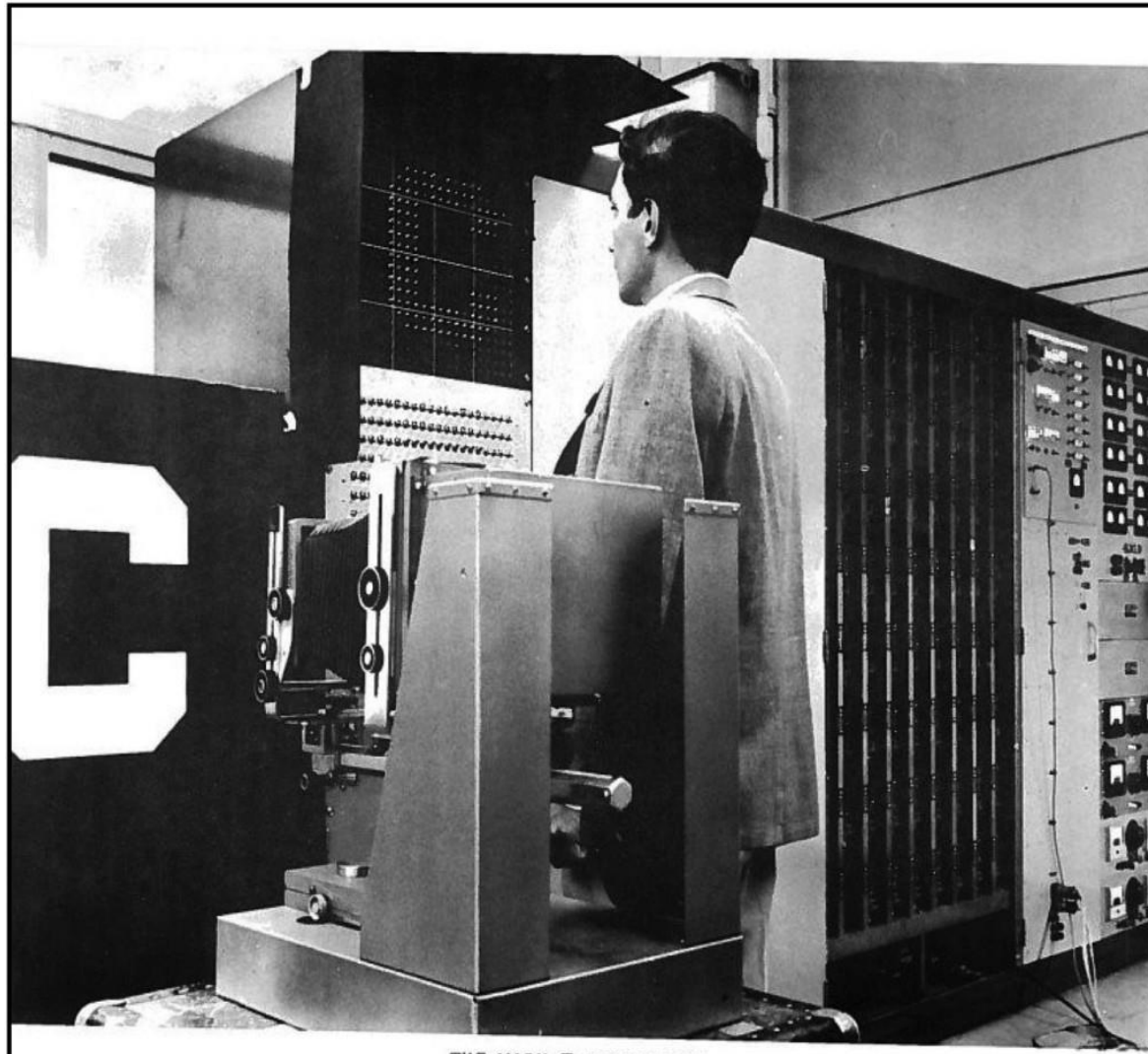
Parameters

Compute

Petaflop/s-days



# Good news: Neural networks are ideal for analog hardware



THE MARK I PERCEPTRON

## NEW NAVY DEVICE LEARNS BY DOING

Psychologist Shows Embryo  
of Computer Designed to  
Read and Grow Wiser

WASHINGTON, July 7 (UPI)—The Navy revealed the embryo of an electronic computer today that it expects will be able to walk, talk, see, write, reproduce itself and be conscious of its existence.

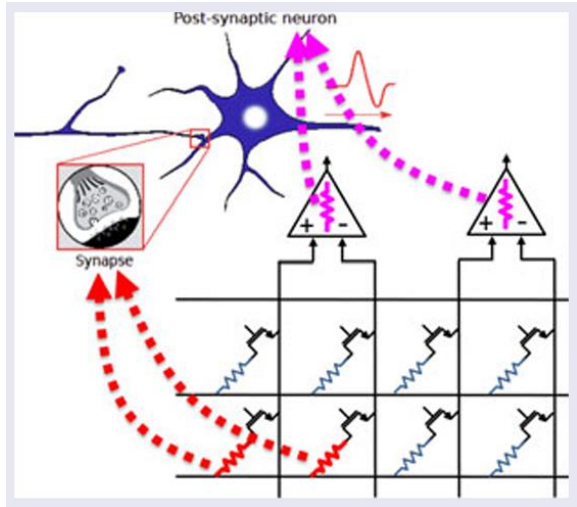
The embryo—the Weather Bureau's \$2,000,000 "704" computer—learned to differentiate between right and left after fifty attempts in the Navy's demonstration for newsmen.

The service said it would use this principle to build the first of its Perceptron thinking machines that will be able to read and write. It is expected to be finished in about a year at a cost of \$100,000.

Dr. Frank Rosenblatt, designer of the Perceptron, conducted the demonstration. He said the machine would be the first device to think as the human brain. As do human beings, Perceptron will make mistakes at first, but will grow wiser as it gains experience, he said.

Dr. Rosenblatt, a research psychologist at the Cornell Aeronautical Laboratory, Buffalo, said Perceptrons might be fired to the planets as mechanical space explorers.

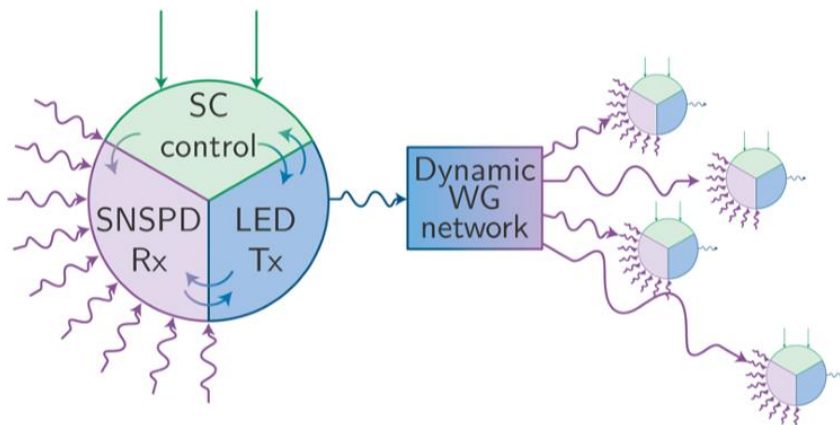
# Neural network hardware uses analog physics to more energy-efficiently perform neural network calculations



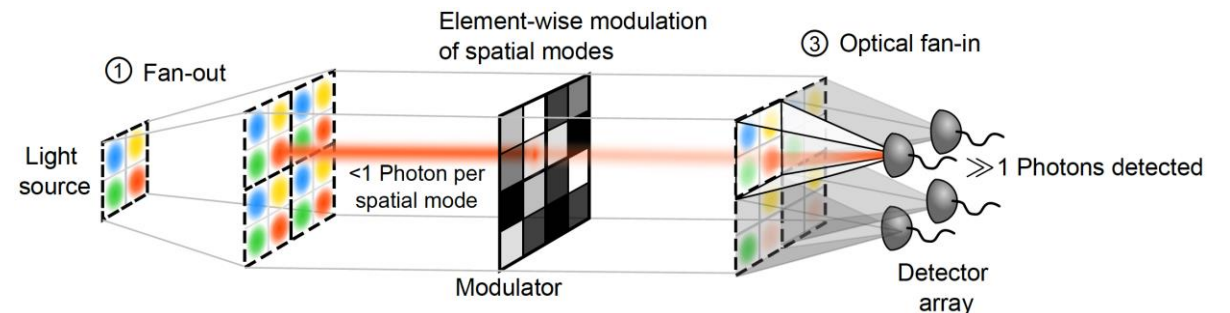
G.W. Burr et al. *Advances in Physics: X* (2017)



Lightmatter Mars chip from Hot Chips 32



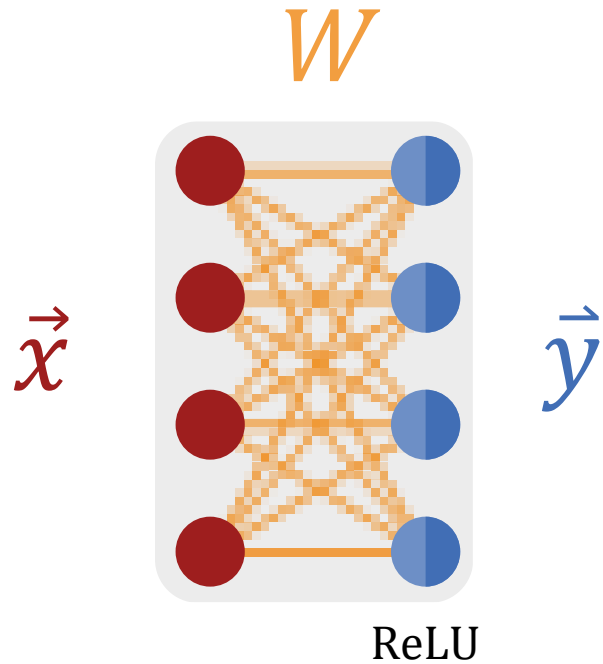
J.M Shainline et al. *Phys. Rev. Applied* (2017)



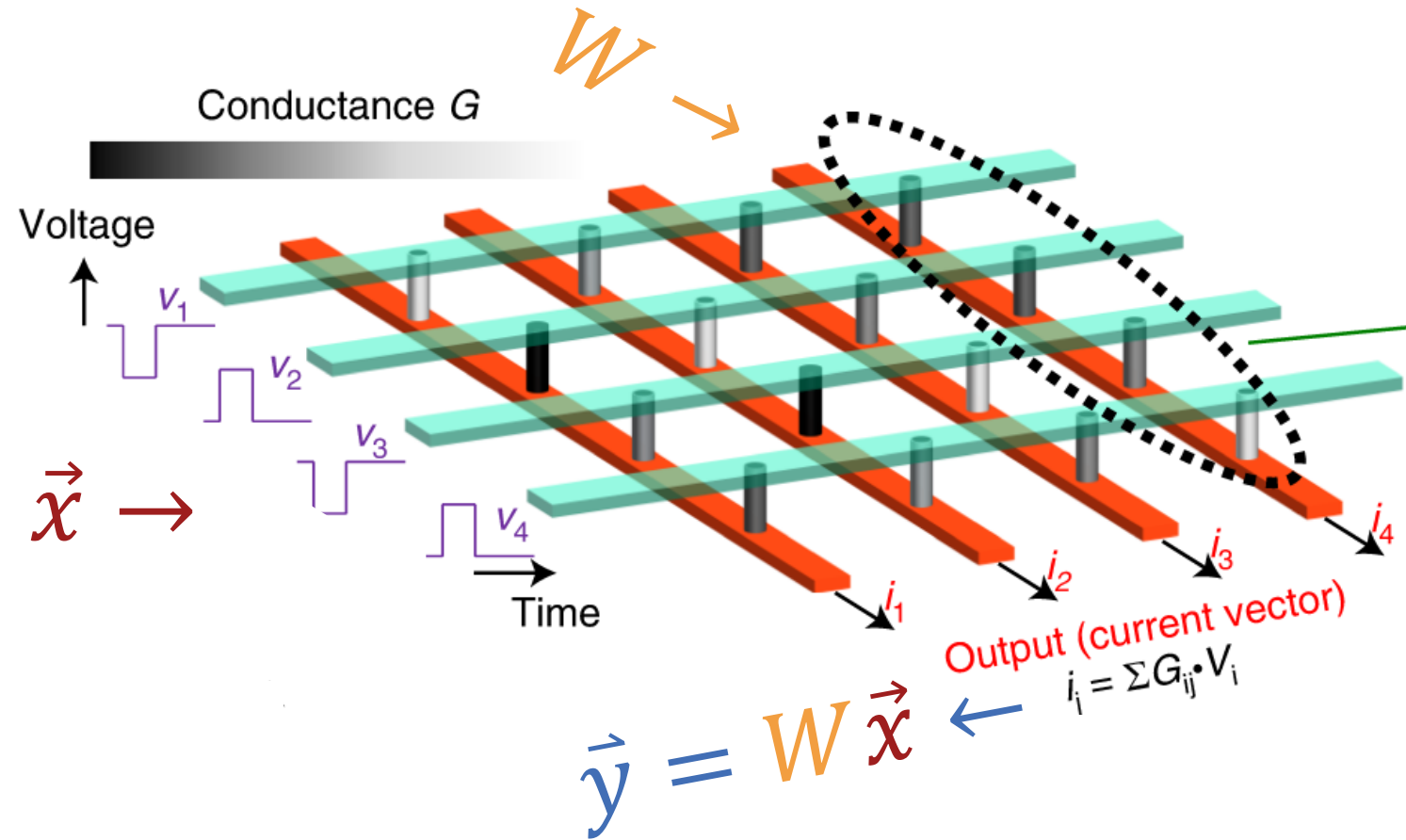
T. Wang, S.-Y. Ma, LGW et al. *Nature Comm* (2022)



# These hardware usually rely on math-physics isomorphism



$\vec{y} = \text{ReLU}(W\vec{x})$   
where  $W\vec{x}$  is a matrix-  
vector product



# But achieving rigorous isomorphism involves trade-offs

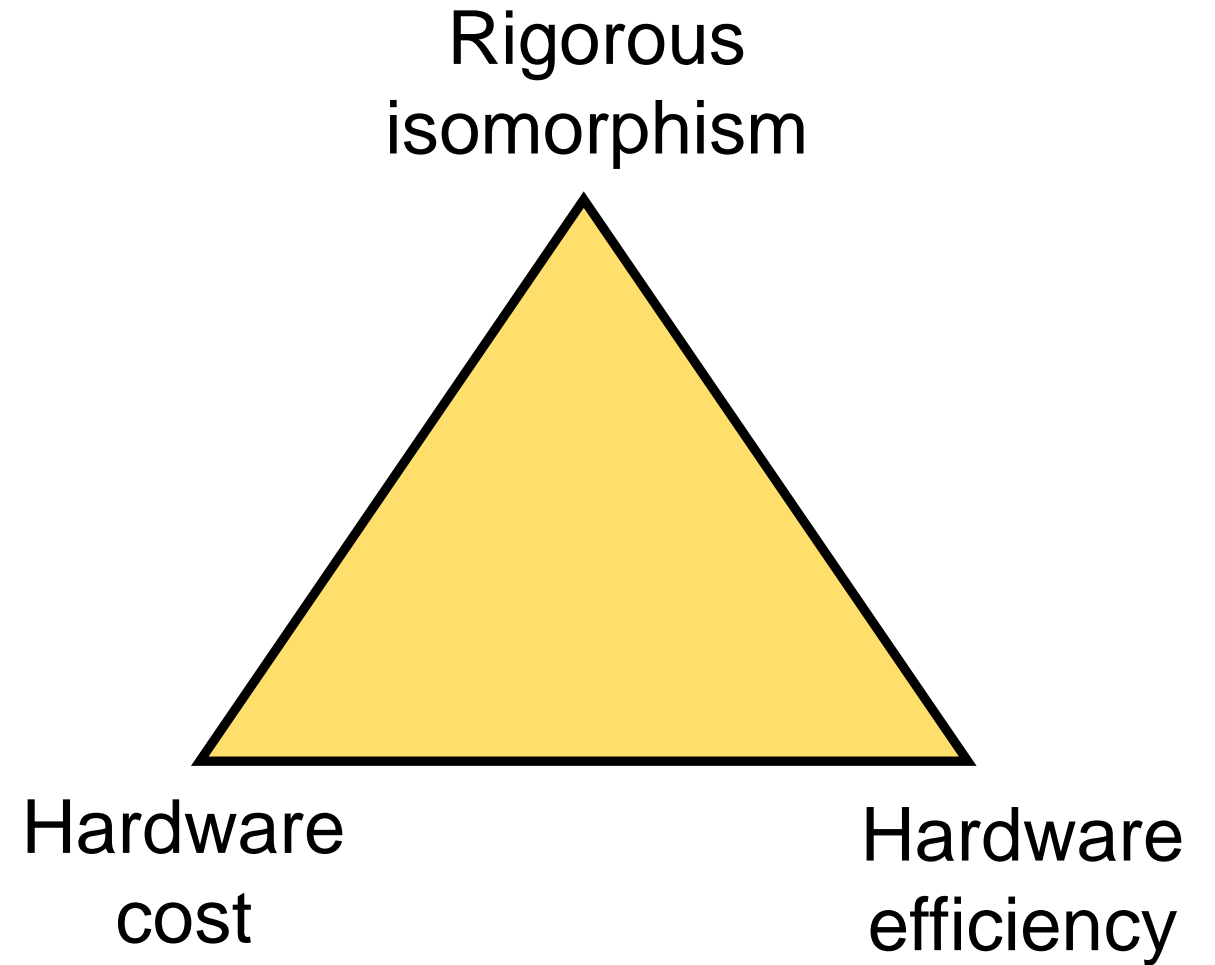
Calibration

Safe parameter regimes

Fabrication tolerances

Explicit error correction

→ High barrier for novel hardware



# But achieving rigorous isomorphism involves trade-offs

Calibration

Rigorous  
isomorphism

Safe parameter regimes



A motivating question for our work:

How much isomorphism do we *really* need?

Fa

Ex



→ High barrier for novel hardware

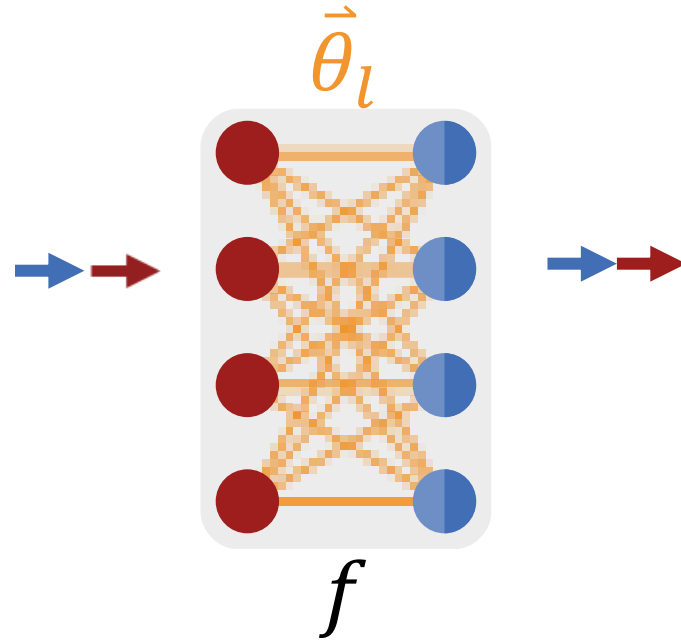
Hardware  
cost

Hardware  
efficiency

(Physical) neural networks

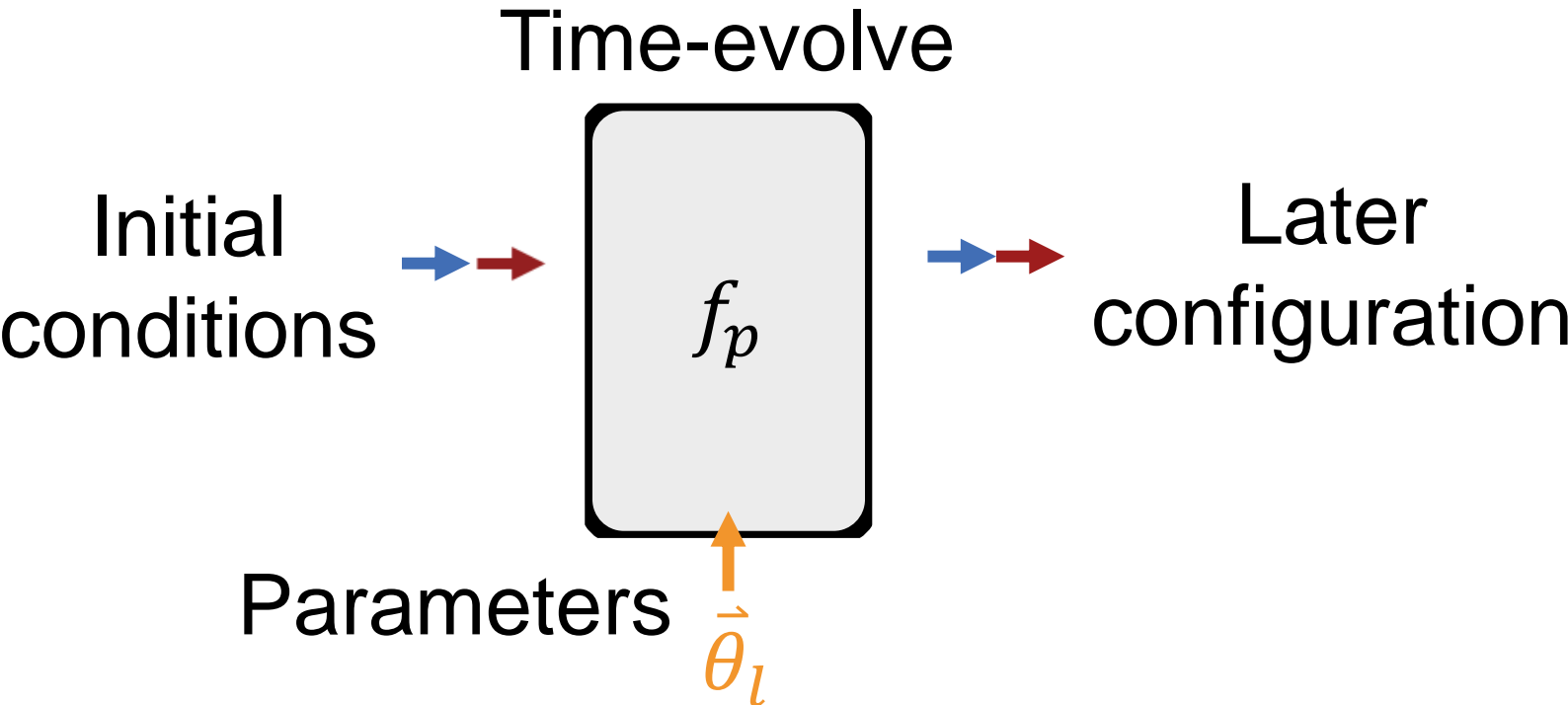


Deep neural network layers are **controlled** mathematical transformations



$$\vec{y}[l + 1] = f(\vec{y}[l], \vec{\theta}_l)$$

# Programmable physical systems give us controllable *physical* transformations



$$\vec{y}[l + 1] = f_p(\vec{y}[l], \vec{\theta}_l)$$

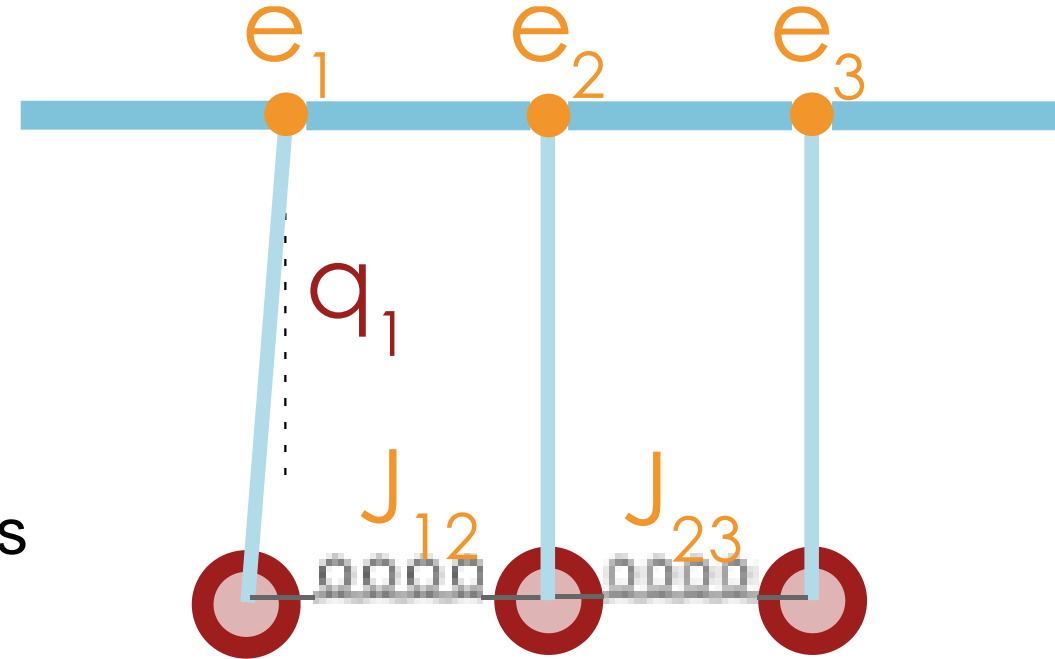
# Example: dynamics of coupled oscillators

Input data = initial ( $t = 0$ ) angles

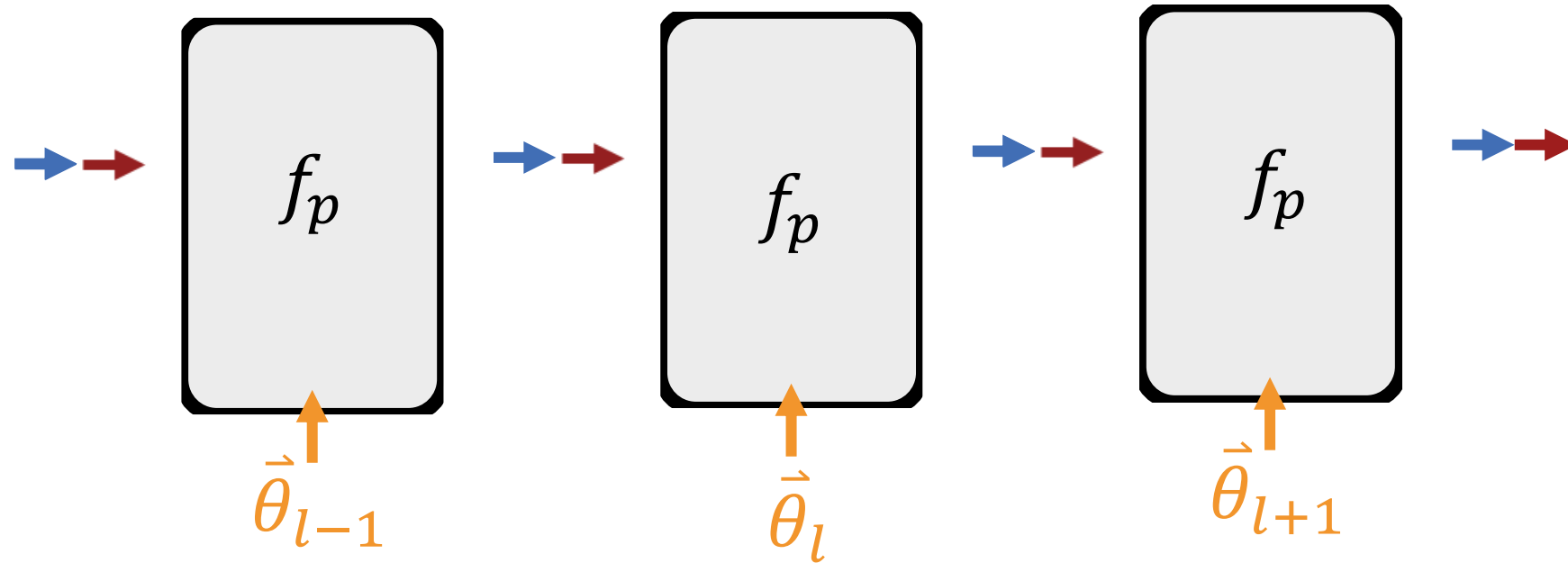
Parameters =  
coupling between oscillators  
(spring stiffness)  
drive (fixed torque at joint)

Output = Later ( $t = T$ ) angles of the oscillators

$$\frac{d^2 q_i}{dt^2} = -\sin q_i + \sum_{j=1}^N J_{ij} (\sin q_j - \sin q_i) + e_i$$



# Deep physical neural networks

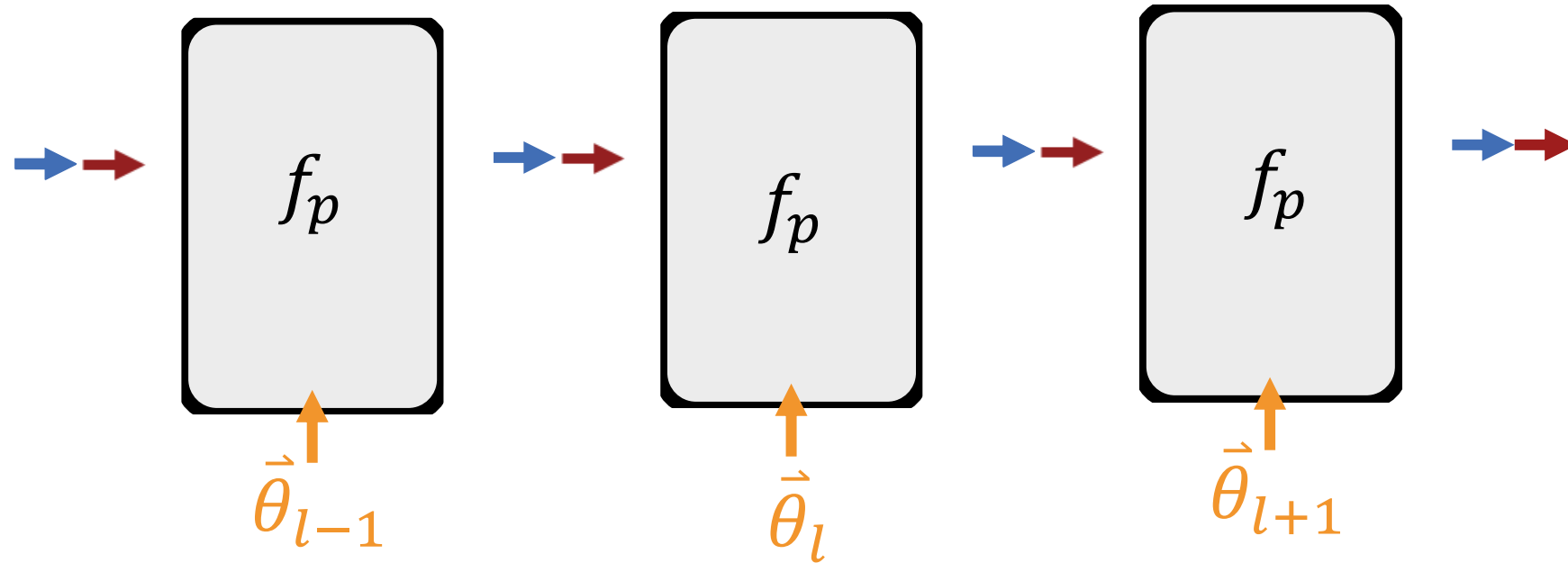


*Physical neural network:*

Network of **controllable physical transformations**



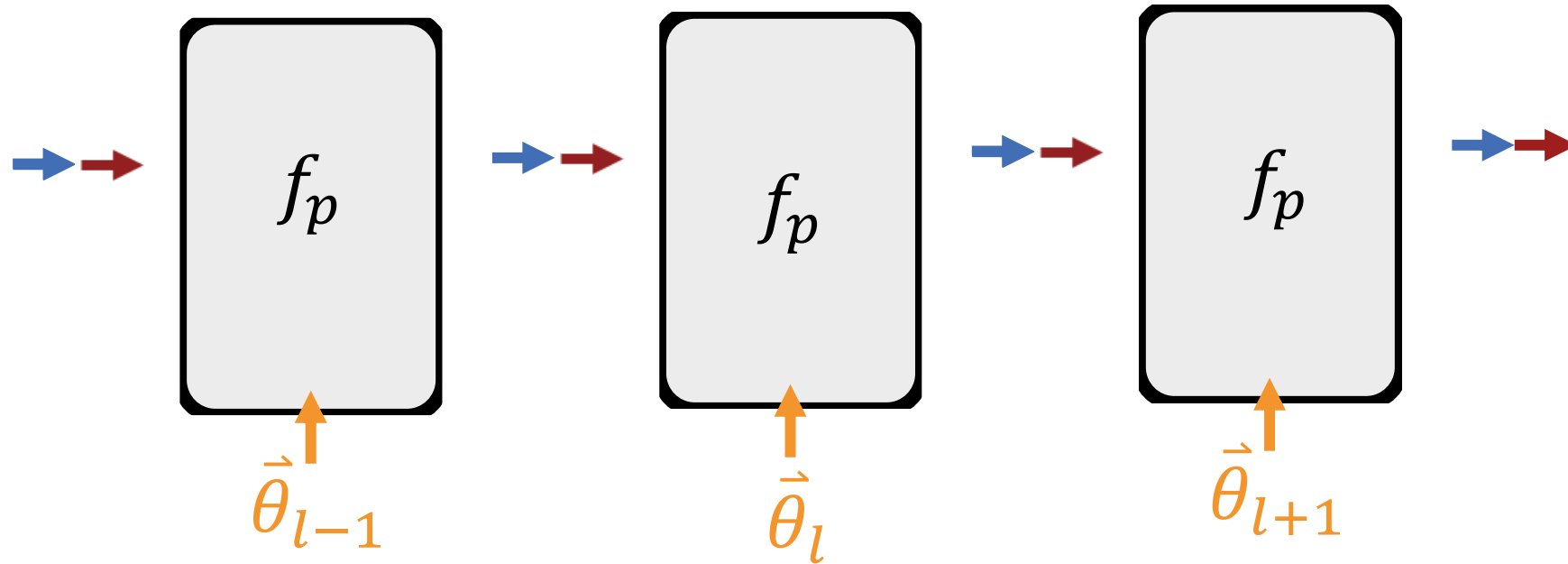
## Deep physical neural networks



*Physical neural network:*

Network of **controllable physical transformations**, trained to perform **physical functions**

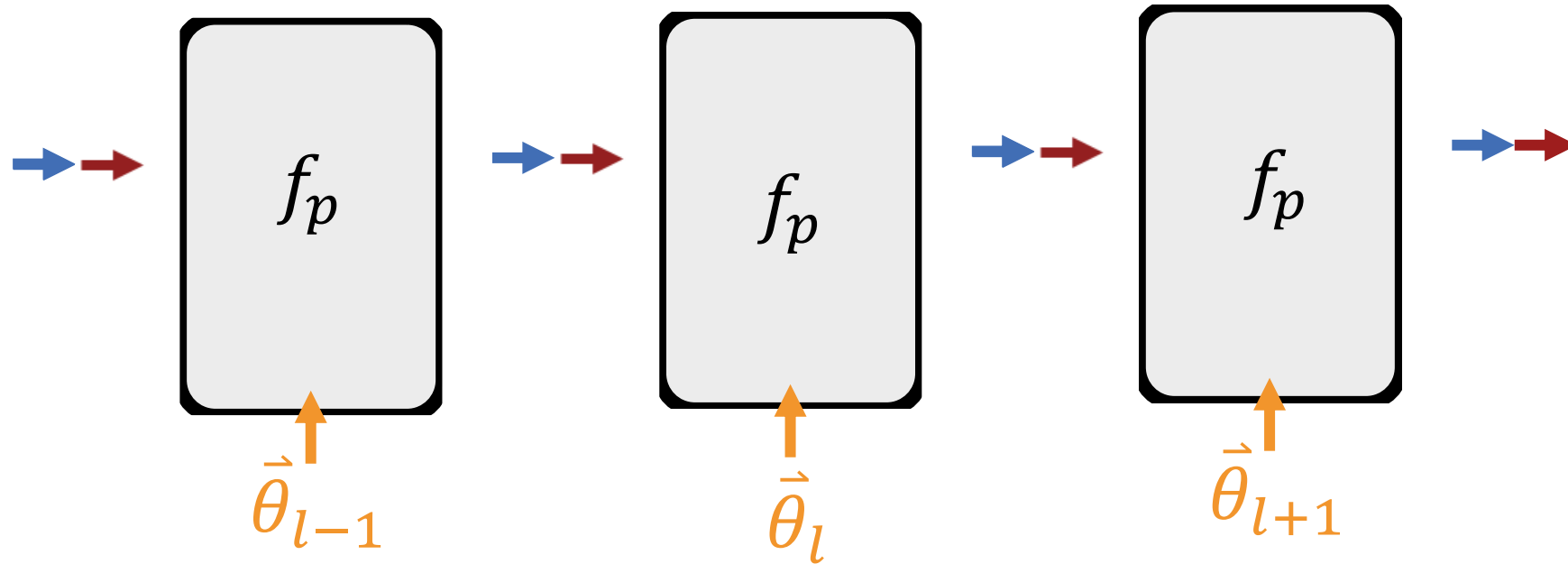
## Deep physical neural networks



*Physical neural network:*

Network of **controllable physical transformations**, trained to perform **physical functions**, similar to how (artificial) neural networks are trained to perform *mathematical functions*

# Deep physical neural networks



## *Physical neural network:*

Network of **controllable physical transformations**, trained to perform **physical functions**, similar to how (artificial) neural networks are trained to perform *mathematical functions*

→ This is a “flexible” analogy, **not** a strict 1:1 emulation of any specific artificial neural network’s math!

**Why on earth should this work?**



# Why on earth should this work?

DNNs model real-world physics well because they have similar structure

Nonlinear, hierarchical, high-dimensional, noisy, analog, local, sparse,...

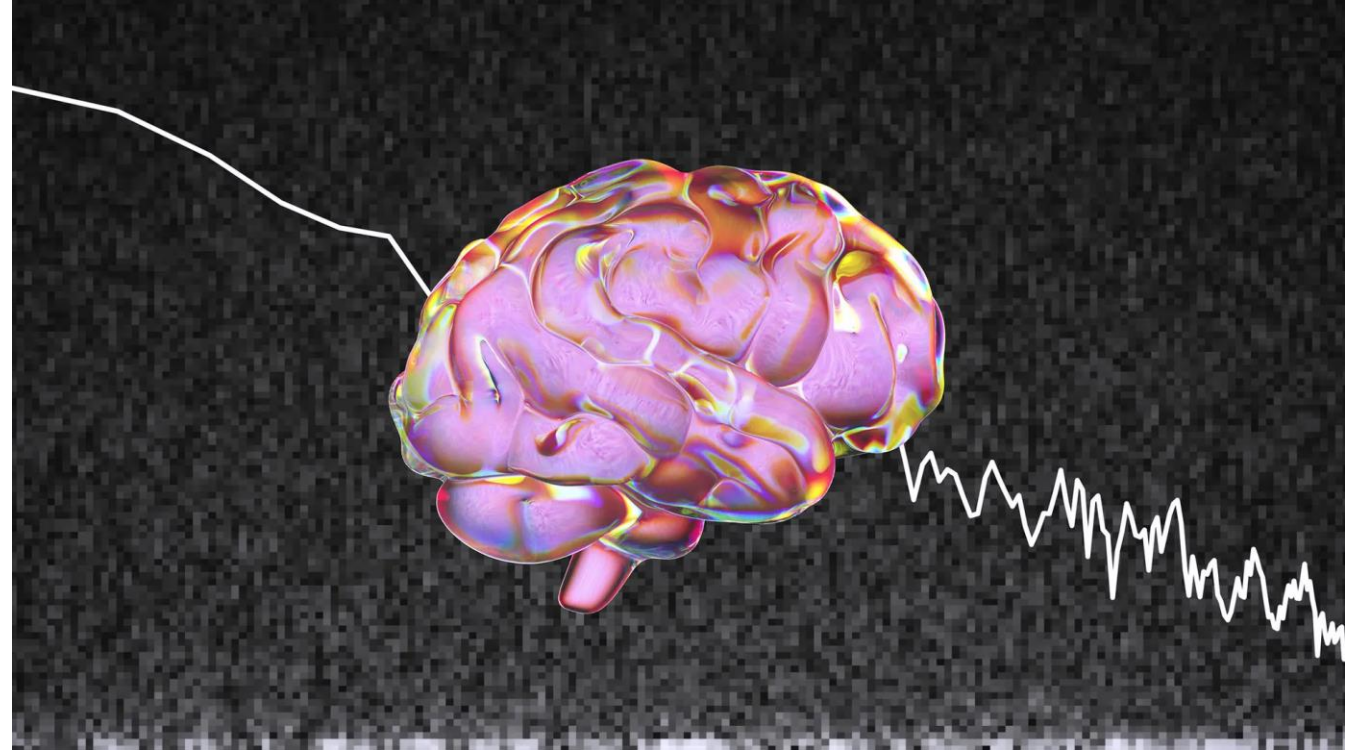


Illustration: Olena Shmahalo/Quanta Magazine; Thomas Donoghue

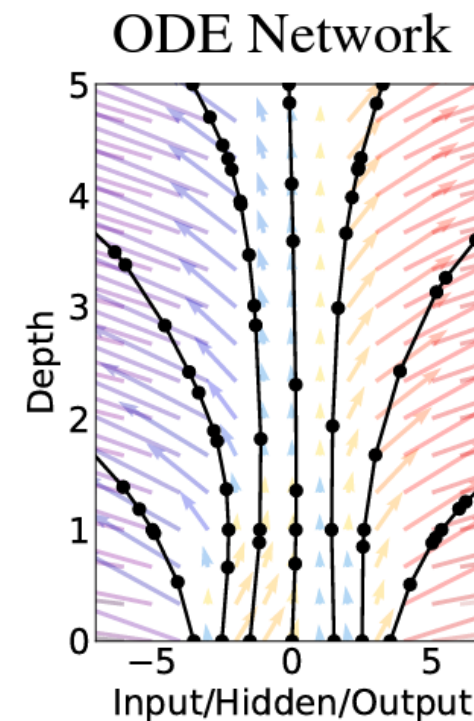
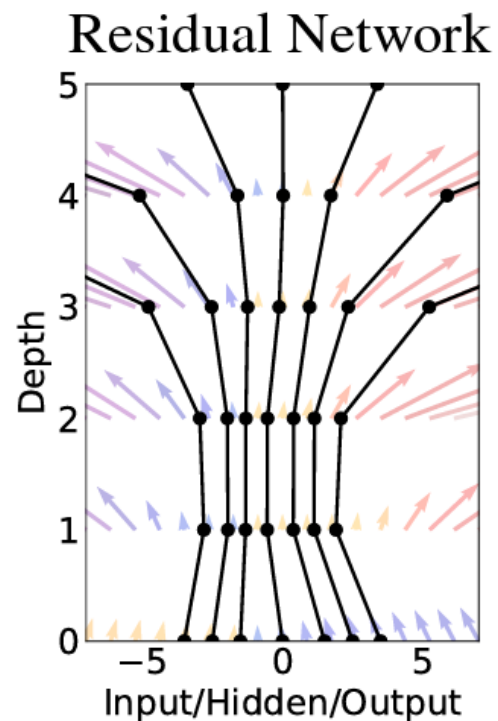
# Why on earth should this work?

DNNs model real-world physics well because they have similar structure

Nonlinear, hierarchical, high-dimensional, noisy, analog, local, sparse,...

Neural ordinary differential equations

$$\mathbf{h}_{t+1} = \mathbf{h}_t + f(\mathbf{h}_t, \theta_t) \longrightarrow \frac{d\mathbf{h}(t)}{dt} = f(\mathbf{h}(t), t, \theta)$$



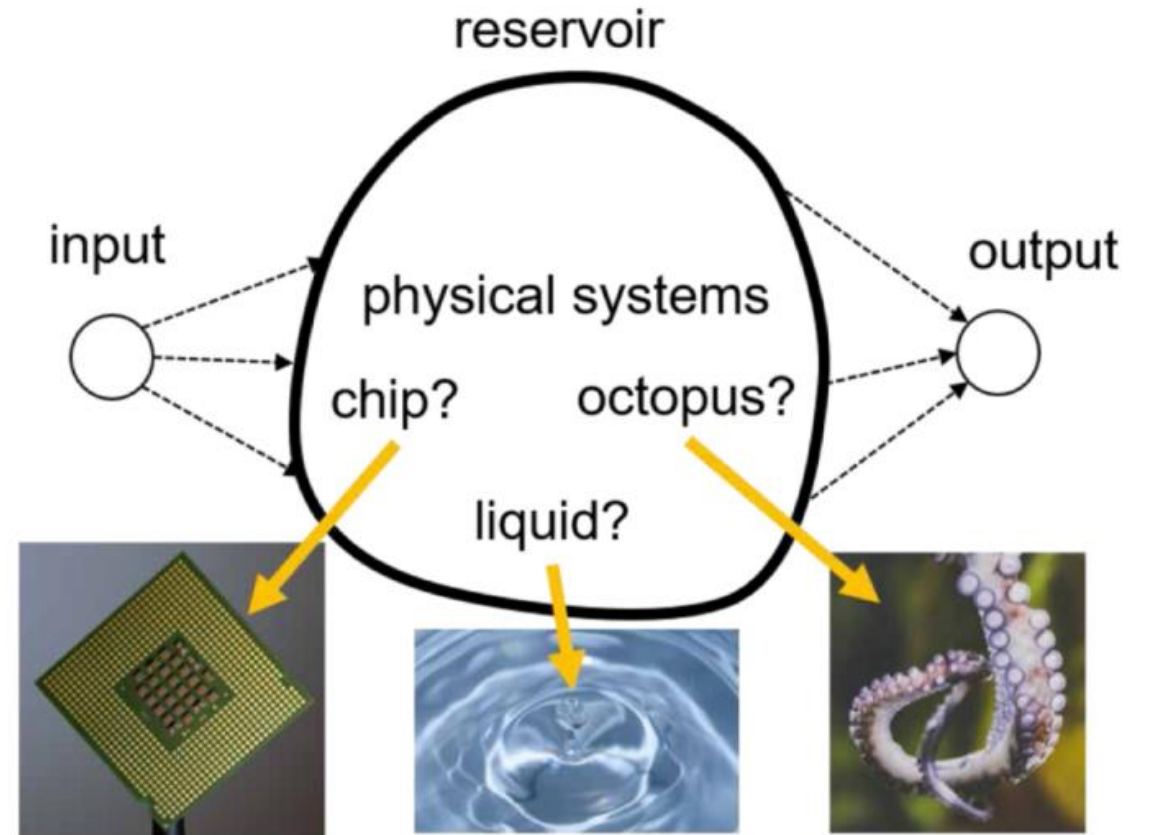
# Why on earth should this work?

DNNs model real-world physics well because they have similar structure

Nonlinear, hierarchical, high-dimensional, noisy, analog, local, sparse,...

Neural ordinary differential equations

Physical reservoir computing



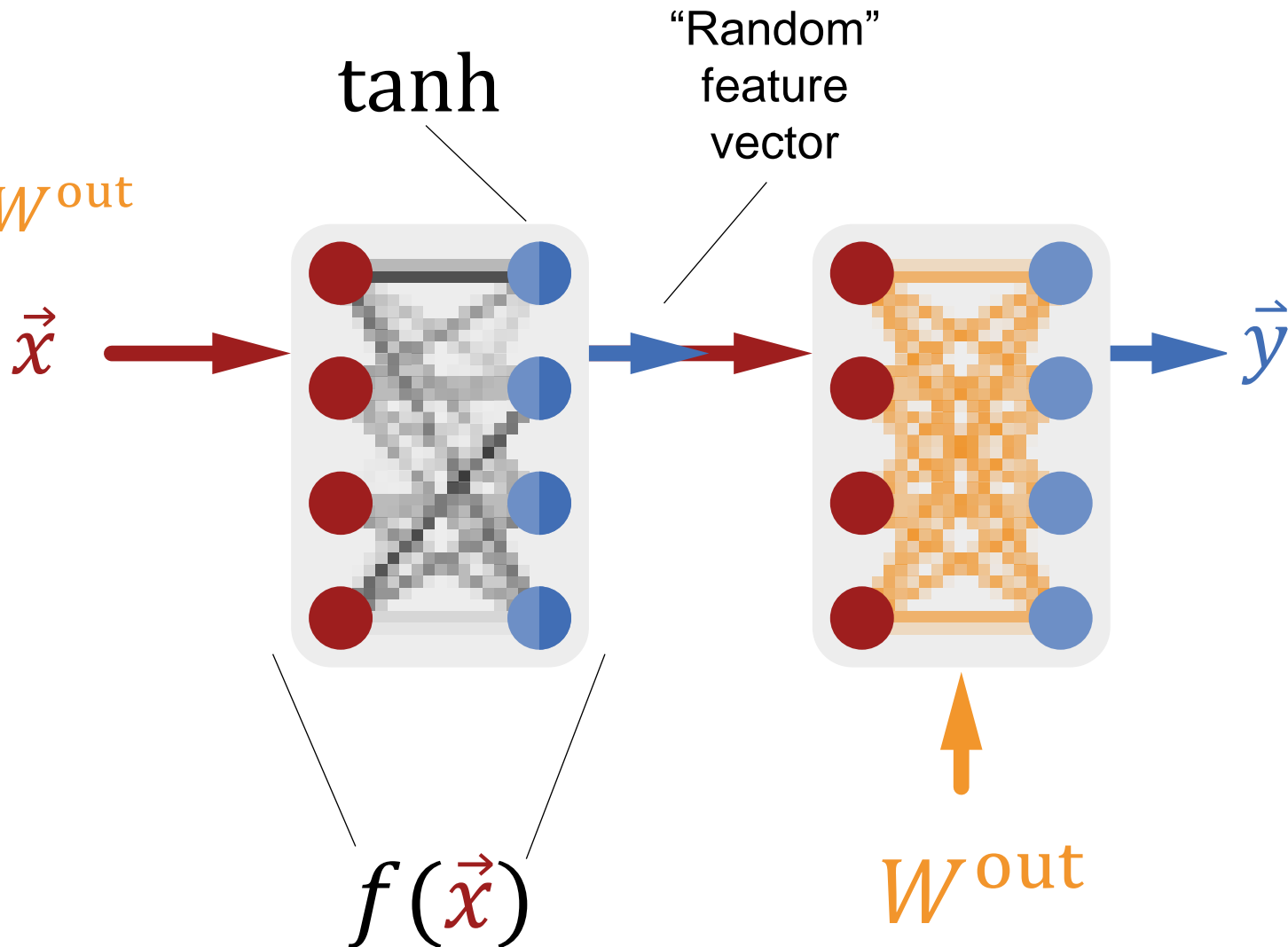
# Random features – echo state, liquid state, “extreme learning”

*Untrained* random neural network

*Trained* linear digital output layer,  $W^{out}$

Fast + stable training

$$\vec{y} = W^{out} f(\vec{x})$$



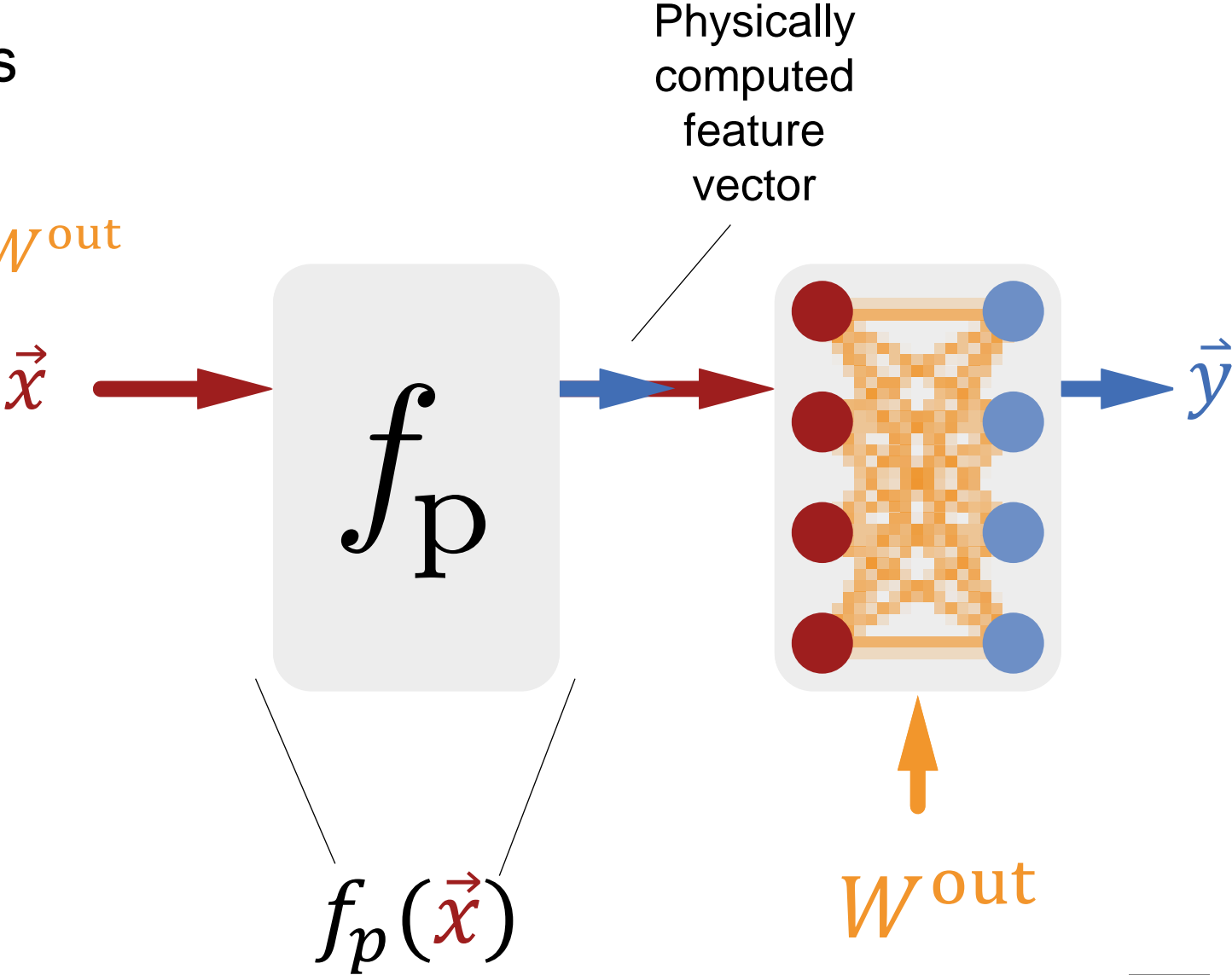
# Physical reservoir computing

*Untrained* physical transformations

*Trained* linear digital output layer,  $W^{out}$

Fast + stable training

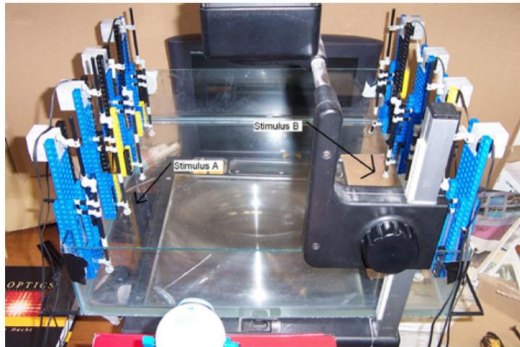
$$\vec{y} = W^{out} f_p(\vec{x})$$



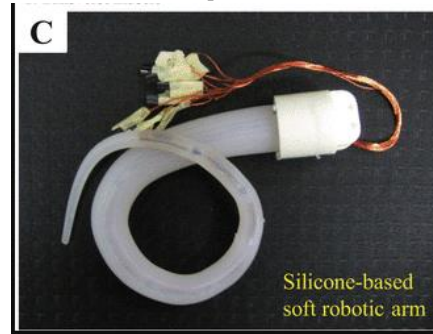


# A marvelous range of things provide USEFUL physical features!

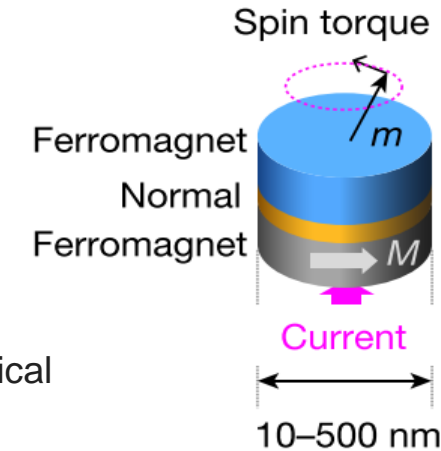
## A bucket of water



## Octopus arms



## Nano-oscillators (spintronic)

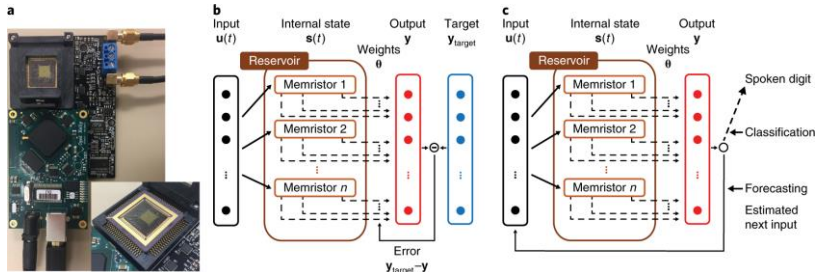


Torrejon et al. "Neuromorphic computing with nanoscale spintronic oscillators." *Nature* (2017)

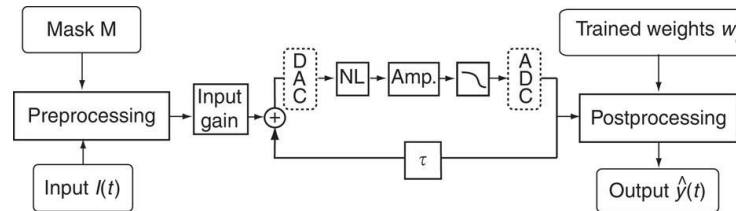
Fernando and Sojakka. "Pattern recognition in a bucket." *European Conference on Artificial Life* (2003).

Nakajima, "Muscular-hydrostat computers: Physical reservoir computing for octopus-inspired soft robots." *Brain Evolution by Design* (2017)

## Nonlinear analog electronics (memristors)

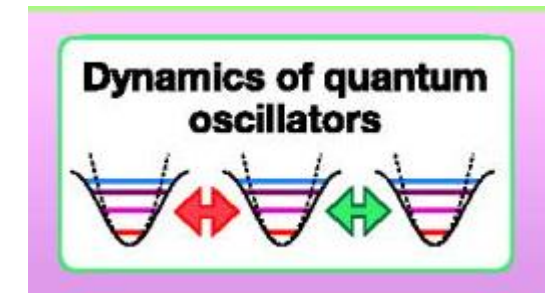


## Optoelectronic loops and networks



Appeltant et al. "Information processing using a single dynamical node as complex system." *Nature Communications* (2011)

## Quantum nonlinear oscillators



Marković & Grollier, *Appl. Phys. Lett* (2020)

Moon, et al. "Temporal data classification and forecasting using a memristor-based reservoir computing system." *Nature Electronics* (2019)

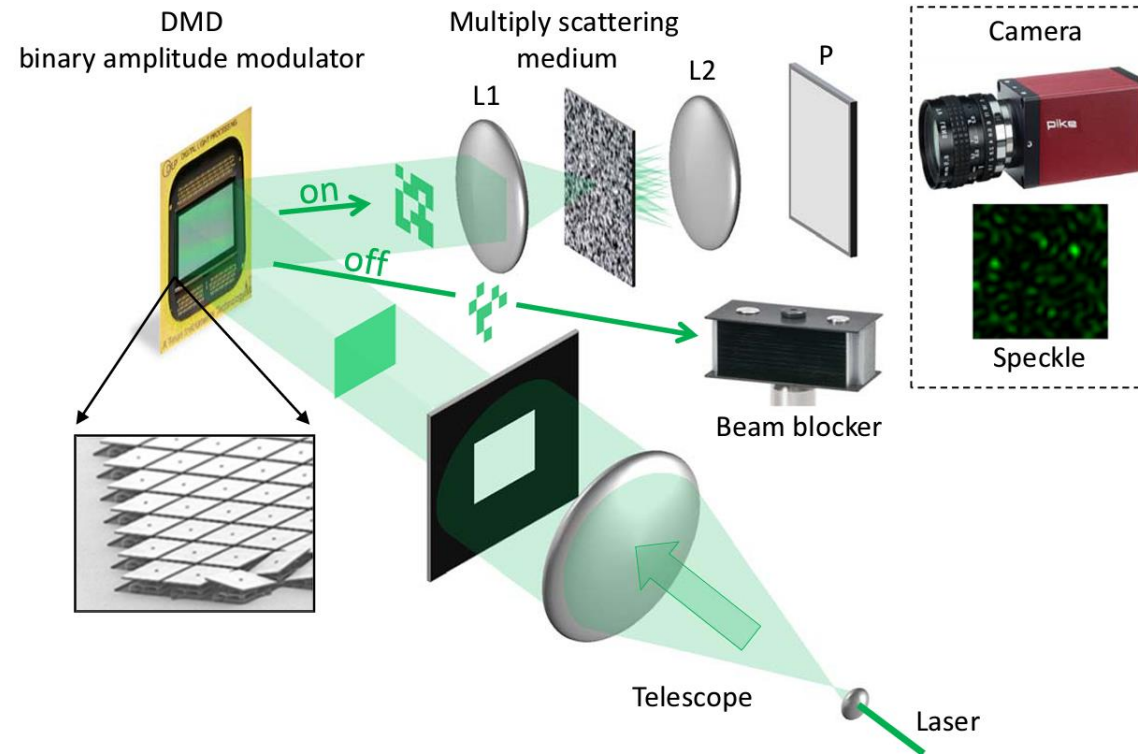
And many more...

# Many such features are computed physically with VASTLY more energy-efficiency than is possible with digital electronics

Just one example:

Random matrix-vector features at: ~100 analog Peta-operations/s  
~10 aJ/op

**10<sup>6</sup> more efficient than GPU\***

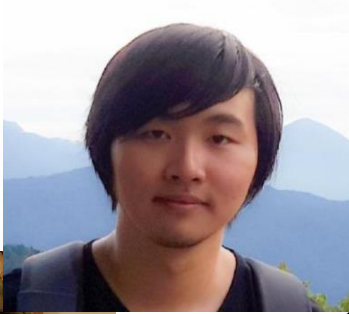


See poster by Fei Xia, ENS

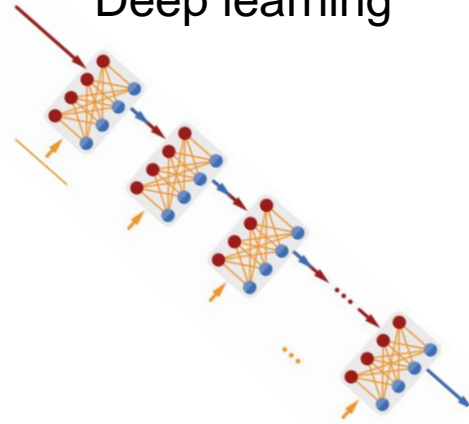
A. Saade et al. International Conference on Acoustics, Speech and Signal Processing (ICASSP). IEEE, 2016

\*for random matrix-vector operations, see supplementary section 3 of arXiv:2104.13386

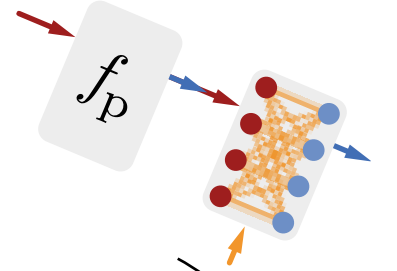
Circa 2018-2020...



Deep learning



Physical reservoir computing

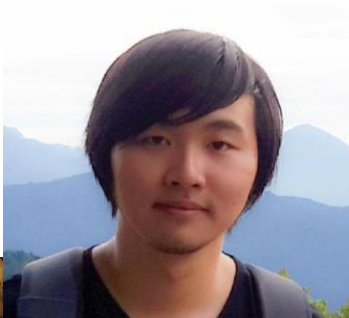




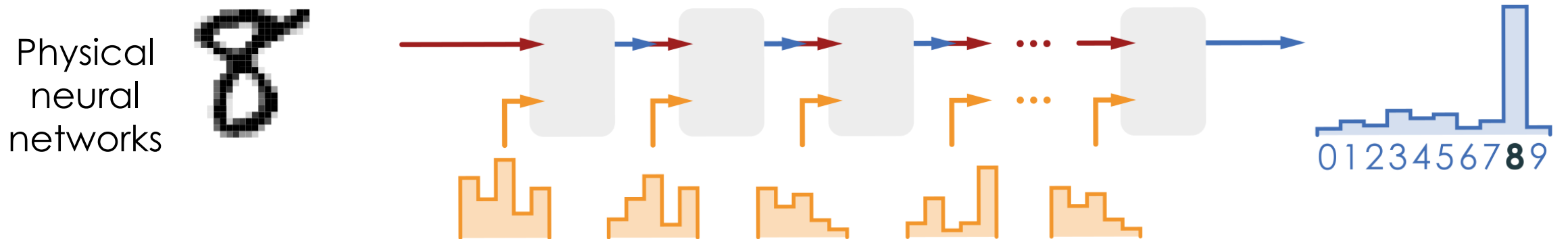
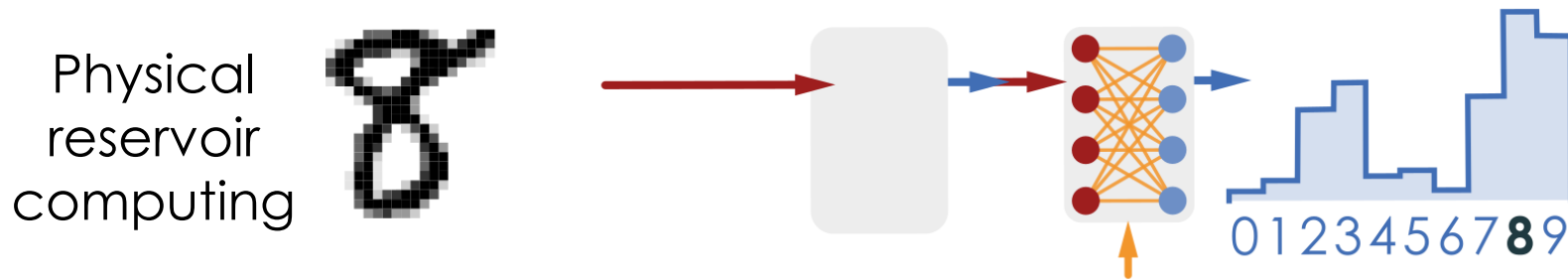
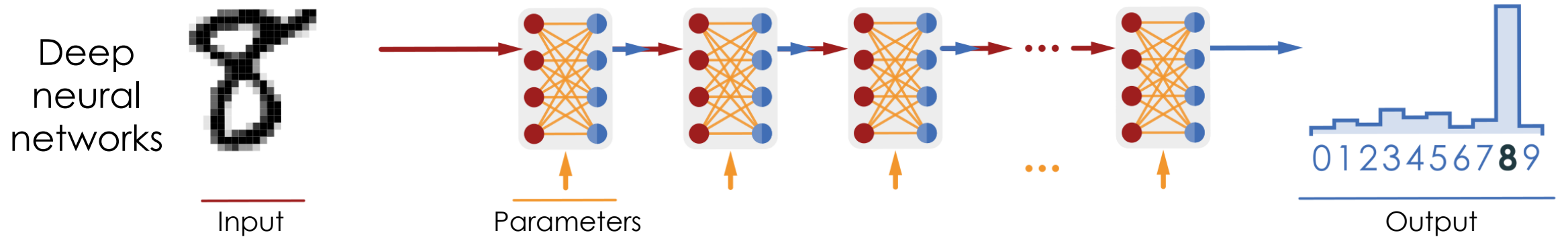
\*\*Many others were thinking about this same basic thing too, albeit in different contexts, see especially:

- quantum circuit learning / variational quantum algorithms (e.g., Fujii, Coles,...)
- “In materio computing” (e.g., Van der Wiel..)
- wave computing (e.g., Fan, Fleury, Marquardt...)

Circa 2018-2020...



# Physical neural networks combine the key ingredients of deep learning with the physics-first opportunism of reservoir computing

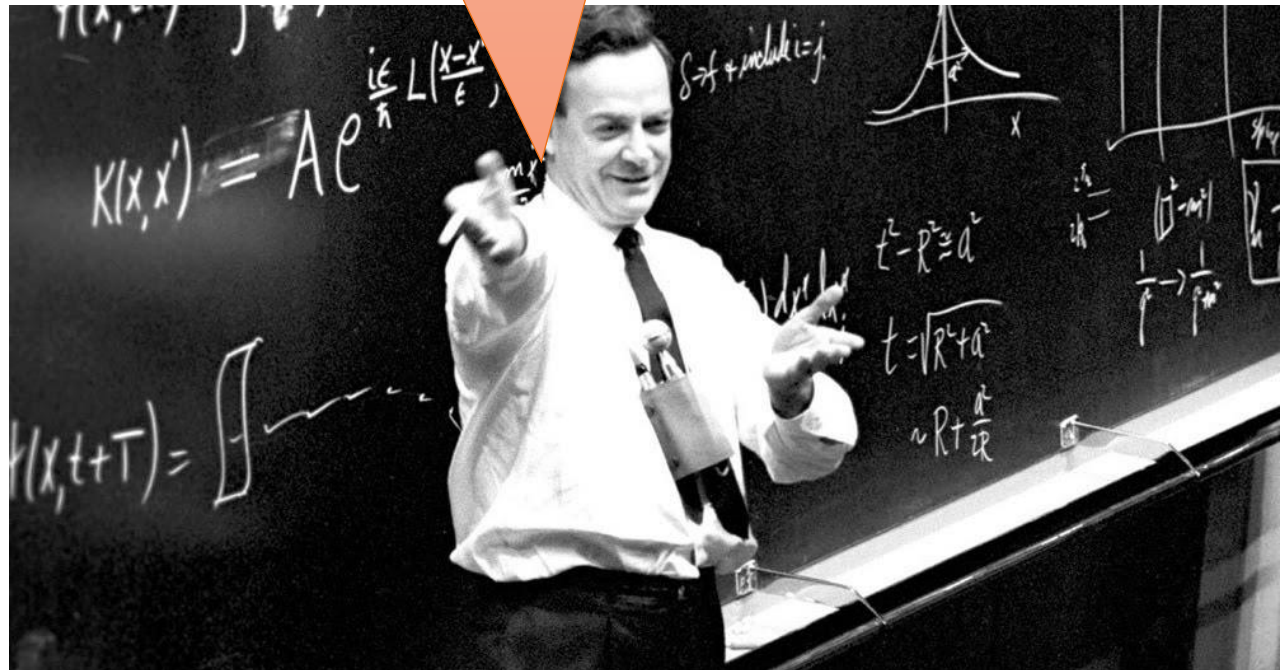




# What would be the pay-off if it works?

- Automated physics-first computing!
- *(Potentially!)* **HUGE** speed up + energy-efficiency boosts for DNN-like calculations
- Learn complex *physical* functions (e.g., “smart” sensing, micromachines)

There is plenty of room at the bottom!  
(for hardware innovation)



# An example physical neural network

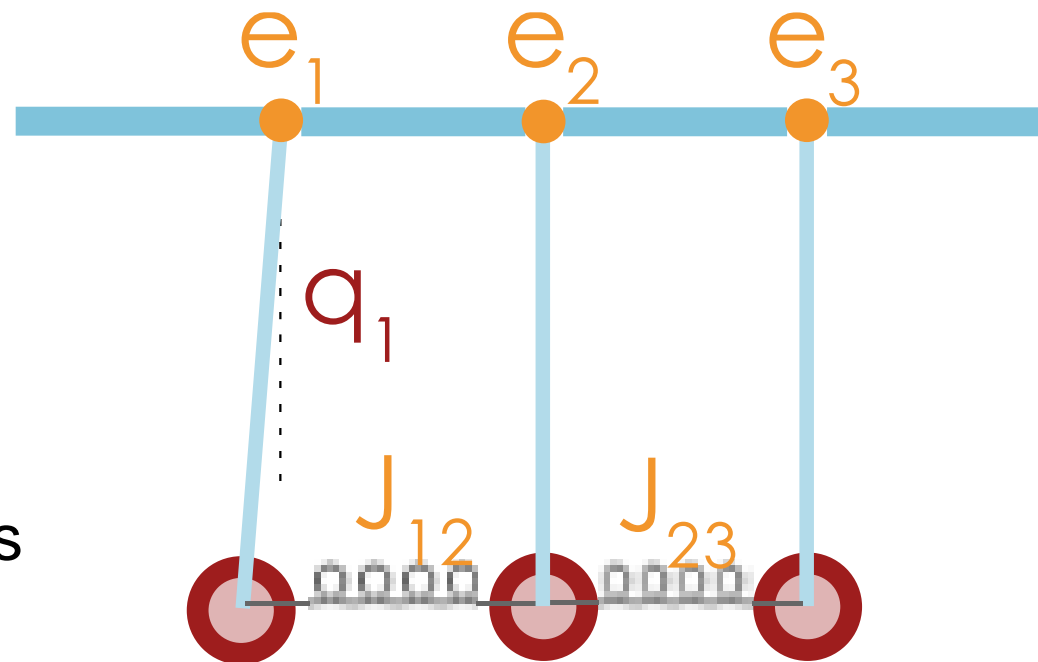
# Classifying images with coupled nonlinear oscillators

Input data = initial ( $t = 0$ ) angles

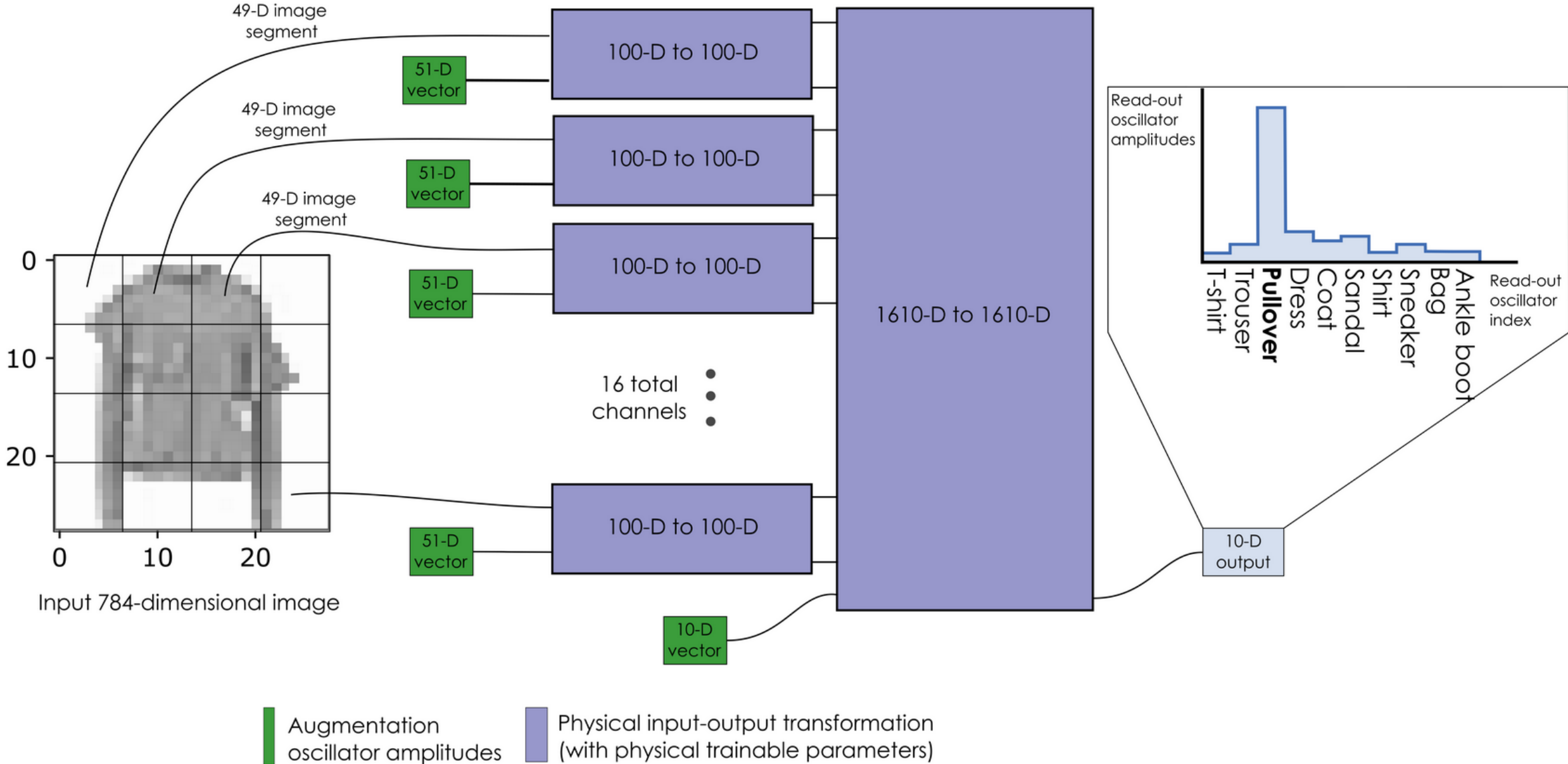
Parameters =  
coupling between oscillators  
(spring stiffness)  
drive (fixed torque at joint)

Output = Later ( $t = T$ ) angles of the oscillators

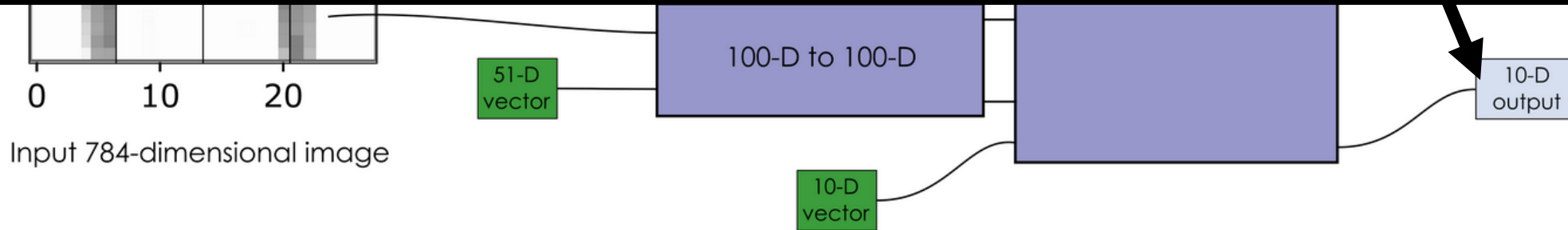
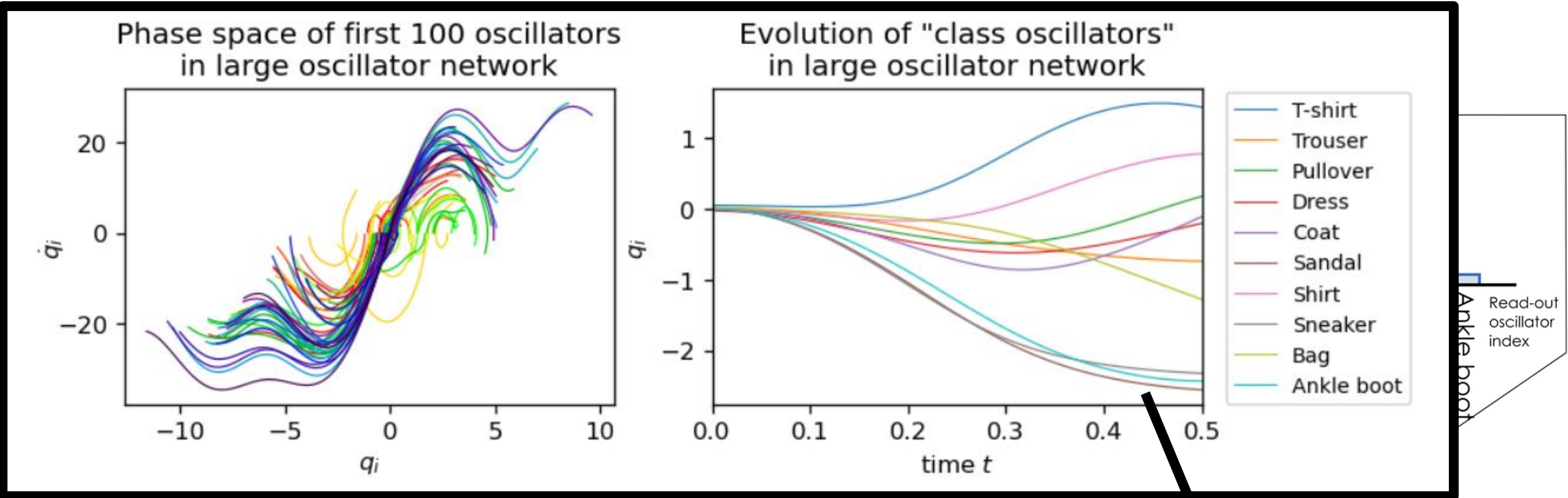
$$\frac{d^2 q_i}{dt^2} = -\sin q_i + \sum_{j=1}^N J_{ij} (\sin q_j - \sin q_i) + e_i$$



# Physical neural network architecture



# Physical neural network architecture

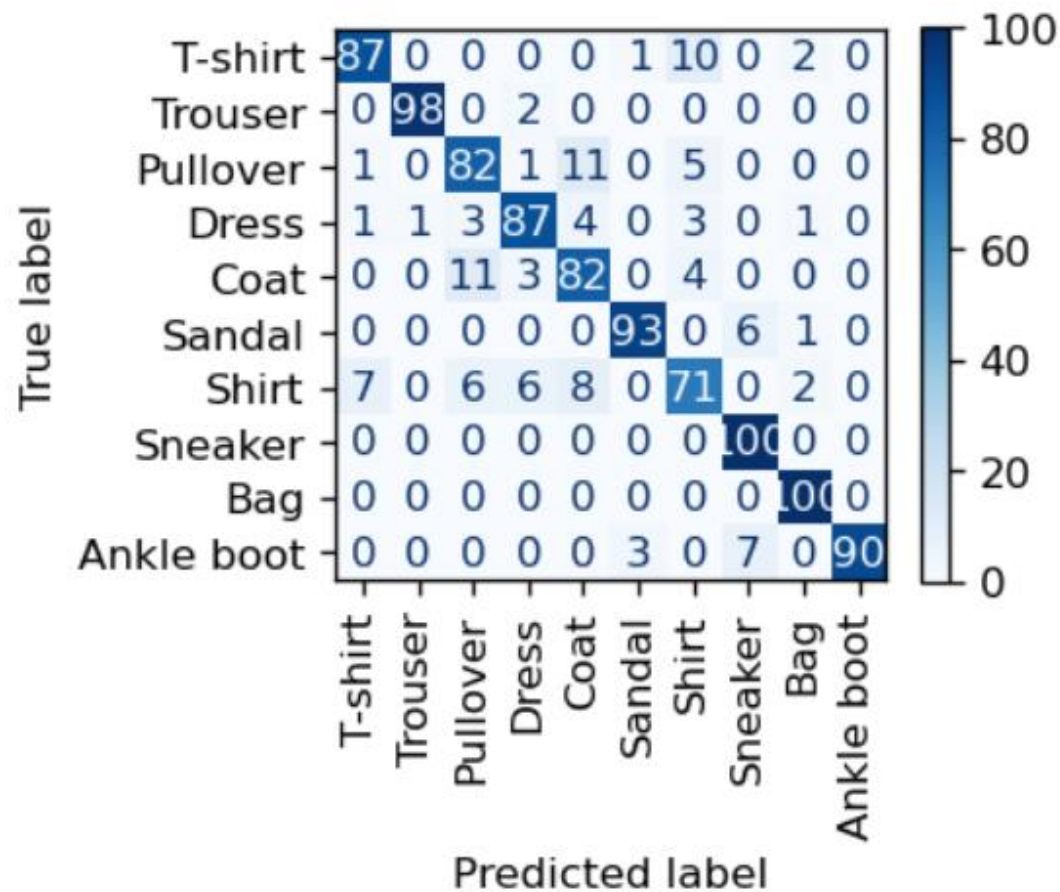
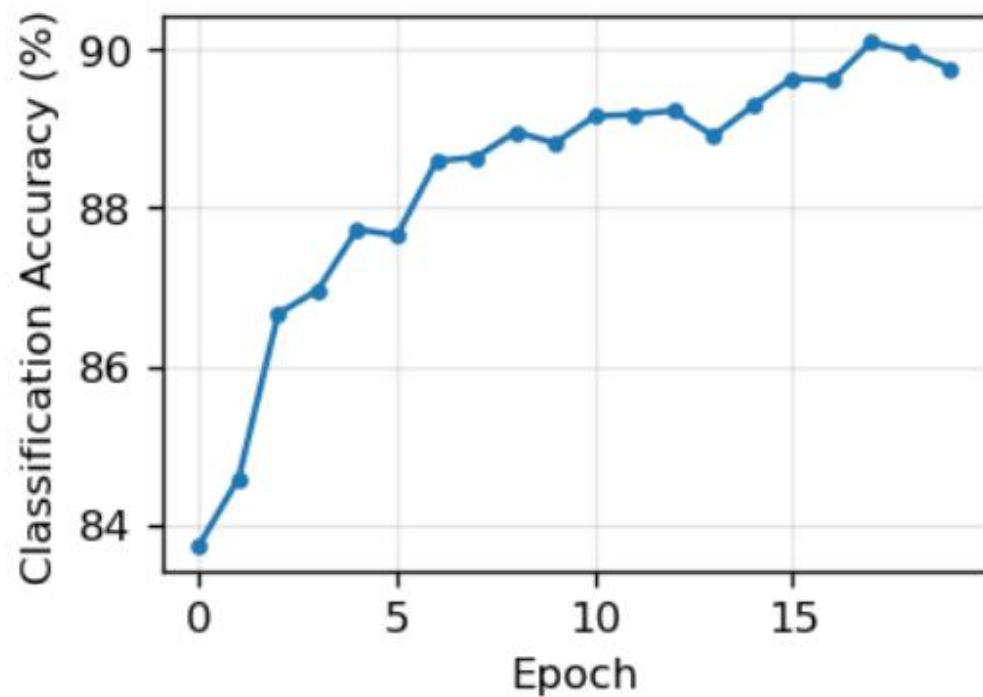


Augmentation oscillator amplitudes

Physical input-output transformation (with physical trainable parameters)



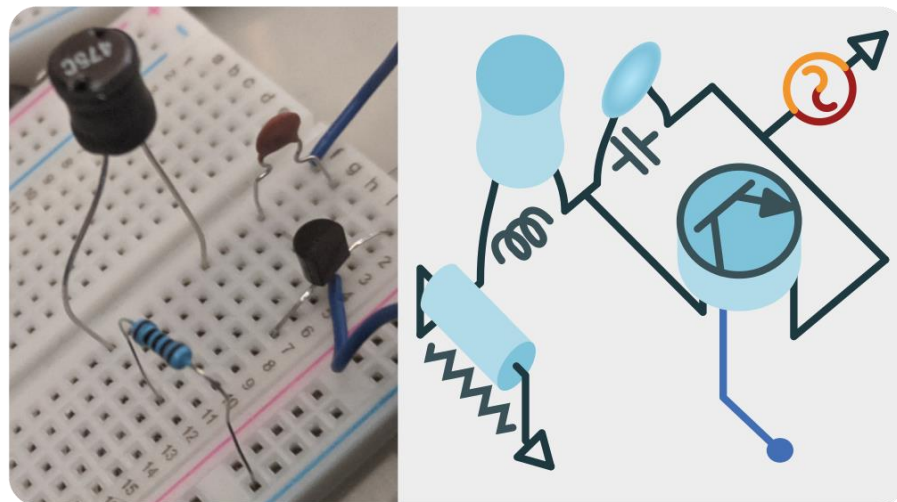
# Classifying fashion images with an oscillator-PNN



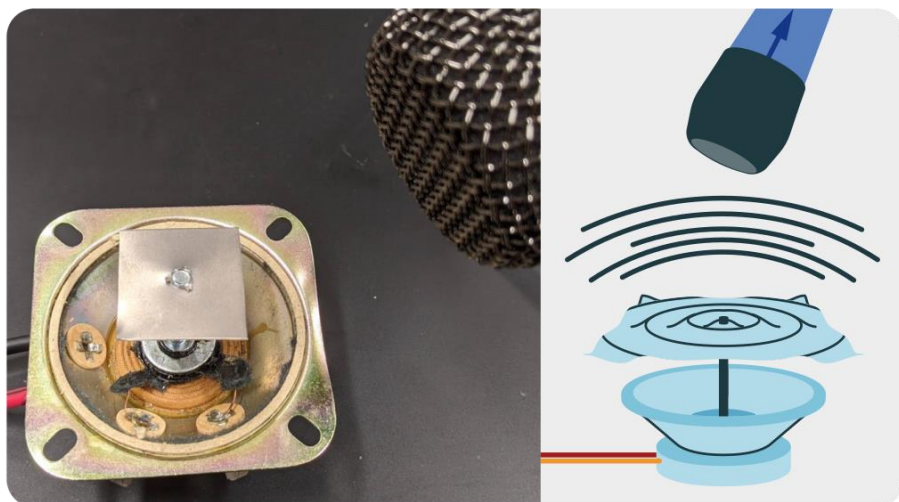
Can *everything* be a neural network?

Yes! (but not always a good one)

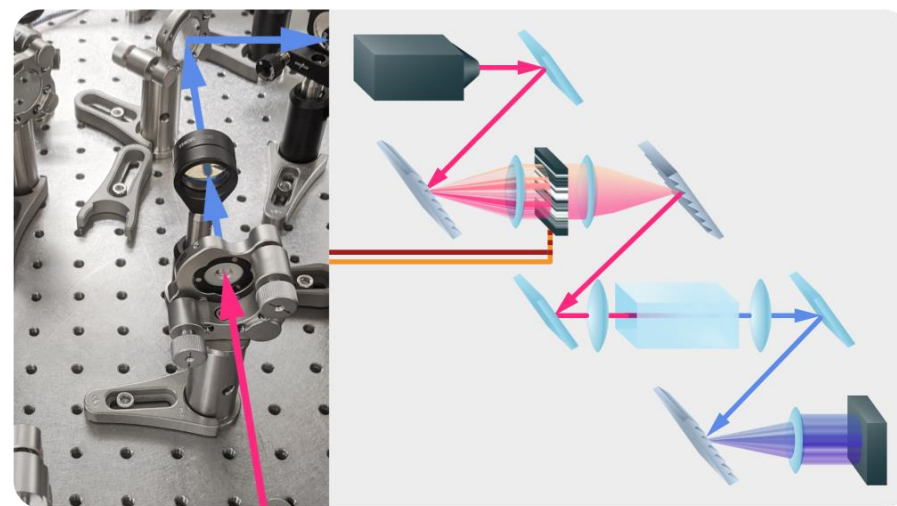
# Electronics



# Mechanics

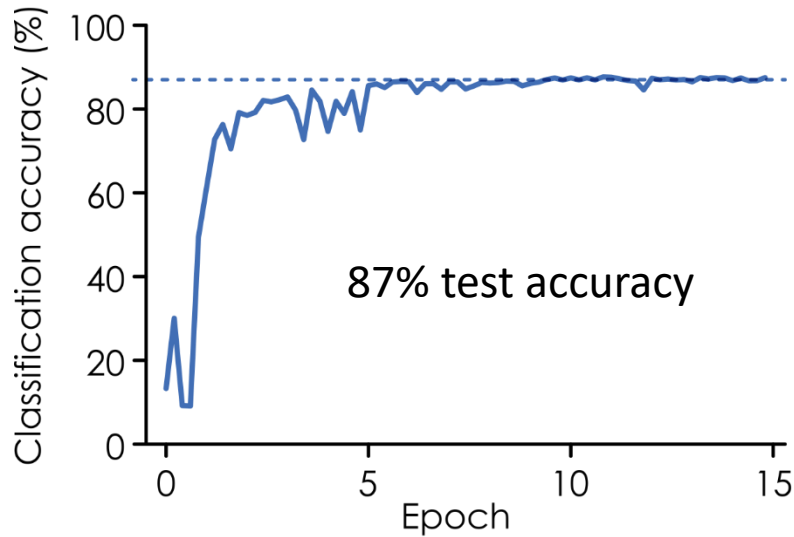
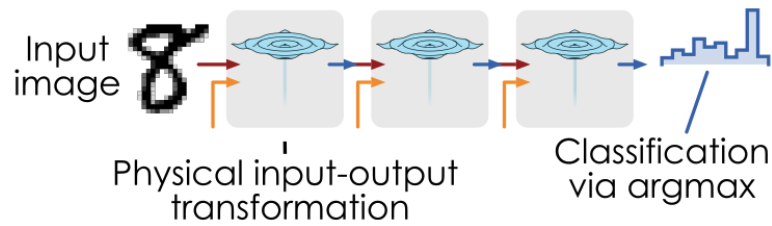


# Optics

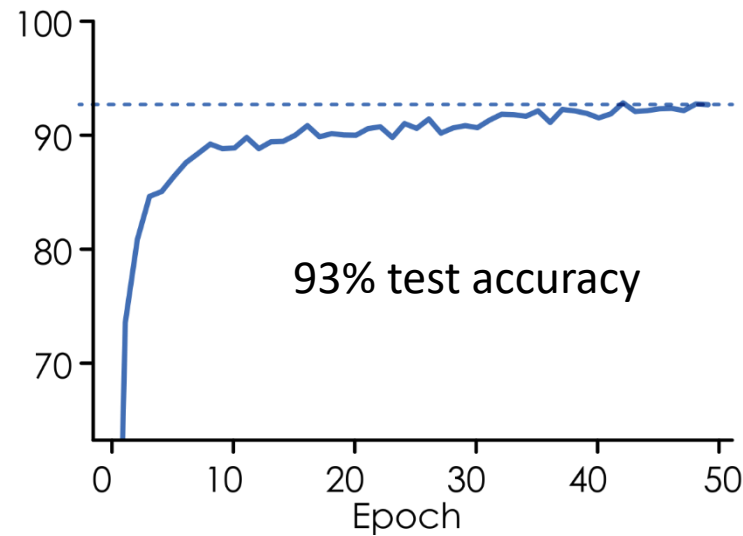
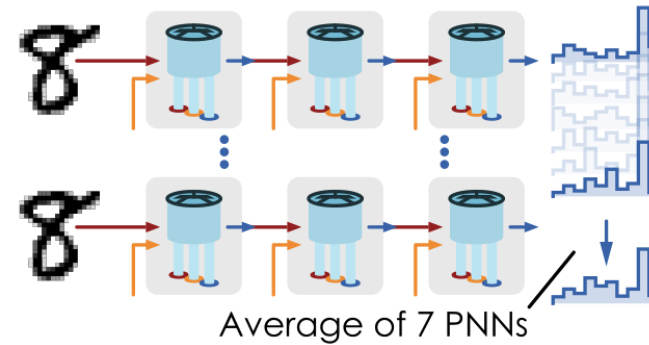


# Diverse PNNs for handwritten digit image classification

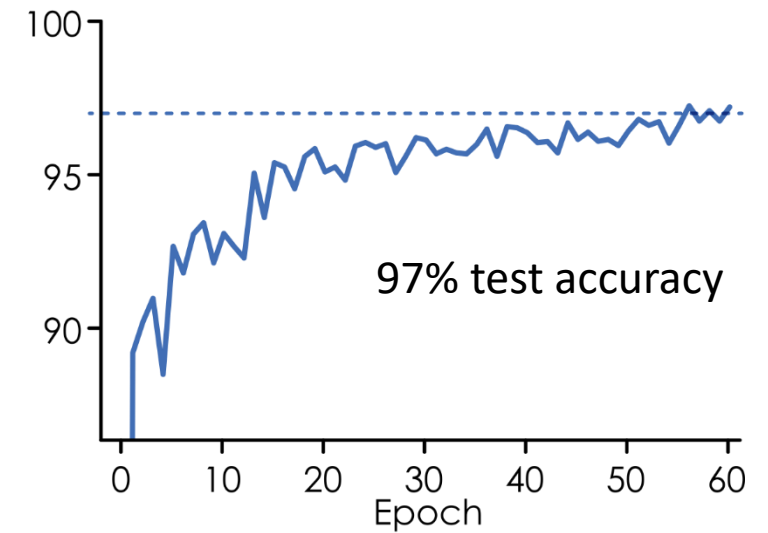
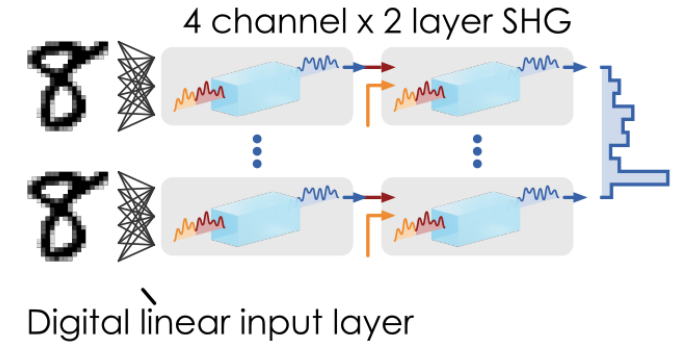
## Mechanics



## Electronics

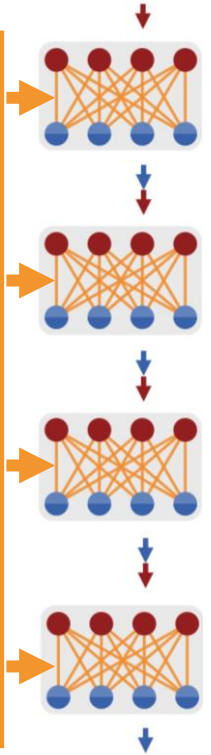


## Optics



# Deep neural networks: training versus inference

Untrained

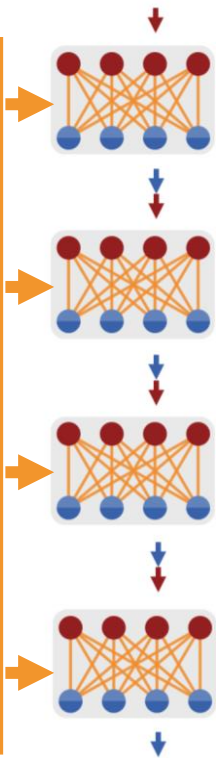


Nonsense

Untrained Parameters

Training

Training input data

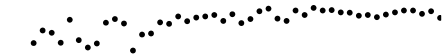


"Cat"

Parameters are **changed**

$$\vec{\theta} \rightarrow \vec{\theta} + d\vec{\theta}$$

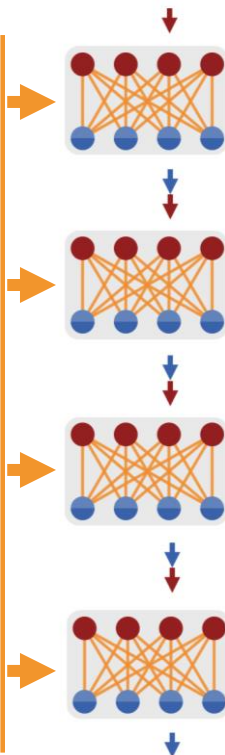
Accuracy



Training step

Inference

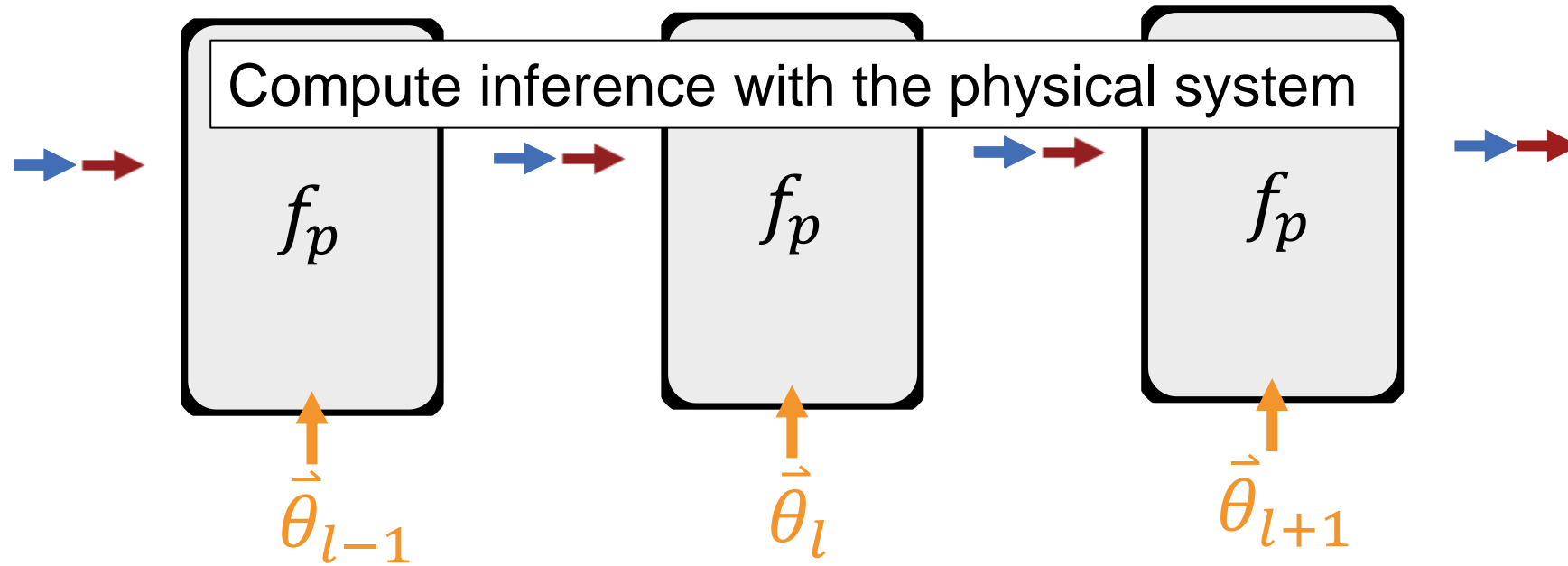
Unseen new input data



"Cat"

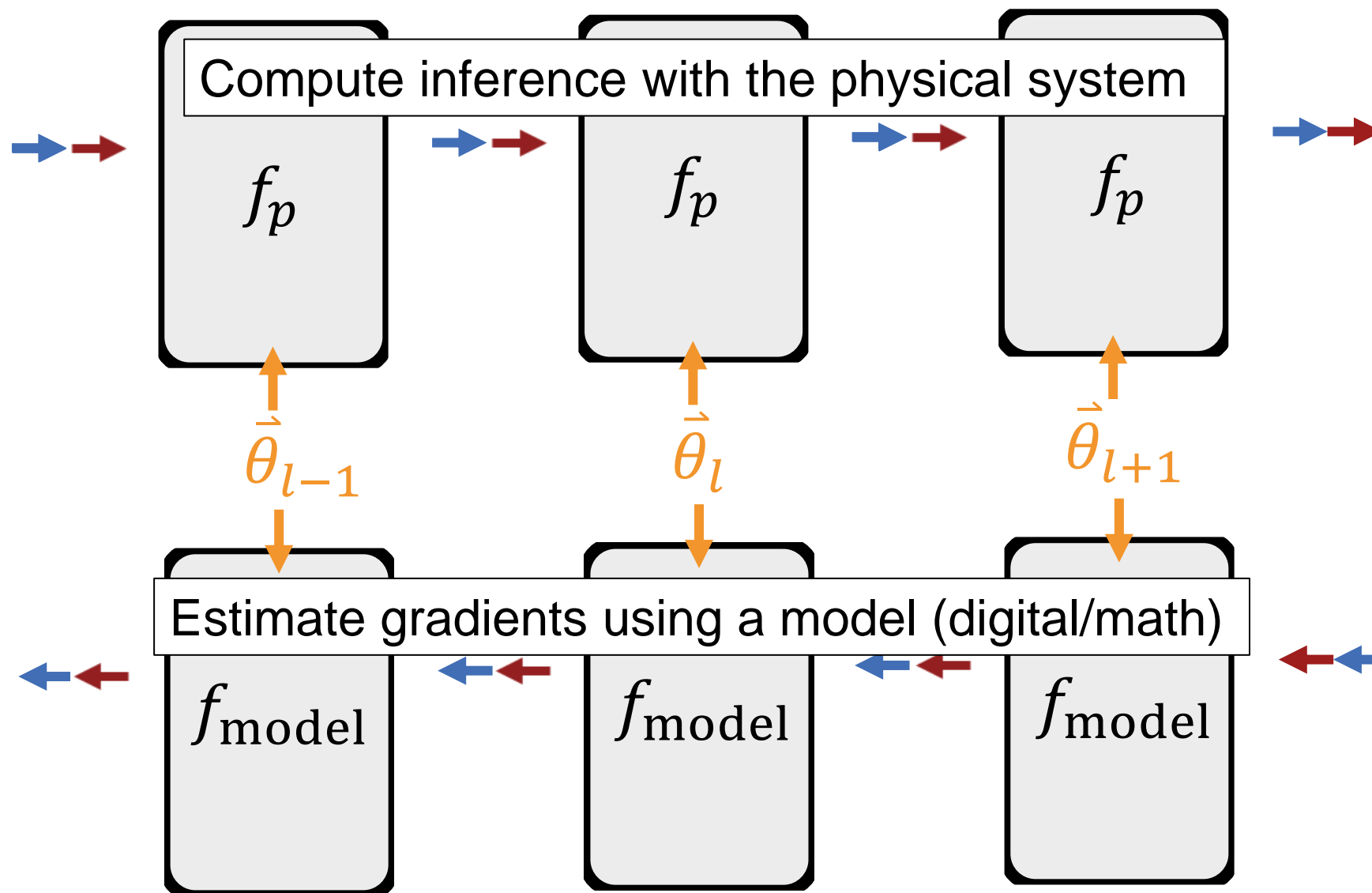
Parameters are **fixed**

# Physics-aware training: Backpropagation through $f_p$



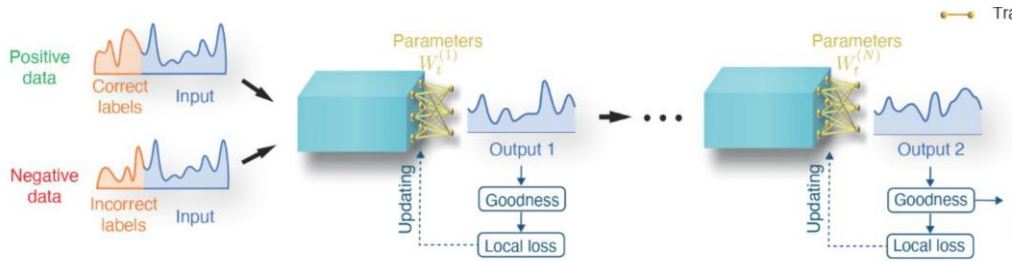


# Physics-aware training: Backpropagation through $f_p$



# Training PNNs *beyond* physics-aware training

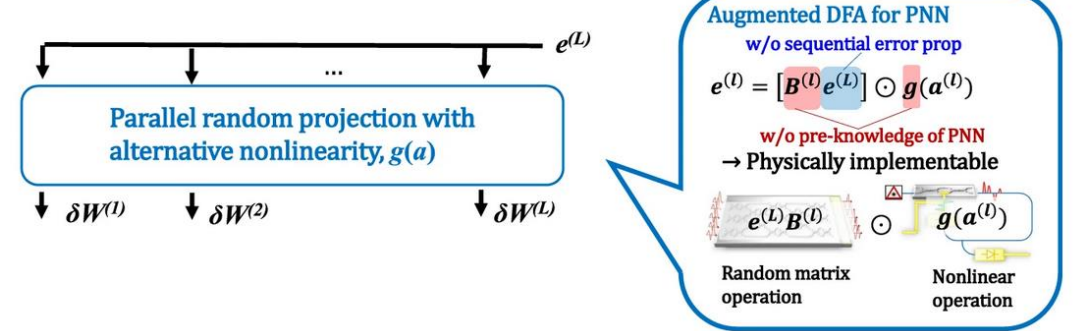
## Forward-forward (layer-by-layer)



Momeni et al., Science (2023)

Hinton, NeurIPS (2023)

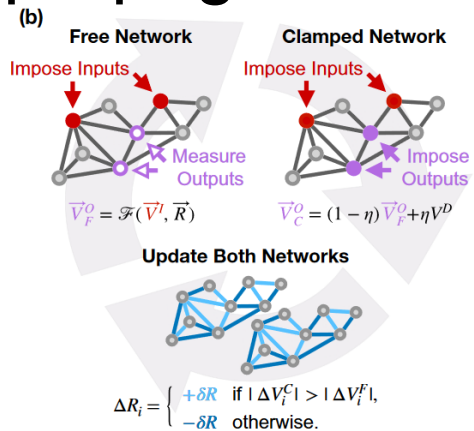
## Direct feedback alignment



Nakajima et al., Nat. Comm (2022)

Lillicrap et al., Nat. Comm (2016)

## Equilibrium propagation / coupled learning

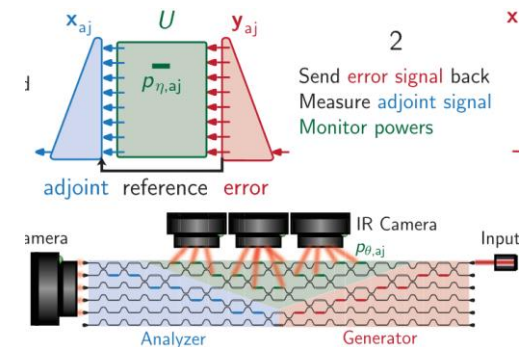


Scellier & Bengio, Frontiers in Comp. Neuro (2017)

Dillavou, Stern, Liu & Durian, Phys Rev Applied (2022)

Laydevant, Ernout, Querlioz & Grollier, CVF (2021)

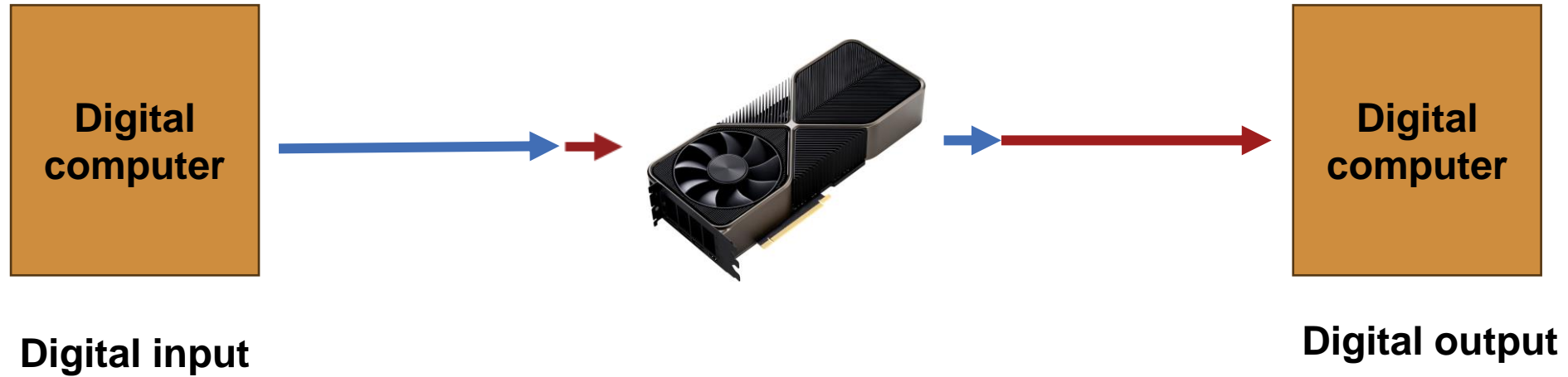
## “Physical adjoint”



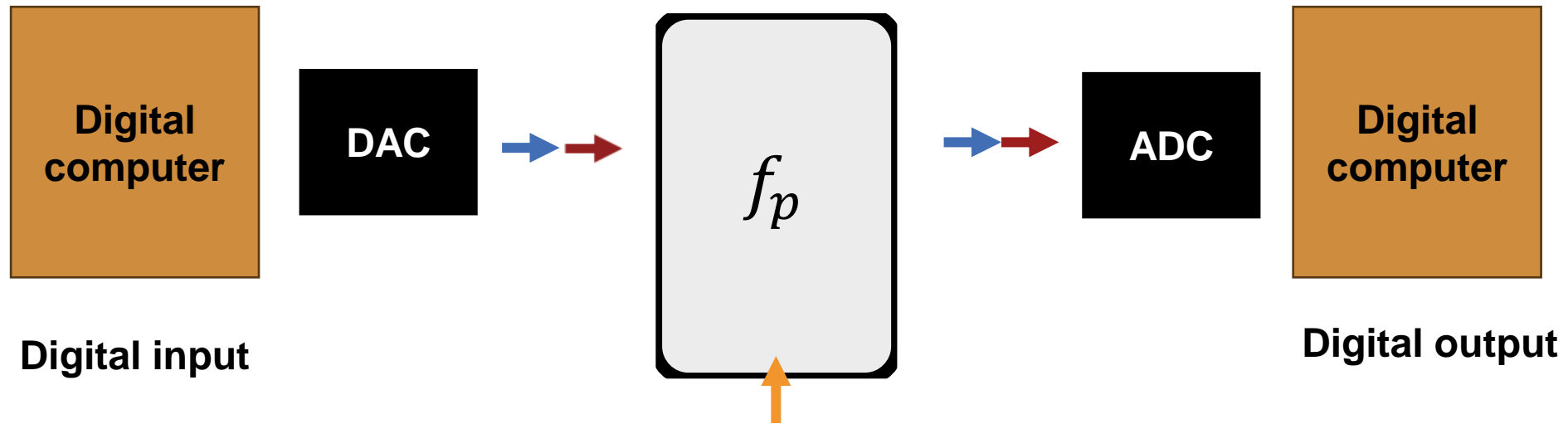
Pai et al., Science (2023)

Lopez-Pastor and Marquardt, PRX (2023)

What can we do with PNNs?



“Deep learning accelerator”



“Deep learning accelerator”

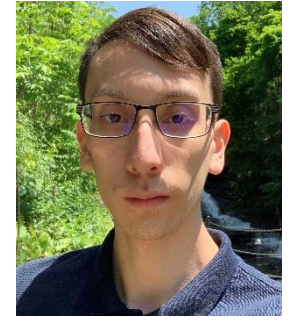
# PNNs for deep learning acceleration



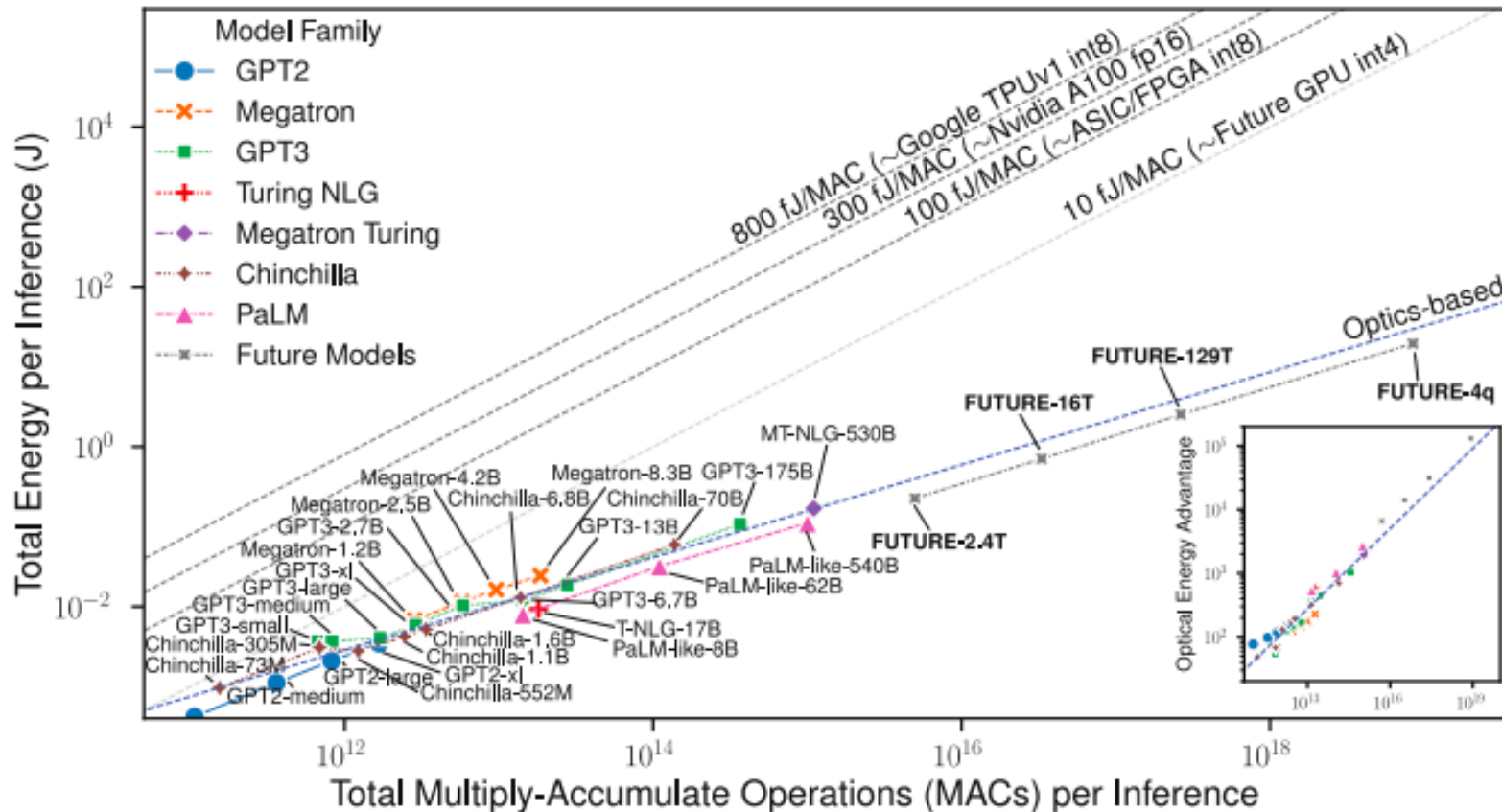
Peter McMahon



Tianyu Wang



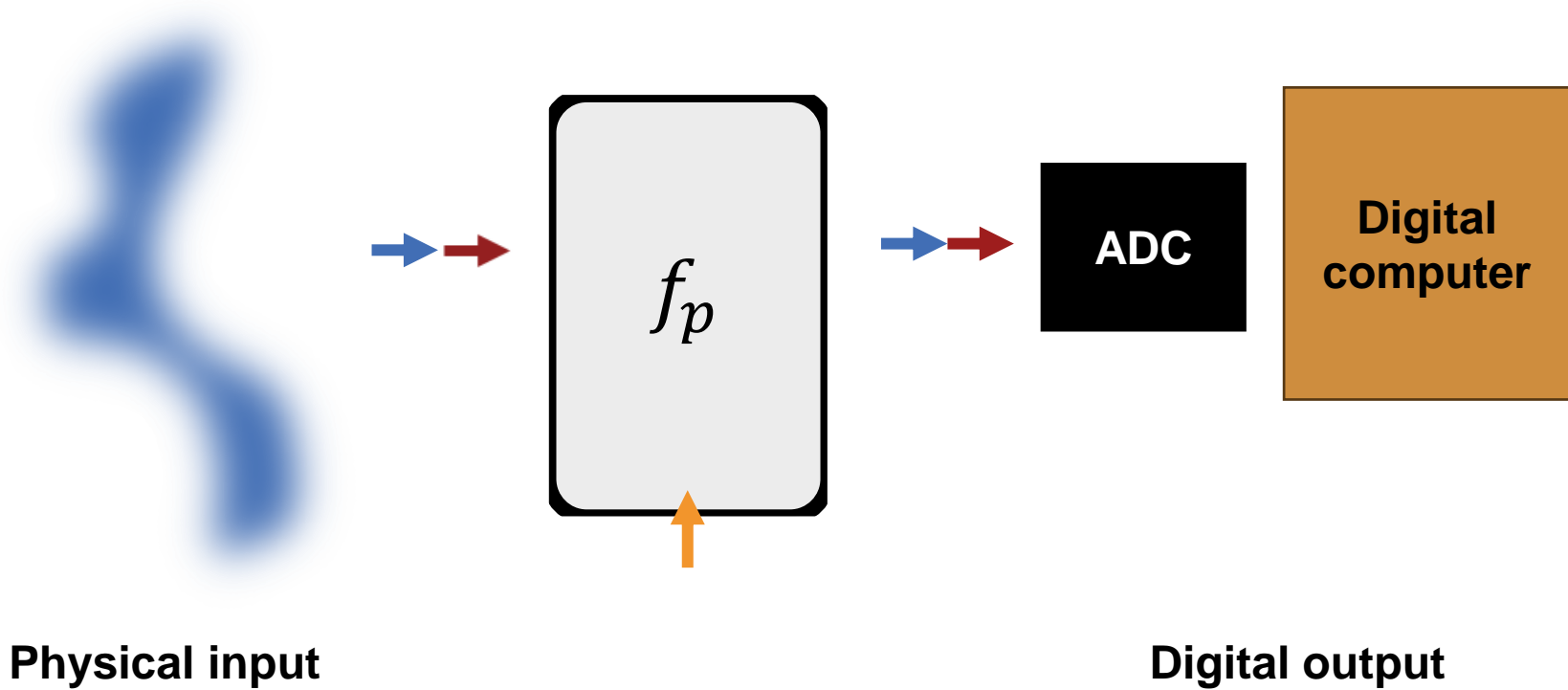
Maxwell Anderson



TLDR:

Optics has **fundamental scaling advantage** – prospect for 100,000x efficiency gain for future Transformer models!





“Smart sensor”

# PNNs for smart sensing

See Mandar and Tianyu's poster(s)!



Peter McMahon

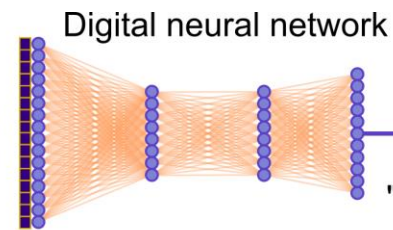


Tianyu Wang



Mandar Sohoni

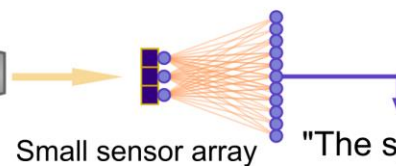
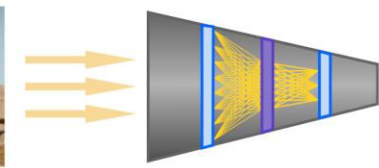
Image sensing  
via direct imaging



Large sensor array

"The speed limit is 50."

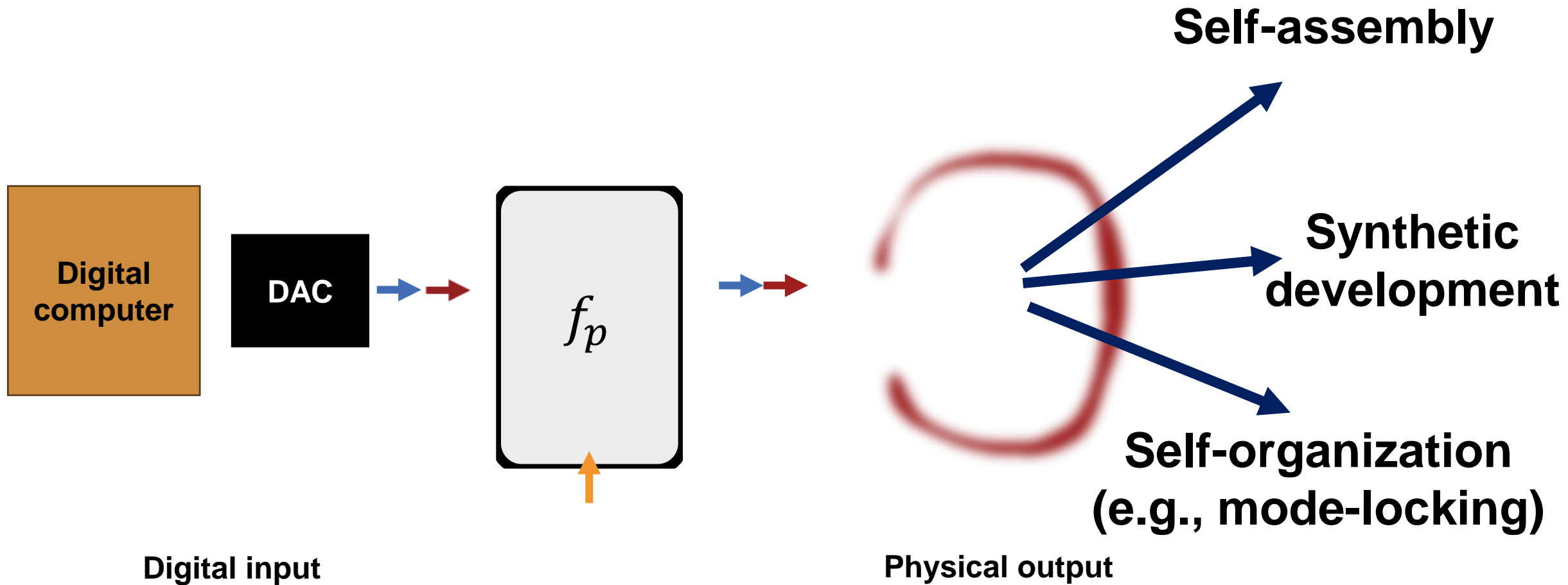
Image sensing via  
optical-neural-network encoding



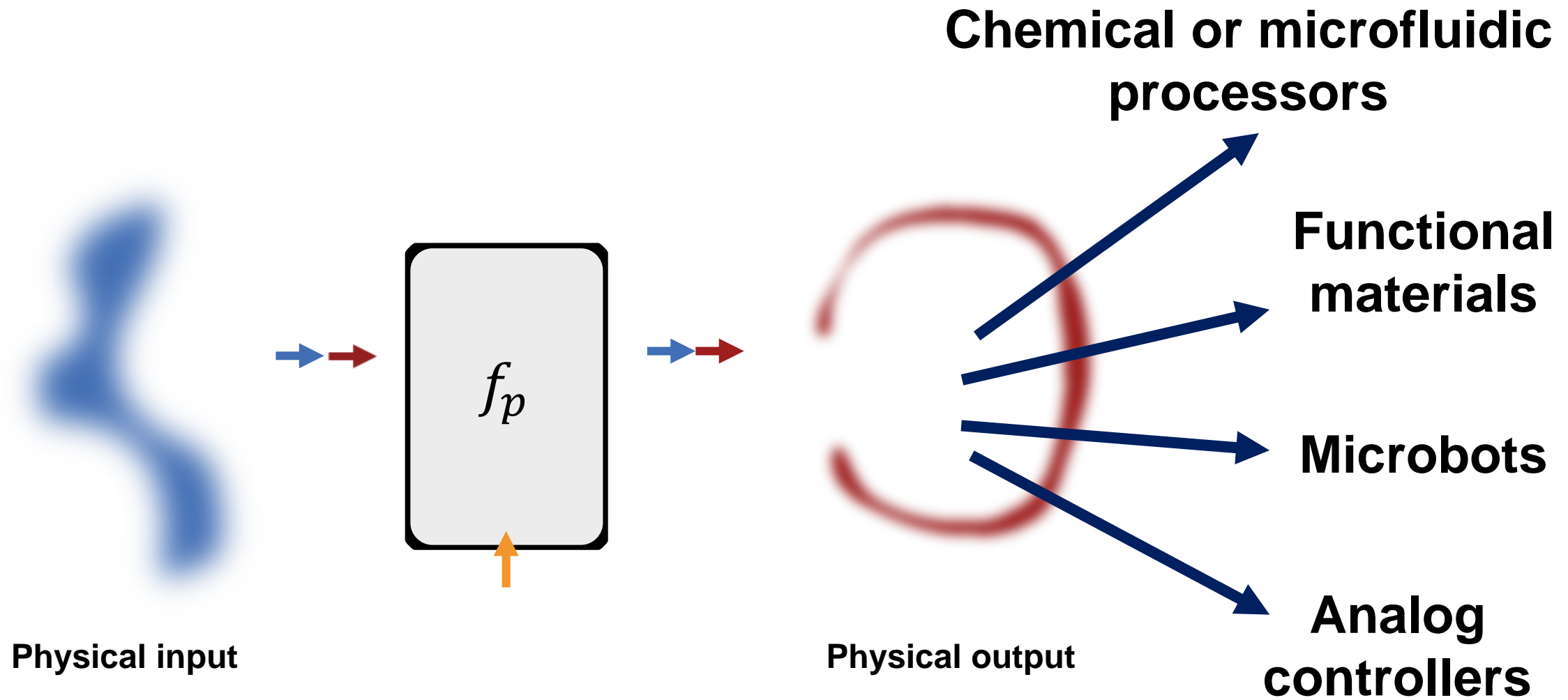
Small sensor array

"The speed limit is 50."

TLDR:  
Optical neural  
network pre-  
processing allows  
faster, more efficient  
machine vision



“Physical neural network generator”

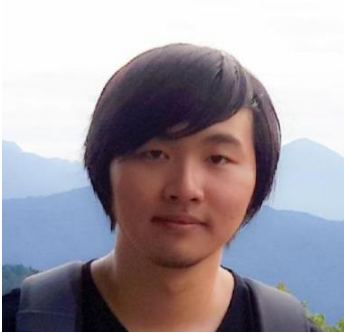


“Physical neural network machine”

# PNNs for learning photonic devices



Peter McMahon

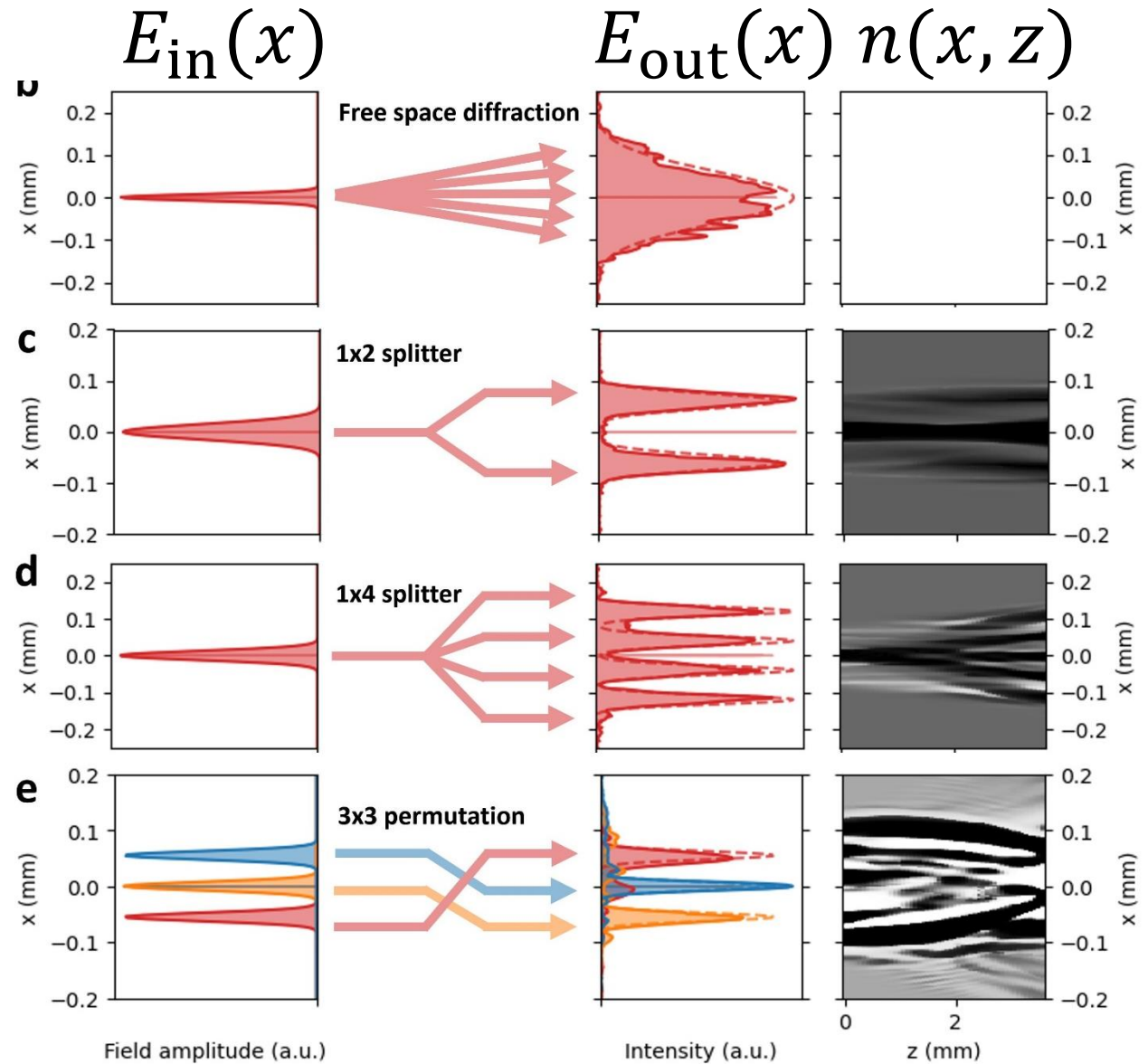
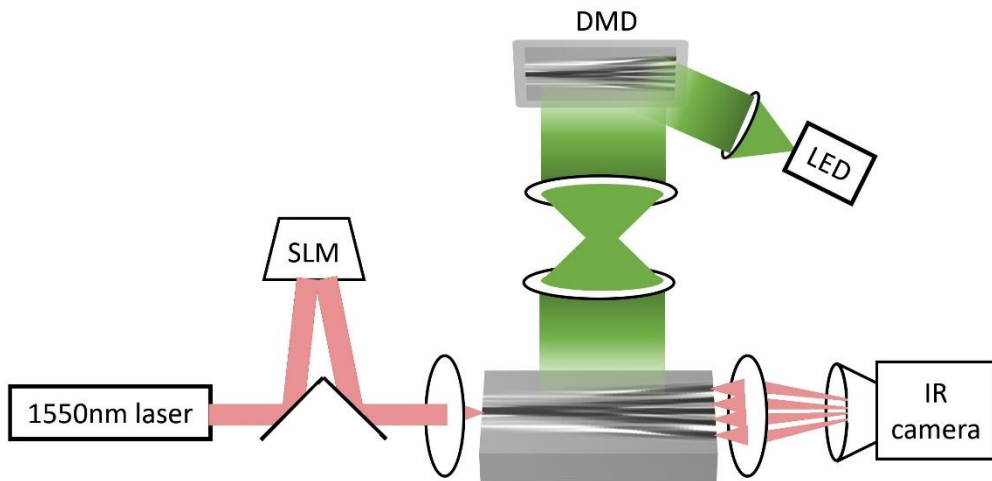


Tatsuhiro Onodera



Martin Stein

Recall Hiro's talk yesterday,  
See his poster!







Some parting thoughts



# Software is *already* “physics-informed”



In this paper we also make the converse claim; **that the state of computer architecture has been a strong influence on our models of thought.**

R. A. Brooks in “Intelligence without reason” (1991)

Software is *already* “physics-informed”, but not quite *purposefully*



In this paper we also make the converse claim; **that the state of computer architecture has been a strong influence on our models of thought.**

R. A. Brooks in “Intelligence without reason” (1991)

# Hardware physics constrains communal optimization of algorithms

Transformers  $\approx \max_{\{\text{algorithms}\}}$  ("AI goodness")



Jeremie Laydevant\*

\*Channeling decades of ideas in neuromorphic computing and theoretical neuroscience...

# Hardware physics constrains communal optimization of algorithms

Transformers  $\approx \max_{\{\text{algorithms}\}}$  ("AI goodness")  
subject to: GPU



Jeremie Laydevant\*

\*Channeling decades of ideas in neuromorphic computing and theoretical neuroscience...

# Towards purposeful physics-constrained software-hardware

$$??? \approx \max_{\{\text{algorithms}\}} (\text{"AI goodness"})$$

subject to: physics alone

Laydevant\*, Wright\*, Wang & McMahon "The hardware is the software", Neuron (2023)

# Towards purposeful physics-constrained software-hardware

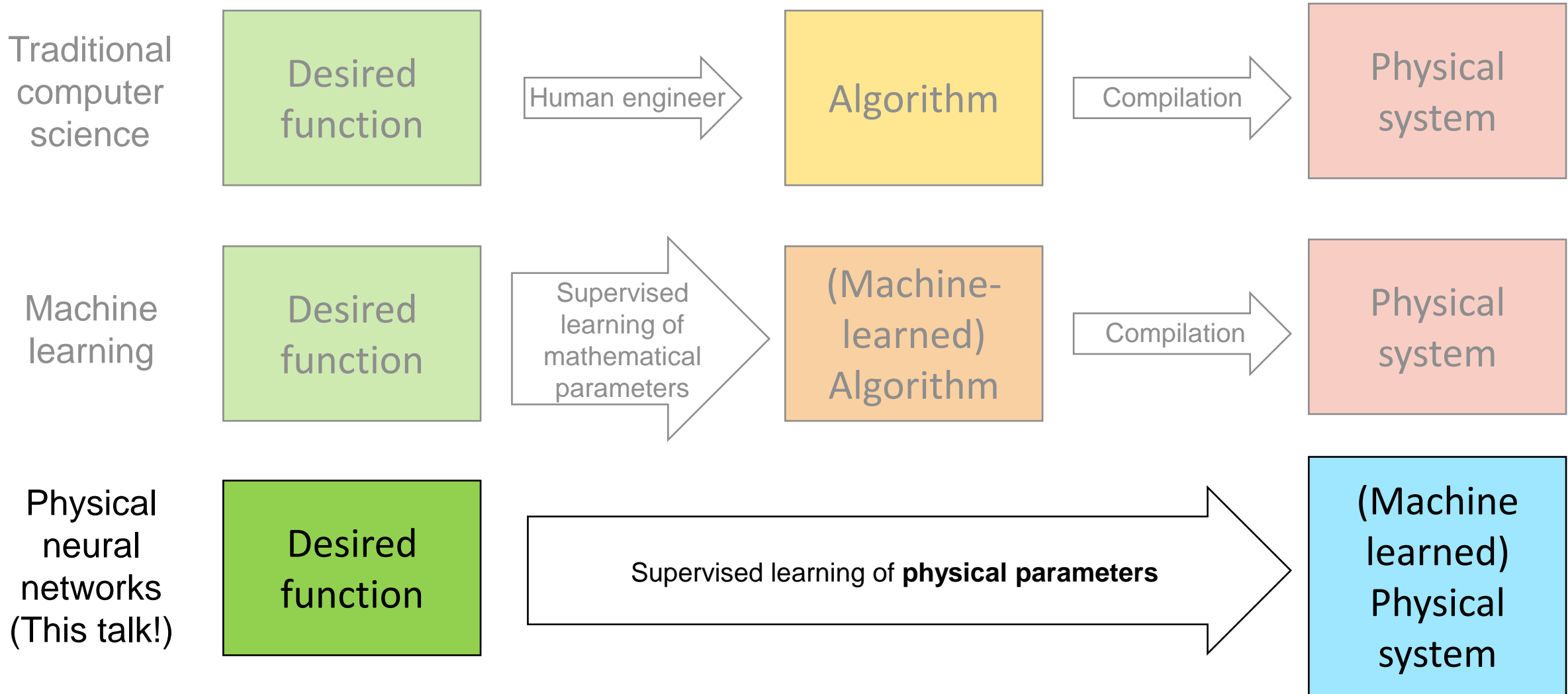
???  $\approx$   $\max_{\{\text{algorithms}\}}$  ("AI goodness")

subject to: physics alone

(Also features laser-based aliens...lighfeforms)

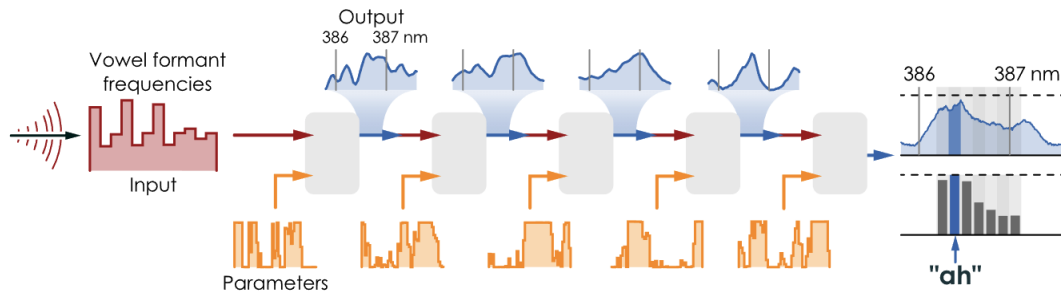
Laydevant\*, Wright\*, Wang & McMahon "The hardware is the software", Neuron (2023)





# Contributions

## (Deep) physical neural networks

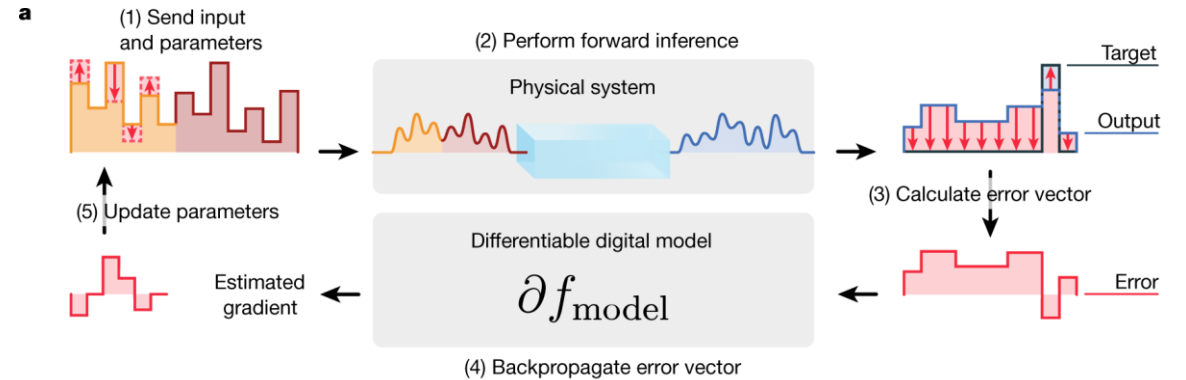


First demonstrations of PNNs: DNN-like calculations with networks of trained physical data transformations.

Potential for:

- Many orders-of-magnitude better speed/efficiency
- Learning approach to physical functionalities

## Physics-aware training



First demonstrations of backprop to train arbitrary physical systems *in situ*

- Scales to high-dimensional parameter spaces
- Trained PNN models inherently mitigate device imperfections, simulation-reality gap, and noise.

L.G. Wright\*, T. Onodera\*, M.M. Stein, T. Wang, D.T. Schachter, Z. Hu, P.L. McMahon,  
Deep physical neural networks trained with backpropagation, *Nature* **601**, 549-555 (2022)



# The hardware IS the software

- In the brain, information processing is **emergent** from physical substrate



Jeremie Laydevant



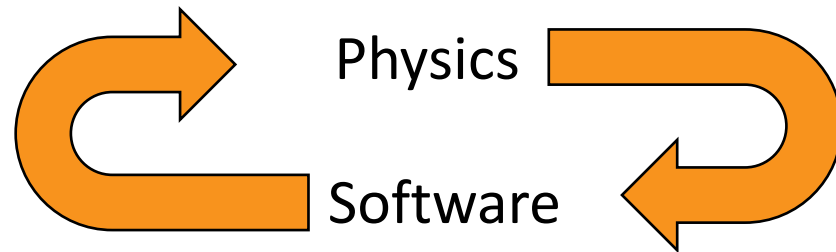
Tianyu Wang



Peter McMahon

# The hardware IS the software

- In the brain, information processing is **emergent** from physical substrate
- Computers we develop should be the same! “Physics-first”



Jeremie Laydevant



Tianyu Wang



Peter McMahon

# The hardware **IS** the software

- In the brain, information processing is **emergent** from physical substrate
- Computers we develop should be the same! “Physics-first”
- BUT: hardware physics  $\neq$  physics of biology (on Earth)



Jeremie Laydevant



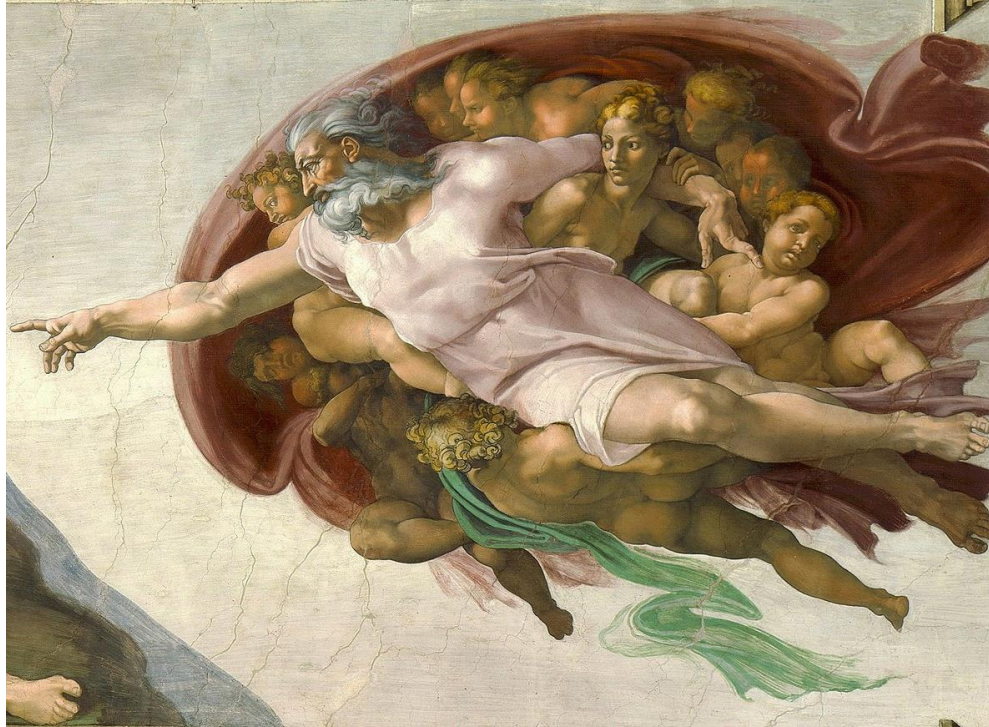
Tianyu Wang



Peter McMahon



# A new(ish) set of questions for neuromorphic computing



- *Alien neuromorphics*: What would the brains and bodies of alien intelligences look like if their biology had early on incorporated “alien” elements like laser radiation, semiconductor electronics, etc.?



Jeremie Laydevant

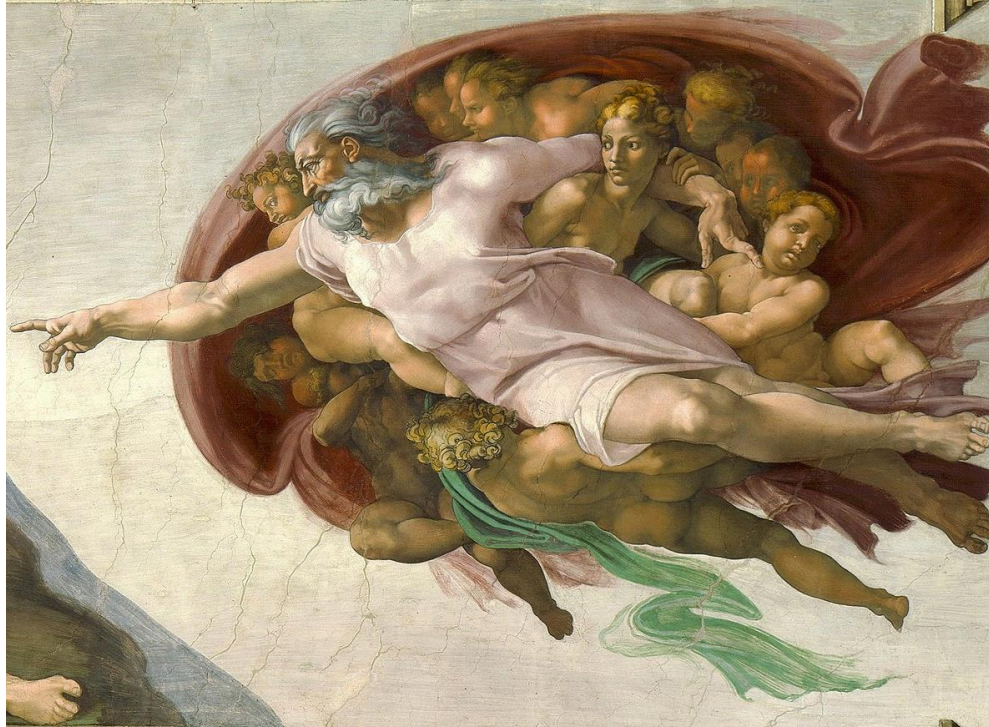


Tianyu Wang



Peter McMahon

# A new(ish) set of questions for neuromorphic computing



- ***Alien neuromorphics***: What would the brains and bodies of alien intelligences look like if their biology had early on incorporated “alien” elements like laser radiation, semiconductor electronics, etc.?
- ***Universal neuromorphics***: What are the “universal principles of intelligence” – physical features we’d expect of **all** intelligent physical systems?



Jeremie Laydevant



Tianyu Wang



Peter McMahon